

1-1-1971

Computer Oriented Stability Analysis Of Reservoir Slopes

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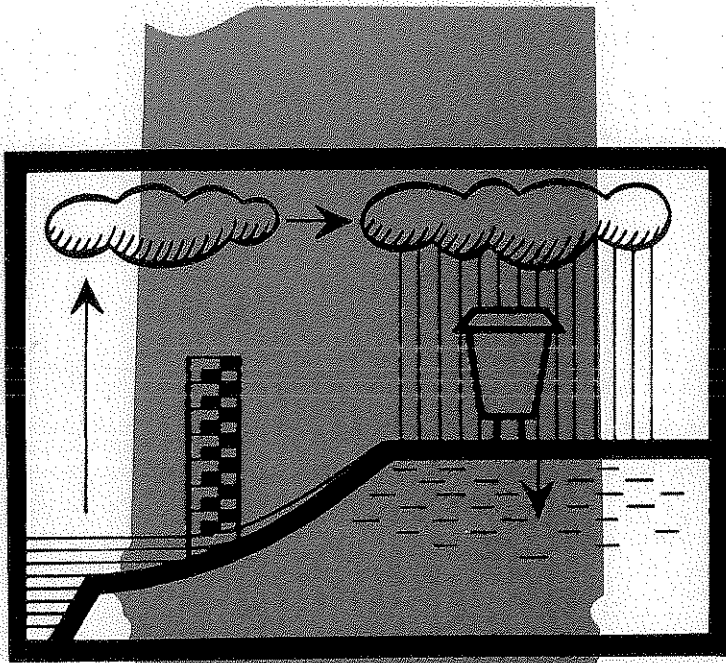
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COMPUTER ORIENTED STABILITY ANALYSIS OF RESERVOIR SLOPES



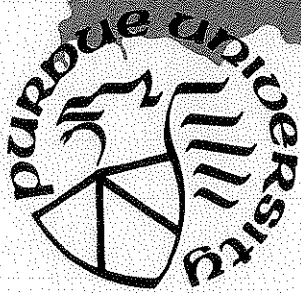
by

R. K. Carter

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January 1971



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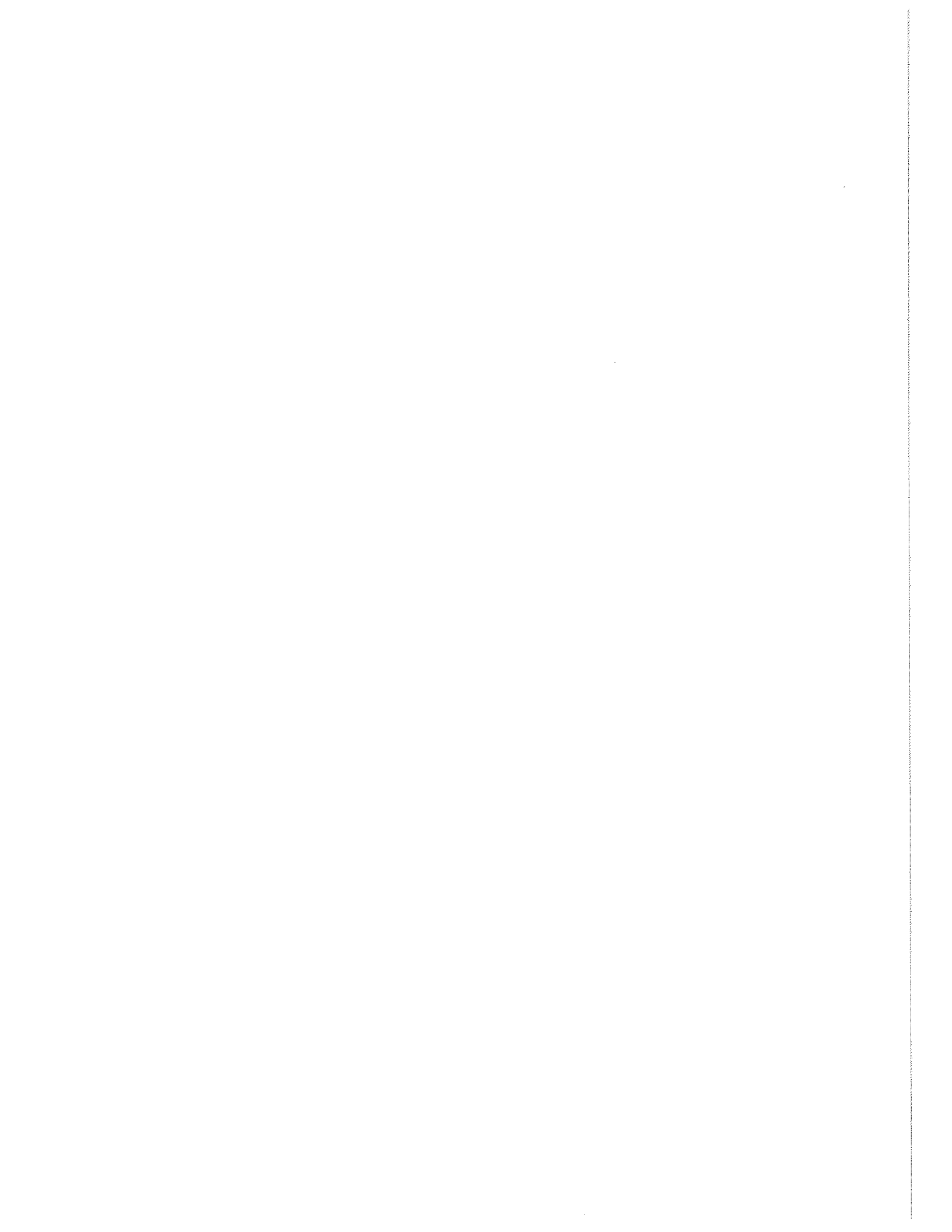
M. E. Harr

The work upon which this report is based was supported in part by funds provided by the United States Department of the Interior, Office of Water Resources Research, as authorized by the Water Resources Research Act of 1964.

Period of Investigation: September 1968 to
January 1971

Report No. 1 for OWRR A-009-IND (Agreement
no. 14-01-001-1633; 01-001-3014; 31-0001-3214)

Purdue University Water Resources Research Center
Technical Report No. 17
January 1971



This report is essentially a reproduction of a thesis entitled "Computer Oriented Slope Stability Analysis by Method of Slices" and submitted to the Faculty of Purdue University by Mr. Robert Kerner Carter in partial fulfillment of the requirements for the degree of Master of Science in Civil Engineering.

ACKNOWLEDGMENTS

The authors wish to acknowledge the assistance of the Office of Water Resources Research, U.S. Department of the Interior, who supported the investigation through the Purdue University Water Resources Research Center. They would like to thank Dr. D. Wiersma for the encouragement and administrative assistance that he offered to this project.

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ABSTRACT

This report is the first for project No. OWRR A-009-IND (Agreement numbers 14-01-0001-1633; 01-0001-3014; 31-0001-3214) entitled "Fluctuation of Reservoir Levels and the Related Cause of Landslides."

The purpose of this particular part of the research was the development of a computer-assisted system of stability analysis for specific reservoir slopes. The versatility of the developed programs includes accommodations for variable ground surface and profile characteristics, both uniform and concentrated external boundary loadings, spatial variations in water pressure, and irregular as well as circular shaped failure surfaces.

Several limiting equilibrium analyses by methods of slices have been reviewed. One of these, the modified Bishop technique, previously considered applicable only to circular failure surfaces, was modified to include irregular shaped surfaces.

The programs have been written in elementary Fortran IV language. There are currently five main programs and eleven integrated supporting routines. Conversion of the programs to small computer systems is considered highly practical.

INTRODUCTION

During the planning and development of reservoirs, a condition generally not assessed is the stability of the slopes bounding the reservoir pool. Accordingly, the consequences of reservoir filling and fluctuations, on developments on or adjacent to these slopes, are unknown. Although failures of reservoir slopes are not very common, the results can be catastrophic in terms of both personal property and loss of life (Kiersch, 1964).¹ The intent of this research project is to develop a systematic technique for determining the potential instability of reservoir slopes.

The technique encompasses two levels of investigation both of which are computer oriented. First, it is desired to locate the potentially troublesome areas by a general-level system. By examining a number of regional factors, e.g., hydrology, geology, and topography, for the areas bounding a proposed reservoir, zones with susceptibility to slope instability can be located. Secondly, a detailed analysis, a specific-level system, is needed for any zone earmarked by the general-level system, to ascertain whether instability of an individual slope would indeed exist. The specific-level system should be sufficiently versatile to accommodate irregular slopes, complexities of the

1. See entries in the List of References, page 50.

subsurface and failure surface geometry, conditions of variable internal water pressures and of ground surface boundary loadings.

This report concerns itself with the second phase of the research project, the development of the specific-level, computer-assisted system for the prediction of reservoir slope stability.

METHODS OF LIMITING EQUILIBRIUM FOR SLOPE STABILITY ANALYSIS

Two approaches have been developed for assessing the stability of slopes by the limiting equilibrium method (Harr, 1966; Romani, 1970). In the first, incipient failure is assumed at all points in the mass. In the second, failure is assumed along a particular surface in a material of reduced strength. The minimum strength reduction factor, also called the factor of safety (F), is generally determined by iteration. Each trial solution of F involves an application of the conditions of statical equilibrium for both the internal and external forces.

The second method is commonly applied to practical problems. It is assumed that the factor of safety has a single value along any trial failure surface, and is a simple ratio of the shearing resistance available along this surface to the shearing resistance required to satisfy statics.

In the common approaches to stability analysis, it is important to realize that the strain characteristics of the material are of no consequence. Also, local zones of overstress may exist even though a "reasonable" value of the factor of safety may be predicted (Romani, 1970).

For analyzing slopes which are characterized by distributions of pore pressures, or by variations in the unit weight, strength properties of the material, or by boundary forces, the method of slices is

convenient. Given an assumed failure surface, the entire free body is divided into a number of vertical-sided increments, as shown in Figure 1, and static equilibrium is applied to each slice. However, barring an unusually simple material, a unique solution is not possible due to the indeterminacy of the slice equilibrium. Figure 2 shows a typical slice for the generalized case involving boundary water. Table 1 lists the unknowns per slice, and the total unknowns for the entire free body, assuming n number of slices. The total number of unknowns is $(5n-2)$, and, using the three statical equations per slice, the total number of equations is $3n$. The problem is therefore $(2n-2)$ indeterminate, and additional assumptions are required to solve it.

Taylor Solution

One of the earliest solutions, originally proposed by Fellinius (1927) and later advanced by Taylor (1940), assumes that the resultant of the side forces, effective or total, on each side of the slice acts parallel to the slice base.¹ Therefore, it is possible to sum forces in the direction normal to the slice base,

$$\sum F_n = 0$$

$$N' + U_\alpha = W \cos \alpha + U_\beta \cos (\alpha - \beta) \quad 1$$

This method and its assumptions are particularly suited to failure surfaces that are circular in shape, since in summing moments about the

1. The assumption generally produces a contradiction of the basic law of equality of action and reaction, when adjacent slices are considered.

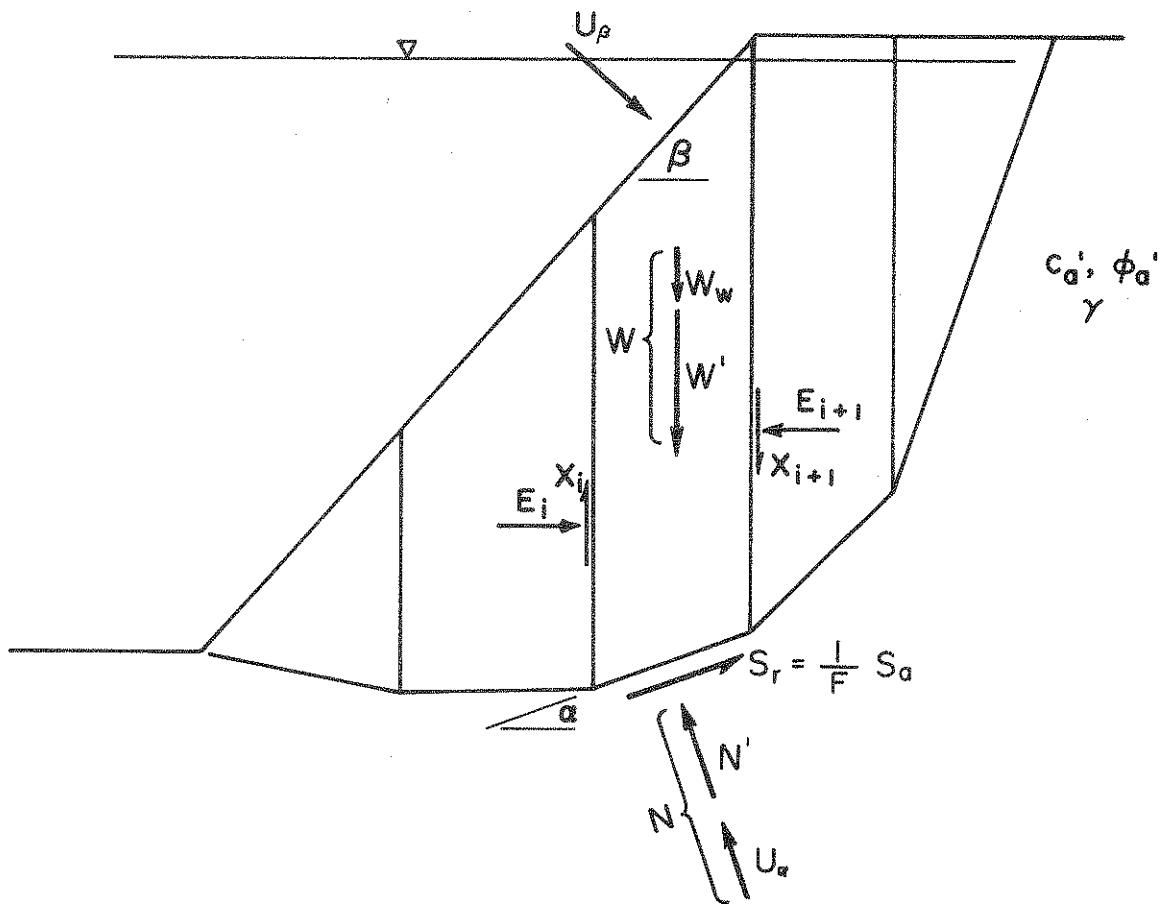


Figure 1 - Free Body for an Assumed Failure Surface

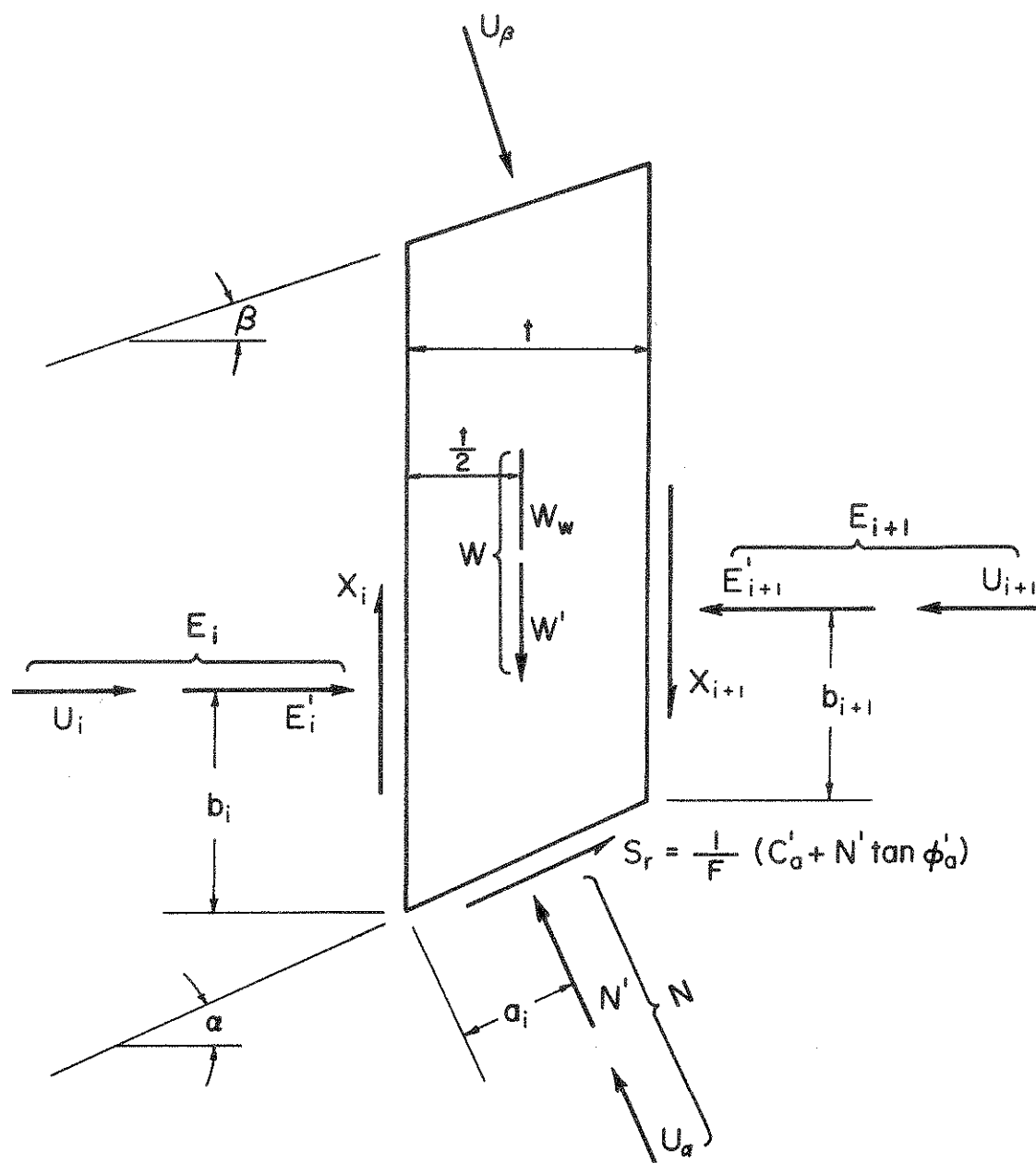


Figure 2 - Typical Slice Free Body

Table 1
Unknowns in Method of Slices

Unknowns	Number/Slice	Total
E	2	$n - 1$
X	2	$n - 1$
N'	1	n
b	2	$n - 1$
a	1	n
F	1	1
		<hr/>
		$5n - 2$

n = number of slices

center of the circle, all forces acting normal to the failure surface would not appear in the equation.

Therefore, summing about the point¹ O all moments shown in Figure 3 for all slices, gives,

$$\begin{aligned} \Sigma (W + U_{\beta} \cos \beta) R \sin \alpha = \Sigma S_r R \\ + \Sigma U_{\beta} \sin \beta (R \cos \alpha - h) \end{aligned} \quad 2$$

where h represents the average height of a slice.

Substituting the Mohr-Coulomb strength relationship,

$$\tau_r = \frac{1}{F} \tau_a = \frac{1}{F} (c'_a + \sigma' \tan \phi'_a)$$

in terms of forces,

$$S_r = \frac{1}{F} S_a = \frac{1}{F} (C'_a + N' \tan \phi'_a) \quad 3$$

factoring R, a constant, from each summation term in Equation 2, and solving for F,

$$F = \frac{\Sigma (C'_a + N' \tan \phi'_a)}{\Sigma (W + U_{\beta} \cos \beta) \sin \alpha - \Sigma U_{\beta} \sin \beta (\cos \alpha - \frac{h}{R})} \quad 4$$

Now, substitute into Equation 4 the expression for N', Equation 1,

$$F = \frac{\Sigma \{C'_a + [W \cos \alpha + U_{\beta} \cos (\alpha - \beta) - U_{\alpha}] \tan \phi'_a\}}{\Sigma (W + U_{\beta} \cos \beta) \sin \alpha - \Sigma U_{\beta} \sin \beta (\cos \alpha - \frac{h}{R})} \quad 5$$

1. Since the side force assumption violates equilibrium, different centers for moments will produce a variety of solutions.

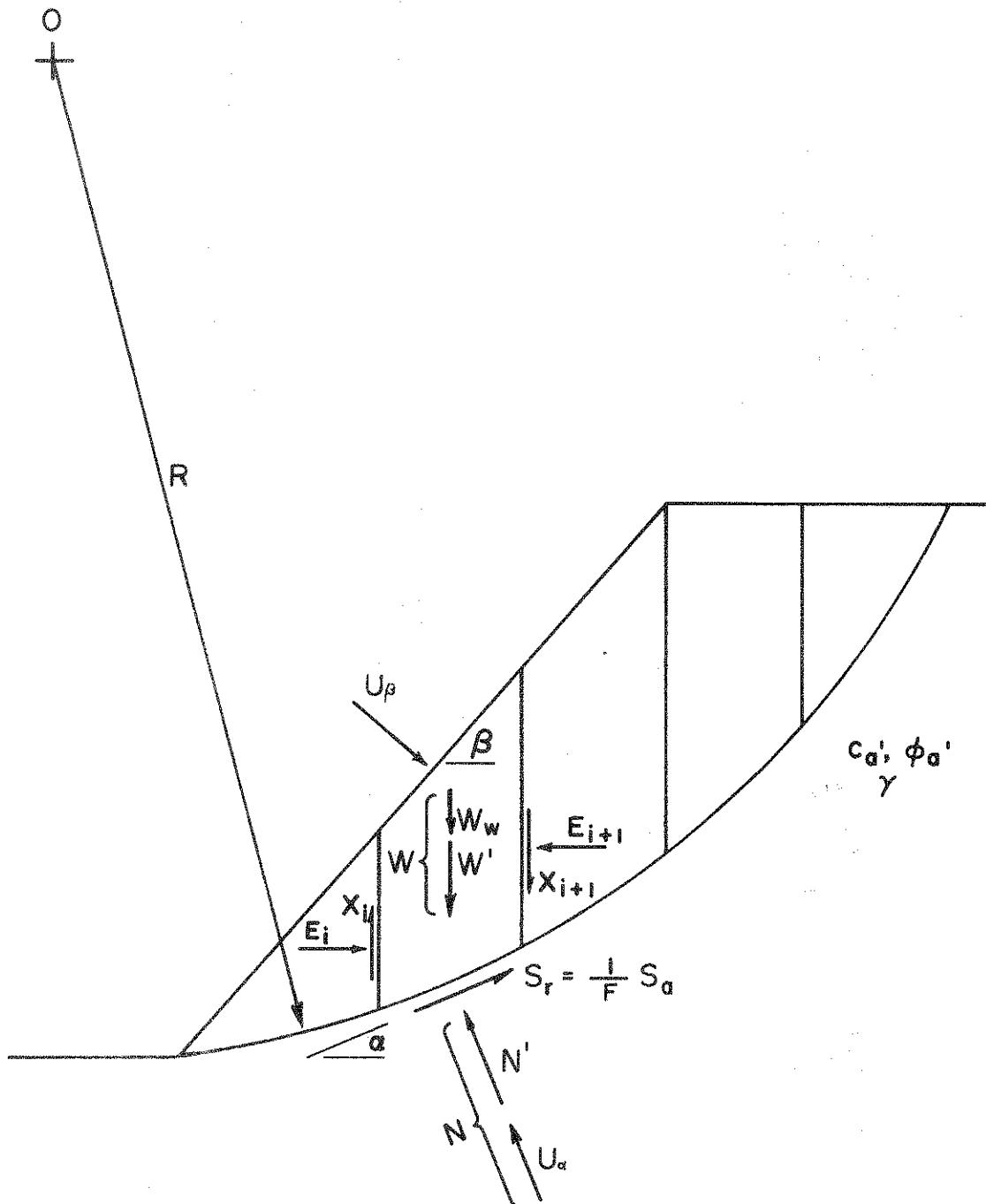


Figure 3- Free Body for an Assumed Circular Failure Surface

Bishop Method

A method which satisfies force equilibrium of each slice and moment equilibrium of the entire free body was proposed by Bishop (1955). Although the following development is for an assumed circular failure surface, the general theory is applicable to irregular surfaces as well.

Summing forces in the vertical direction on the slice in Figure 2, gives,

$$\sum F_v = 0$$

$$(N' + U_\alpha) \cos \alpha + S_r \sin \alpha + X_i = W + U_\beta \cos \beta + X_{i+1} \quad 6$$

Now, substitute the Mohr-Coulomb effective stress relationship, Equation 3, and solve for N' .

$$N' = \frac{W + U_\beta \cos \beta - U_\alpha \cos \alpha + X_{i+1} - X_i - \frac{C'_a \sin \alpha}{F}}{\cos \alpha + \frac{\sin \alpha \tan \phi'_a}{F}} \quad 7$$

Backsubstituting Equation 7 into Equation 4, the moment expression, and simplifying,

$$F = \frac{\sum \left\{ \frac{C'_a + (W + U_\beta \cos \beta - U_\alpha \cos \alpha + X_{i+1} - X_i) \sec \alpha \tan \phi'_a}{1 + \frac{\tan \alpha \tan \phi'_a}{F}} \right\}}{\sum \{ \sin \alpha (W + U_\beta \cos \beta) \} - \sum \{ U_\beta \sin \beta (\cos \alpha - \frac{h}{R}) \}} \quad 8$$

Since X and E are internal forces, the following conditions must hold,

$$\sum (X_{i+1} - X_i) = 0 \quad 9a$$

$$\sum (E'_{i+1} - E'_i) = 0 \quad 9b$$

Now, resolve forces in the tangential direction on the slice,

Figure 2,

$$S_r + X_i \sin \alpha + (E'_i + U_i) \cos \alpha =$$

$$W \sin \alpha + X_{i+1} \sin \alpha + (E'_{i+1} + U_{i+1}) \cos \alpha \quad 10$$

or

$$E'_{i+1} - E'_i = \frac{S_r - (W + X_{i+1} - X_i) \sin \alpha}{\cos \alpha} \quad 11$$

Substituting S_r , Equation 3, and taking the sum over all slices yields,

$$\sum (E'_{i+1} - E'_i) = \sum \{m \sec \alpha - (W + X_{i+1} - X_i) \tan \alpha\} \quad 12$$

where

$$m = \frac{C'_a + (W + U_\beta \cos \beta - U_\alpha \cos \alpha + X_{i+1} - X_i) \sec \alpha \tan \phi'_a}{\tan \alpha \tan \phi'_a}$$

$$1 + \frac{F}{F}$$

Or from Equation 9b,

$$\sum \{m \sec \alpha - (W + X_{i+1} - X_i) \tan \alpha\} = 0 \quad 13$$

Bishop suggests an iterative solution in which Equation 9a is used in assuming a set of X forces, Equation 8 is applied to find the corresponding F , and Equation 13 is used to provide relative corrections to the assumed X forces. A solution is achieved when the three equations are simultaneously satisfied.

The solution however does not satisfy complete statics. Each slice will be in vertical and tangential equilibrium, and the entire free body will be in moment equilibrium. Yet, each slice will not necessarily be

in moment equilibrium. Due this deficiency of statics, a range of solutions exists for a number of possible $(X_{i+1} - X_i)$ arrays.

Modified Bishop Method

Realizing that the iteration for what has been termed the "complete Bishop analysis" is quite tedious, Bishop suggested simplifying the solution by assuming that the shear forces acting on the vertical sides of each slice are equal in magnitude and opposite in direction, thereby reducing Equation 8 to an expression of only one unknown,

$$F = \frac{\sum \left\{ \frac{C'_a + (W + U_\beta \cos \beta - U_\alpha \cos \alpha) \sec \alpha \tan \phi'_a}{1 + \frac{\tan \alpha \tan \phi'_a}{F}} \right\}}{\sum \{(W + U_\beta \cos \beta) \sin \alpha\} - \sum \{U_\beta \sin \beta (\cos \alpha - \frac{h}{R})\}} \quad 14$$

Bishop (1955) examined this assumption for a number of simple cases and found a difference of only approximately 1% (with respect to the unmodified method) in the factor of safety. Since the modified Bishop method requires a gross assumption of statics, like the Taylor method, it has also been considered limited to circular failure surfaces.

Morgenstern and Price Method

In the Morgenstern and Price (1965) method, not only are the normal and tangential force equilibriums ensured but also moment equilibrium for each slice. The simplifying assumption is made regarding the relationship between X and E .

$$X = \lambda f(x) E \quad 15$$

where $f(x)$ is an assumed normalized function supplied by the user.

Again, since no unique solution exists, iteration for a solution is necessary. By a systematic technique, boundary conditions are met, and values of F and λ are found as the solution for a given $f(x)$.

Although the developers reported that the factor of safety is relatively insensitive to $f(x)$, a great deal of work is indeed necessary, and Whitman and Bailey (1967) concluded that for most projects the simpler techniques are justified.

Bell Method

More recently, Bell (1968) presented another technique which is applicable to irregular surfaces. Bell develops the three equations of equilibrium for the entire free body rather than for each of n slices. In addition to the factor of safety, the distribution of normal stress acting on the assumed failure surface is unknown. The distribution is assumed to be,

$$\sigma_n = C_1 Wt + C_2 f(x_i, y_i, z_i) \quad 16$$

where

W = weight of slice

t = thickness of slice

$$f = \sin 2\pi \left(\frac{x_n - x_i}{x_n - x_o} \right)$$

x_i = right interslice x coordinate

y_i = right interslice ground surface y coordinate

z_i = right interslice slip surface y coordinate

C_1 and C_2 are unknowns

Assuming the normal stress distribution leaves only three unknowns. By linear algebra techniques, a clever solution from iteration is presented. But, just as in the Morgenstern and Price technique, the result is dependent on f .

PROPOSED METHOD OF ANALYSIS FOR
IRREGULAR SURFACES

Neither the Taylor method nor the modified Bishop method of analysis satisfy statics in the gross sense. The key assumption made in the Taylor analysis is summation of forces on a slice normal to its base with cancellation of all side force components in this direction. The unique point that can then be used for summing external moments and comparing the factor of safety of different assumed failure surfaces is indeed the point of intersection of the normal lines to each slice base. Consequently, the Taylor analysis, by virtue of the key assumption, is limited to circular failure surfaces, the unique point of moment summation being the center of the circle.

On the other hand, the critical assumption made in the modified Bishop method of analysis is summation in the vertical direction of the forces acting on a slice with cancellation of side forces in this direction. In the original development, the assumed failure surface was circular, and the point used for summation of external moments and, hence, comparison of the factors of safety for different assumed surfaces, was the circle center. However, the center of the circle is not the unique point that should be used for external moment equilibrium. Consider the following development.

Referring to Figure 4, sum moments of all external forces for all slices about the arbitrary point O, resolving each force into a horizontal and vertical component.¹

$$\begin{aligned} \Sigma (N' + U_{\alpha})(\bar{y} \sin \alpha - \bar{x} \cos \alpha) + \Sigma W \bar{x} + \Sigma U_{\beta} (\bar{x} \cos \beta - \bar{a} \sin \beta) \\ - \Sigma S_r (\bar{x} \sin \alpha + \bar{y} \cos \alpha) = 0 \end{aligned} \quad 17$$

$$\text{where } \bar{a} = \bar{y} - h$$

Applying the associative law of addition, Equation 17 may be written,

$$\begin{aligned} \Sigma \{(N' + U_{\alpha})(\bar{y} \sin \alpha - \bar{x} \cos \alpha) + W \bar{x} + U_{\beta} (\bar{x} \cos \beta - \bar{a} \sin \beta) \\ - S_r (\bar{x} \sin \alpha + \bar{y} \cos \alpha)\} = 0 \end{aligned} \quad 18$$

Substitute into Equation 18, S_r , the Mohr-Coulomb effective stress relationship, Equation 3, and rearrange,

$$\begin{aligned} \Sigma \{N' (\bar{y} \sin \alpha - \bar{x} \cos \alpha - \bar{x} \frac{\sin \alpha}{F} \tan \phi'_a - \bar{y} \frac{\cos \alpha}{F} \tan \phi'_a) \\ + W \bar{x} - \frac{C'_a}{F} (\bar{x} \sin \alpha + \bar{y} \cos \alpha) + U_{\alpha} (\bar{y} \sin \alpha - \bar{x} \cos \alpha) \\ + U_{\beta} (\bar{x} \cos \beta - \bar{a} \sin \beta)\} = 0 \end{aligned} \quad 19$$

Now, substitute the complete expression for N' , Equation 7.

-
1. The forces X_i and E_i being internal to the sliding free body do not produce an external moment.

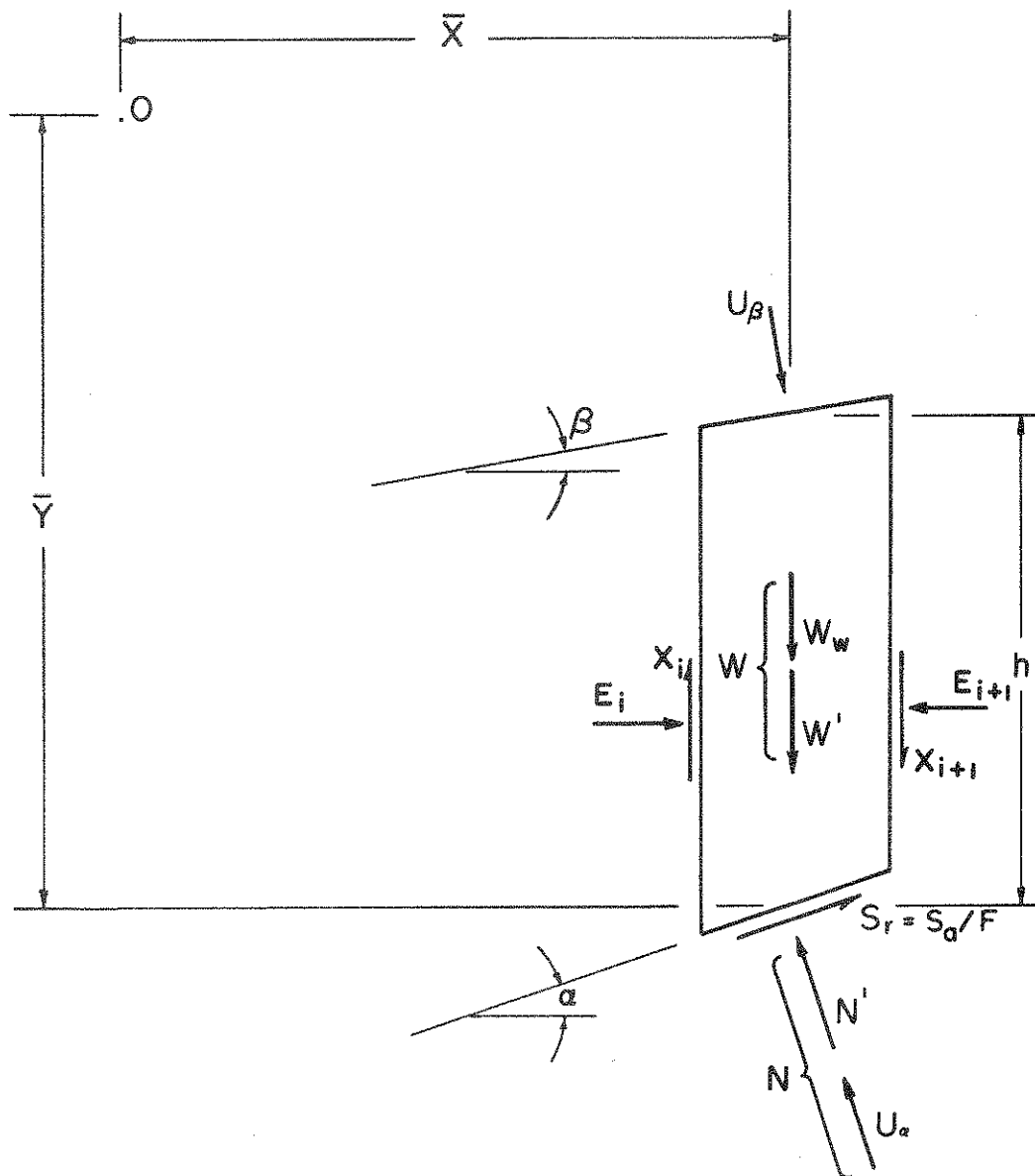


Figure 4 - External Forces for a Slice with Reference to an Arbitrary Center

$$\begin{aligned}
& \Sigma \left\{ \left[\frac{F(W + U_{\beta} \cos \beta - U_{\alpha} \cos \alpha + \Delta X) - C'_a \sin \alpha}{F \cos \alpha + \sin \alpha \tan \phi'_a} \right] \right. \\
& \quad \left. (\bar{y} \sin \alpha - \bar{x} \cos \alpha - \bar{x} \frac{\sin \alpha \tan \phi'_a}{F} - \bar{y} \frac{\cos \alpha \tan \phi'_a}{F}) \right. \\
& \quad + W \bar{x} - \frac{C'_a}{F} (\bar{x} \sin \alpha + \bar{y} \cos \alpha) + U_{\alpha} (\bar{y} \sin \alpha - \bar{x} \cos \alpha) \\
& \quad \left. + U_{\beta} (\bar{x} \cos \beta - \bar{a} \sin \beta) \right\} = 0 \tag{20}
\end{aligned}$$

$$\text{where } \Delta X = X_{i+1} - X_i$$

Using the least common denominator,

$$F(F \cos \alpha + \sin \alpha \tan \phi'_a),$$

collect like terms in Equation 20.

$$\begin{aligned}
& \Sigma \{ [W (F^2 \bar{y} \sin \alpha - F \bar{y} \cos \alpha \tan \phi'_a) - C'_a F \bar{y} + U_{\alpha} F \bar{y} \tan \phi'_a \\
& \quad + U_{\beta} (F^2 \bar{y} \cos \beta \sin \alpha - F^2 \bar{a} \sin \beta \cos \alpha - \bar{y} F \cos \beta \cos \alpha \tan \phi'_a \\
& \quad - \bar{a} F \sin \alpha \sin \beta \tan \phi'_a) \\
& \quad + \Delta X (F^2 \bar{y} \sin \alpha - F^2 \bar{x} \cos \alpha - F \bar{x} \sin \alpha \tan \phi'_a - F \bar{y} \cos \alpha \tan \phi'_a)] \\
& \quad \div (F^2 \cos \alpha + F \sin \alpha \tan \phi'_a) \} = 0 \tag{21}
\end{aligned}$$

Cancelling F from each term, dividing through by $\cos \alpha$, and transposing the ΔX term gives,

$$\begin{aligned}
& \Sigma \{ (W\bar{y} (\tan \phi'_a - F \tan \alpha) + C'_a \frac{\bar{y}}{\cos \alpha} - U_\alpha \bar{y} \frac{\tan \phi'_a}{\cos \alpha} \\
& - U_\beta (\bar{F}\bar{y} \cos \beta \tan \alpha - F\bar{a} \sin \beta - \bar{y} \cos \beta \tan \phi'_a \\
& - \bar{a} \sin \beta \tan \alpha \tan \phi'_a)] \\
& \div (F + \tan \alpha \tan \phi'_a) \} \\
& = \Sigma \{ \Delta X \left(\frac{\bar{F}\bar{y} \tan \alpha - F\bar{x} - \bar{x} \tan \alpha \tan \phi'_a - \bar{y} \tan \phi'_a}{F + \tan \alpha \tan \phi'_a} \right) \} \quad 22
\end{aligned}$$

Simplifying the ΔX coefficient and the U_β coefficient using,

$$\bar{k} = 1 - \frac{h}{\bar{y}},$$

$$\begin{aligned}
& \Sigma \{ [W\bar{y} (\tan \phi'_a - F \tan \alpha) + C'_a \frac{\bar{y}}{\cos \alpha} - U_\alpha \bar{y} \frac{\tan \phi'_a}{\cos \alpha} \\
& - U_\beta \bar{F}\bar{y} (\cos \beta \tan \alpha - \bar{k} \sin \beta) \\
& + U_\beta \tan \phi'_a \bar{y} (\cos \beta + \bar{k} \sin \beta \tan \alpha)] \\
& \div (F + \tan \alpha \tan \phi'_a) \} \\
& = \Sigma \Delta X \left[\frac{\bar{y} (F \tan \alpha - \tan \phi'_a)}{F + \tan \alpha \tan \phi'_a} - \bar{x} \right] \quad 23
\end{aligned}$$

Factoring \bar{y} and rearranging terms yields,

$$\begin{aligned}
& \Sigma \bar{y} \left\{ \tan \phi'_a \left[W - \frac{U_\alpha}{\cos \alpha} + U_\beta (\cos \beta + \bar{k} \sin \beta \tan \alpha) \right. \right. \\
& \quad \left. \left. + \frac{C'_a}{\cos \alpha} - F [W \tan \alpha + U_\beta (\cos \beta \tan \alpha - \bar{k} \sin \beta)] \right] \right. \\
& \quad \left. \div (F + \tan \alpha \tan \phi'_a) \right. \\
& \quad \left. = \Sigma \bar{y} \Delta X \left[\frac{\tan \alpha - \frac{\tan \phi'_a}{F}}{1 + \frac{\tan \alpha \tan \phi'_a}{F}} - \frac{\bar{x}}{\bar{y}} \right] \right. \quad 24
\end{aligned}$$

If the "true" set of forces ΔX were known, the solution of Equation 24 would give a value of F compatible with vertical equilibrium of each slice and moment equilibrium of the entire free body at all points in the x - y plane. Since the "true" set of forces ΔX cannot be determined without further assumptions, consider the consequence of applying the modified Bishop assumption, namely $\Delta X = 0$, to Equation 24.

Rewriting Equation 24 with this assumption,

$$\Sigma \bar{y} \left(\frac{A_1 - F A_2}{F + A_3} \right) = 0 \quad 25$$

where

$$A_1 = \frac{C'_a}{\cos \alpha} + \tan \phi'_a \left[W - \frac{U_\alpha}{\cos \alpha} + U_\beta (\cos \beta + \bar{k} \sin \beta \tan \alpha) \right]$$

$$A_2 = W \tan \alpha + U_\beta (\cos \beta \tan \alpha - \bar{k} \sin \beta)$$

$$A_3 = \tan \alpha \tan \phi'_a$$

The value of F resulting from the solution of Equation 25 is no longer a function of the material properties and the shape of the slip surface only, but also of the vertical position of the point for which

the external moment equation is written. In other words, the factor of safety will vary as y_o (the y coordinate of the moment center) is varied, and will be a constant as x_o (the x coordinate of the moment center) is varied with y_o constant.

As y_o increases, the difference between \bar{y}_1 becomes smaller, and hence \bar{y}_1 approaches a constant. For this limiting condition, \bar{y} can be factored out of the summation in Equation 25 giving Equation 26.

$$\Sigma \left(\frac{A_1 - F A_2}{F + A_3} \right) = 0 \quad 26$$

where

$$A_1 = \frac{C'_a}{\cos \alpha} + \tan \phi'_a \left[W - \frac{U}{\cos \alpha} + U_\beta (\cos \beta + \sin \beta \tan \alpha) \right]$$

$$A_2 = W \tan \alpha + U_\beta (\cos \beta \tan \alpha - \sin \beta)$$

$$A_3 = \tan \alpha \tan \phi'_a$$

Equation 26, which is no longer dependent upon the position of the moment center, can be used for circular as well as irregular surfaces.

In the past (Bishop, 1955), comparisons have been made between the Taylor method and the modified Bishop method (as originally developed) by examining the factor of safety as a function of the central angle of the assumed slip circle, θ , as shown in Figures 5a and 5b. Similar comparisons have also been made with regards to the more sophisticated analyses (Morgenstern and Price, 1965). The general conclusion is that the modified Bishop method gives a better approximation of the more rigorous analyses than the Taylor method (Morgenstern and Price, 1965), and that the Taylor method is in gross error for large central angles of arc (Bishop, 1955).

In Figure 6, a plot of Equation 25 (y_o , the moment center, versus F) is presented for two different slip circles, labelled 1 and 2. The soil

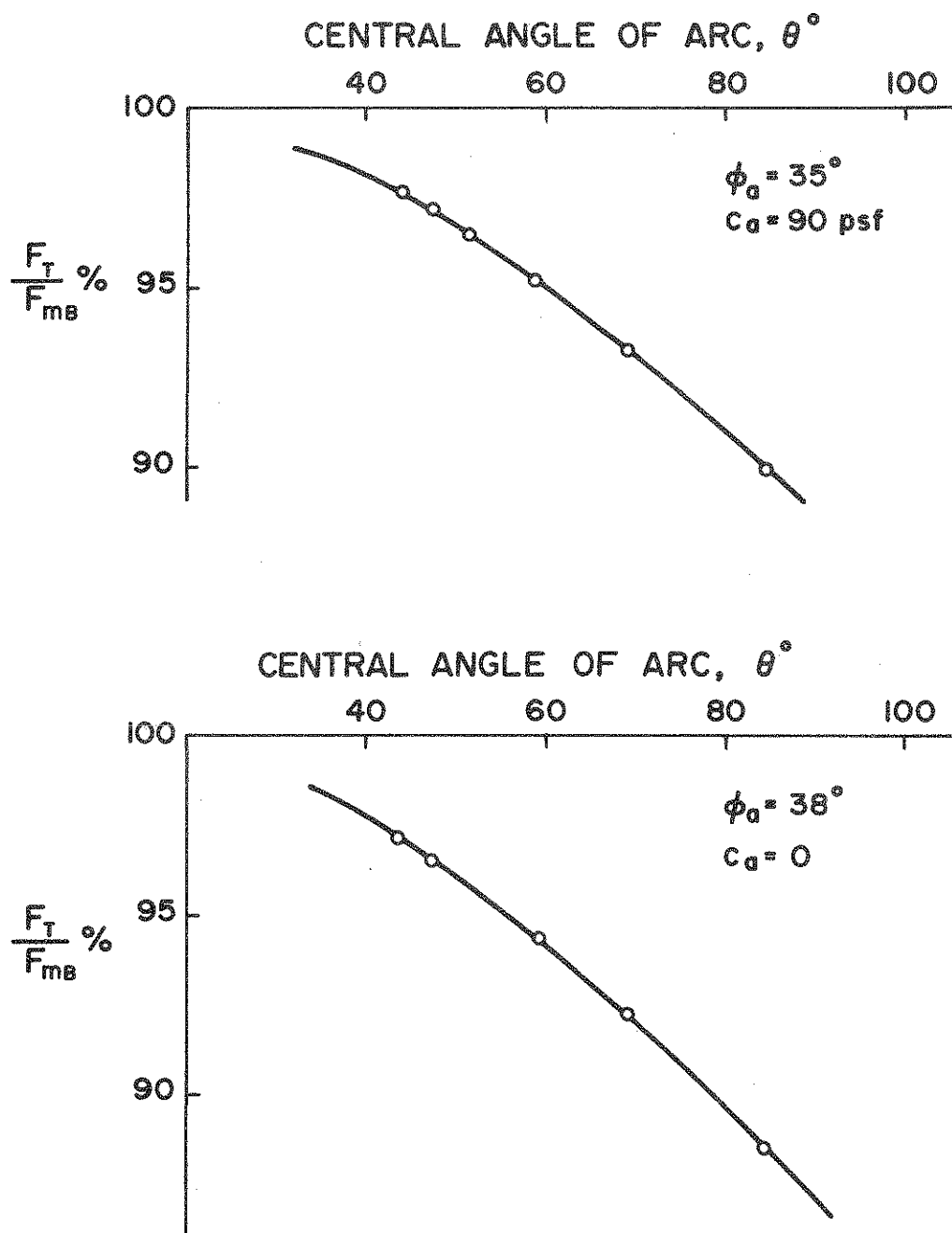


Figure 5 - Influence of Central Angle of Arc on Factor of Safety

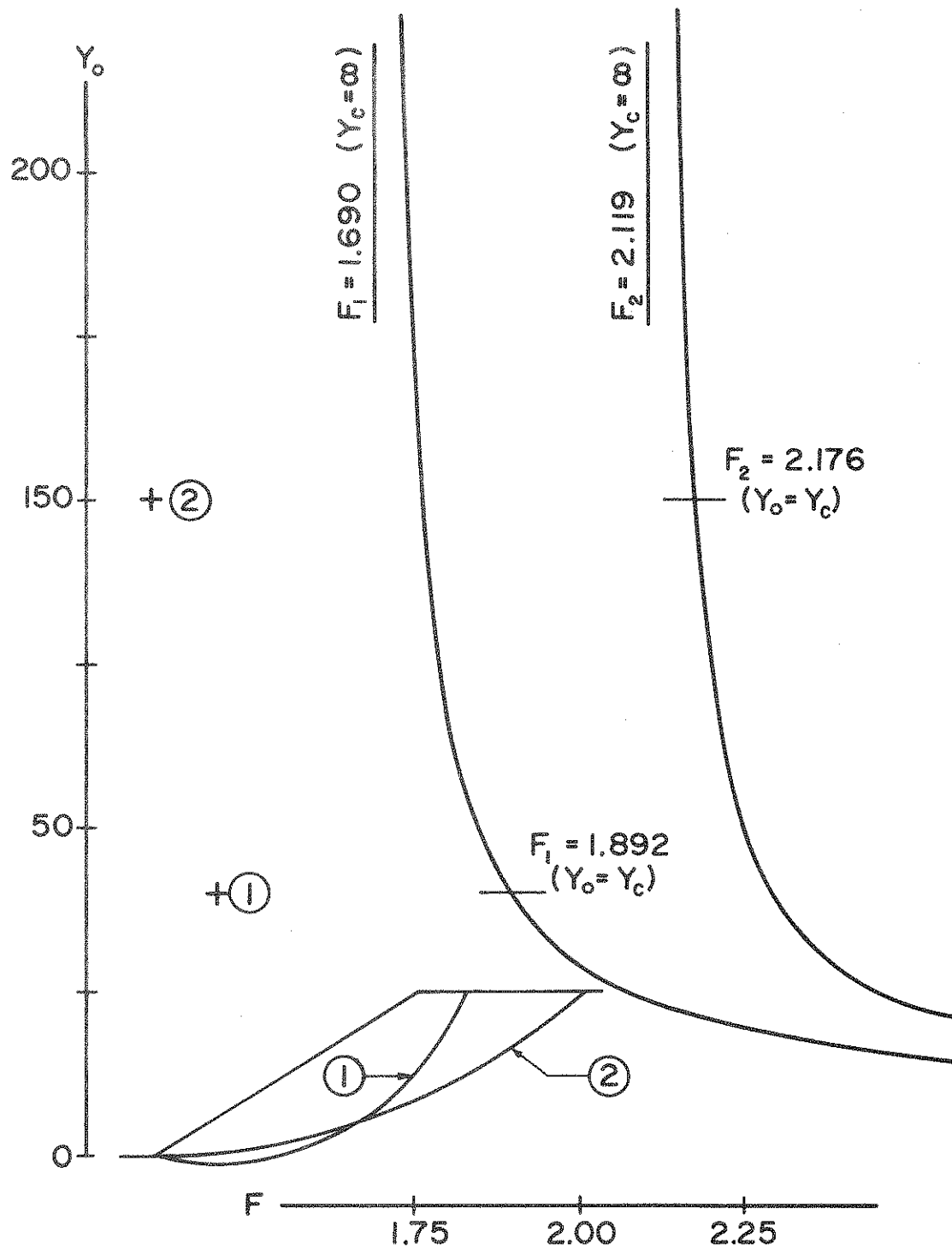


Figure 6 - Factor of Safety versus Moment Center
for $\phi_a = 35^\circ$, $c_a = 90$ psf

profile and assumed slip circles are superimposed on the plot so that the vertical scale of the plot is conformable with the vertical and horizontal scale of the profile.

Figures 7 and 8 show the results for the same profile and circles but with different material parameters.

Table 2 summarizes the Figures, includes the results of the Taylor analysis, and adds circles intermediate to 1 and 2.

The unique point that should be used for summation of external moments with the modified Bishop assumption is seen to be not the center of the circle but rather $y_o = \text{infinity}$. Examination of Table 2 indicates that the ratio of the Taylor result and the adapted, modified Bishop result ($y_o = \text{infinity}$) is essentially constant with the variation in θ . Since the modified Bishop ($y_o = y_c$) factor of safety varies with y_o (which is indirectly a function of θ), consistent comparisons when seeking the minimum factor of safety are not possible. Use of the modified Bishop assumption ($\Delta X = 0$) with summation of external moments at $y_o = \text{infinity}$ seems more appropriate, because the F is a minimum with respect to such a center. The use of $y_o = y_c$ for the Taylor assumption is appropriate because of the force summation in the radial direction and because the F is minimized with such a center. The $y_o = \infty$ center is convenient also for the irregular surface analysis.

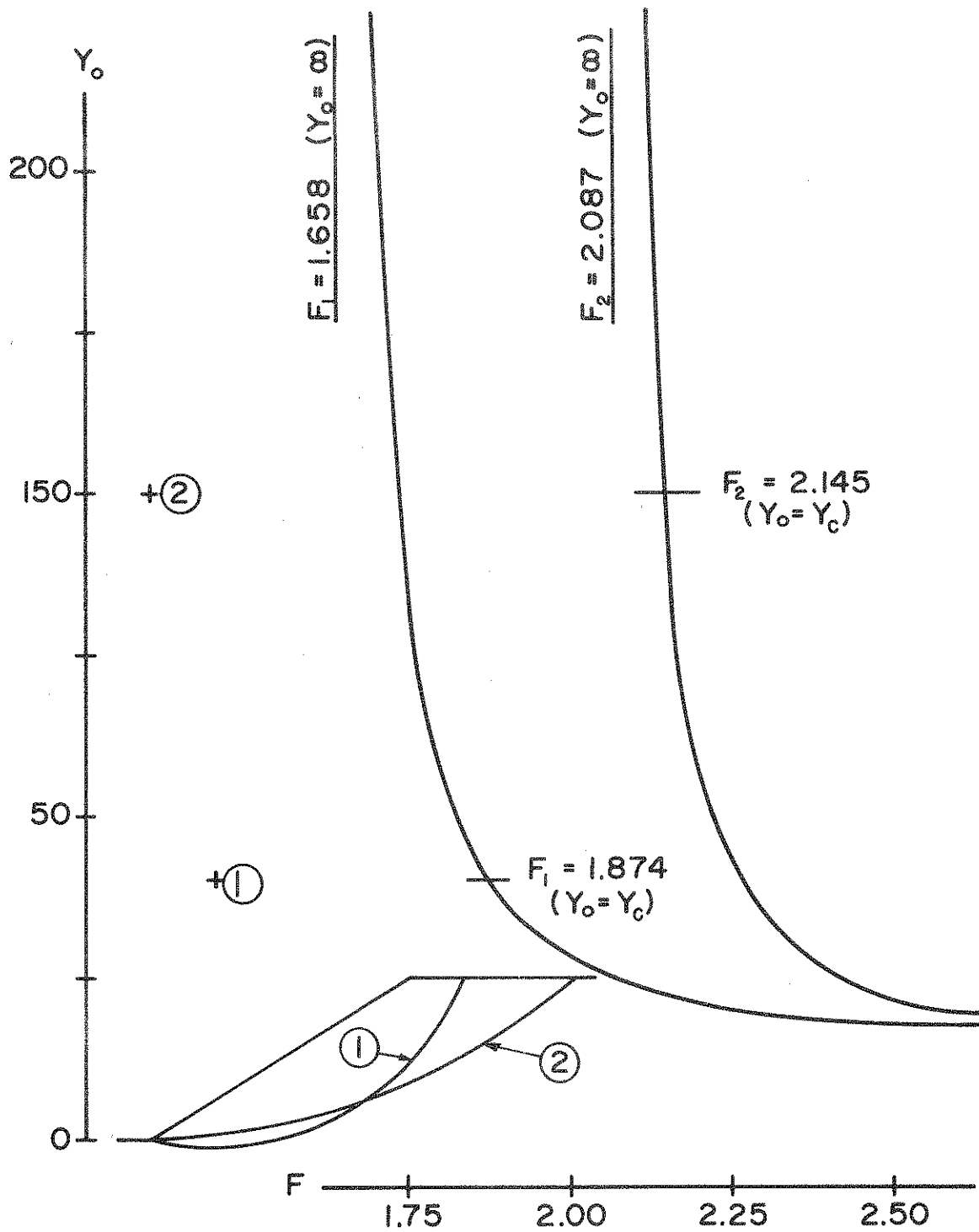


Figure 7 - Factor of Safety versus Moment Center
for $\phi_a = 38^\circ$

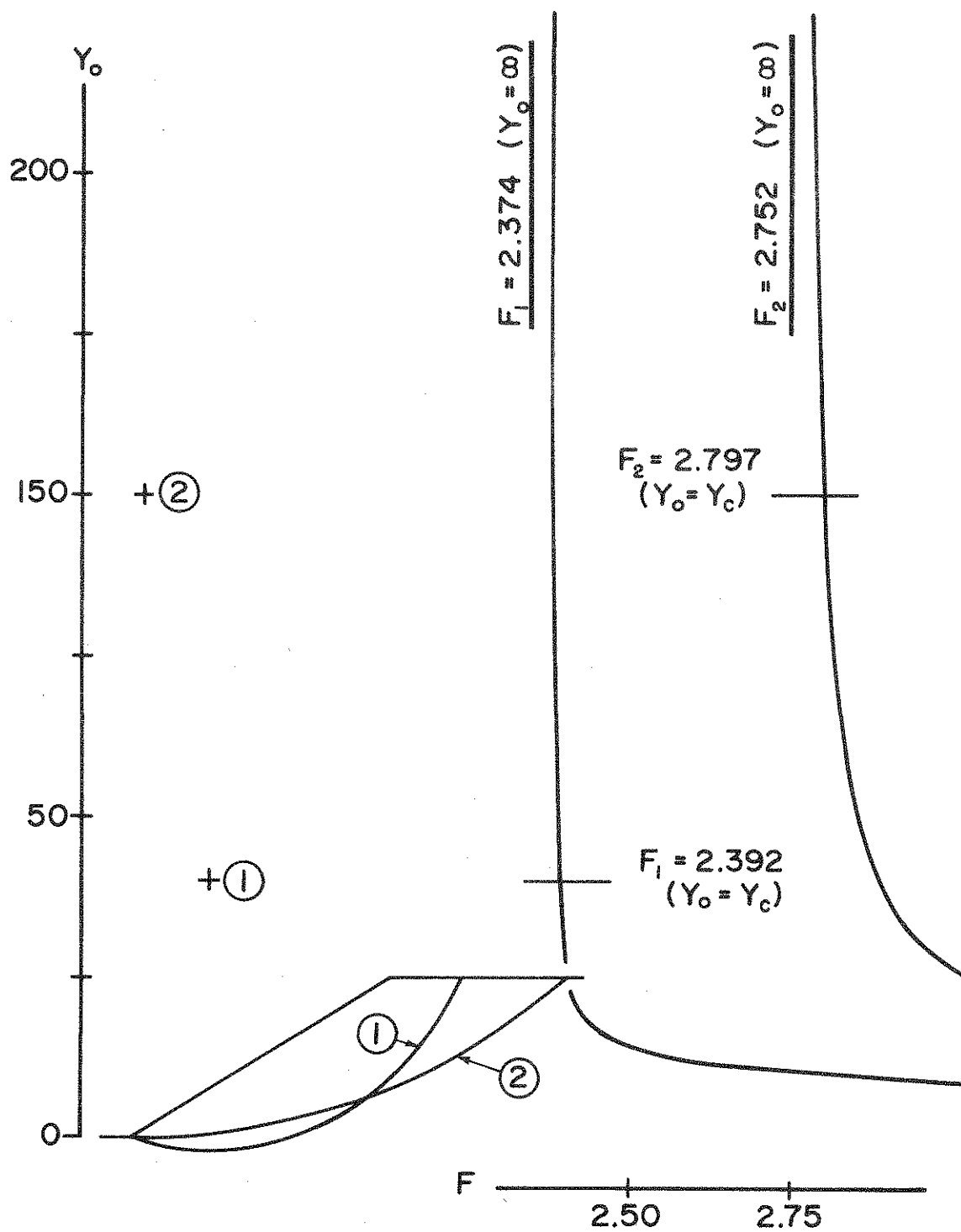


Figure 8 - Factor of Safety versus Moment Center
for $c_o = 1000$ psf.

Table 2

Summary of Central Angle of Arc and Moment Center versus F
 $(\gamma = 130 \text{ pcf})$

Central θ°	$\phi_a = 35^\circ, c_a = 90 \text{ pcf}$			$\phi_a = 38^\circ$			$c_a = 1000 \text{ psf}$		
	F_T	F_{MB} $Y_O = Y_C$	F_{MB} $Y_O = \infty$	F_T	F_{MB} $Y_O = Y_C$	F_{MB} $Y_O = \infty$	F_T	F_{MB} $Y_O = Y_C$	F_{MB} $Y_O = \infty$
84.26 (circle 1)	1.704	1.892	1.690	1.661	1.874	1.658	2.392	2.392	2.374
68.53	1.764	1.891	1.756	1.726	1.870	1.726	2.407	2.407	2.362
58.20	1.849	1.944	1.843	1.816	1.927	1.817	2.456	2.456	2.413
51.55	1.941	2.016	1.936	1.910	1.995	1.911	2.537	2.537	2.496
47.08	2.032	2.095	2.028	2.001	2.071	2.002	2.650	2.650	2.609
44.04 (circle 2)	2.121	2.176	2.119	2.086	2.145	2.087	2.797	2.797	2.752

PROGRAM CHARACTERISTICS

Purpose

The Fortran IV programs developed under this research include five main programs and eleven, interchangeable, supporting routines. The four main programs used for stability analysis are designated SLOPE1, SLOPE2, SLOPE3, and SLOPE4. The first three programs, SLOPE1, SLOPE2, and SLOPE3, analyze circular failure surfaces and differ only in the definition of the factor of safety. SLOPE1 calculates the Taylor factor of safety (Equation 5), and SLOPE2 calculates the modified Bishop factor of safety (Equation 14). The third program, SLOPE3 uses in the stability analysis the adjusted form of the modified Bishop factor of safety, i.e., the moment center is equal to $y_0 = \infty$ (Equation 26). The fourth stability program, SLOPE4, also calculates the adjusted form of the modified Bishop factor of safety but for irregular shaped failure surfaces.

The fifth main program, FLWNET, is a supporting program for the stability package. It is required whenever a flow net is included in the analysis. Program FLWNET generates the twenty-one coefficients needed to define a fifth order polynomial trend surface.

Table 3 lists the supporting routines called by each of the five main programs.

Table 3

Supporting Routines of each
Main Program

SLOPE1	SLOPE2	SLOPE3	SLOPE4	FLWNET
INOUT	INOUT	INOUT	INOUT	HEAD
STORE1	STORE2	STORE3	STORE4	
CROSS	CROSS	CROSS	SLPBNB	
WEIGHT	WEIGHT	WEIGHT	WEIGHT	
HEAD	HEAD	HEAD	HEAD	
RADIUS	RADIUS	RADIUS	FACTOR	
	FACTOR	FACTOR		

Usage

Input to the four stability programs is in three groups of information: description of the slope profile; description of the slip surface or search parameters; and transfer of control options.

Description of Profile

All four programs accept the same format for the description of the profile. The soil profile needs to be described completely in the first quadrant of a Cartesian coordinate system by a series of straight line segments. In addition, the x coordinate of the slope crest must be greater than the x coordinate of the slope toe, thereby describing the actual sloping ground surface by positive sloping line segments. The following order must be observed for entering the boundary segments. First, the ground surface segments are sequenced from left to right. Next, the subsurface boundary segments are ordered such that any vertical line would intersect, with depth, boundaries that are in a subsequent position of the order. This restriction on subsurface boundaries is necessitated by the slice weight calculation, but, of course, may be removed if execution time is not important and an ordering loop is provided in subroutine WEIGHT.

Correlation between the boundary segments of the profile and the soil types within the profile is achieved by recording with each boundary segment an integer code. The magnitude of this integer code represents the order in which the properties of the soil type below the segment are read later. A particular soil type, represented

by γ , c' , and ϕ' , needs to be entered only once, whereas, it is quite likely that several boundary segments will have the same integer code.

Both concentrated and uniform loads acting on the ground surface can be accommodated.

An equilibrium condition of ground water (for either static or steady state flow) can be managed by either of two options. For both cases, it is necessary to describe the entire ground water surface by a series of coordinate points entered in increasing x coordinate order. One option accounts for pore pressures by letting the vertical distance from the point in question to the ground water surface equal the pressure head. The other option allows for flow net variations by using the polynomial trend surface determined by program FLWNET.

Description of Slip Surface-Search Parameters

The format of the second group of information, the description of the slip surface or search parameters, is the same for the first three programs, SLOPE1, SLOPE2, and SLOPE3. Specific circular failure surfaces can be analyzed by describing the radius and the (x,y) coordinates of the center for each circle. If, on the other hand, the minimum factor of safety of a profile is sought, a grid search must be conducted.

Under the grid search option, it is necessary to indicate not only the specifications for the size of the grid but also a radius increment value. For any given circle center, subroutine RADIUS generates an array of radii that includes the maximum of the toe radius and crest radius, and all radii of circles that are tangent to subsurface boundaries. The maximum value in the array is the

minimum of radii of circles that are tangent to boundaries that have a zero soil type code. Therefore, it is imperative that the latter boundaries be entered accordingly. The main program calculates the factor of safety of all circles in the radius array. In addition, the main program generates circles having radii that are greater than each array radius, by integer increments of the radius increment value, but less than the succeeding array radius.

Figure 9 illustrates the grid search parameters.

Program SLOPE⁴ requires a different format for the description of the slip surface or search parameters than SLOPE1, SLOPE2, and SLOPE3. If a specific irregular surface needs to be analyzed, it must be described by a set of coordinates points ordered in increasing x coordinates. For the irregular surface analysis, it is also possible to conduct a search by defining eight parameters. The main program will generate surfaces within the irregular search specifications, overlay each surface on the soil profile, and solve for the factor of safety of each surface that is compatible with the profile.

If one were to assume that the critical irregular failure surface for the slope shown in Figure 10 passed through the points I_1 and I_2 where the y coordinate of I_1 is the minimum y coordinate of the surface, it would follow that the limiting shapes for the range of probable surfaces would be I_1I_2 and I_1AI_2 . Recognizing that the critical failure surface will possess some continuity, it is necessary to scan the triangle I_1AI_2 in some sequential search scheme.

Leonardo of Pisa, a thirteenth century mathematician, did a great deal of work in connection with series, from which the

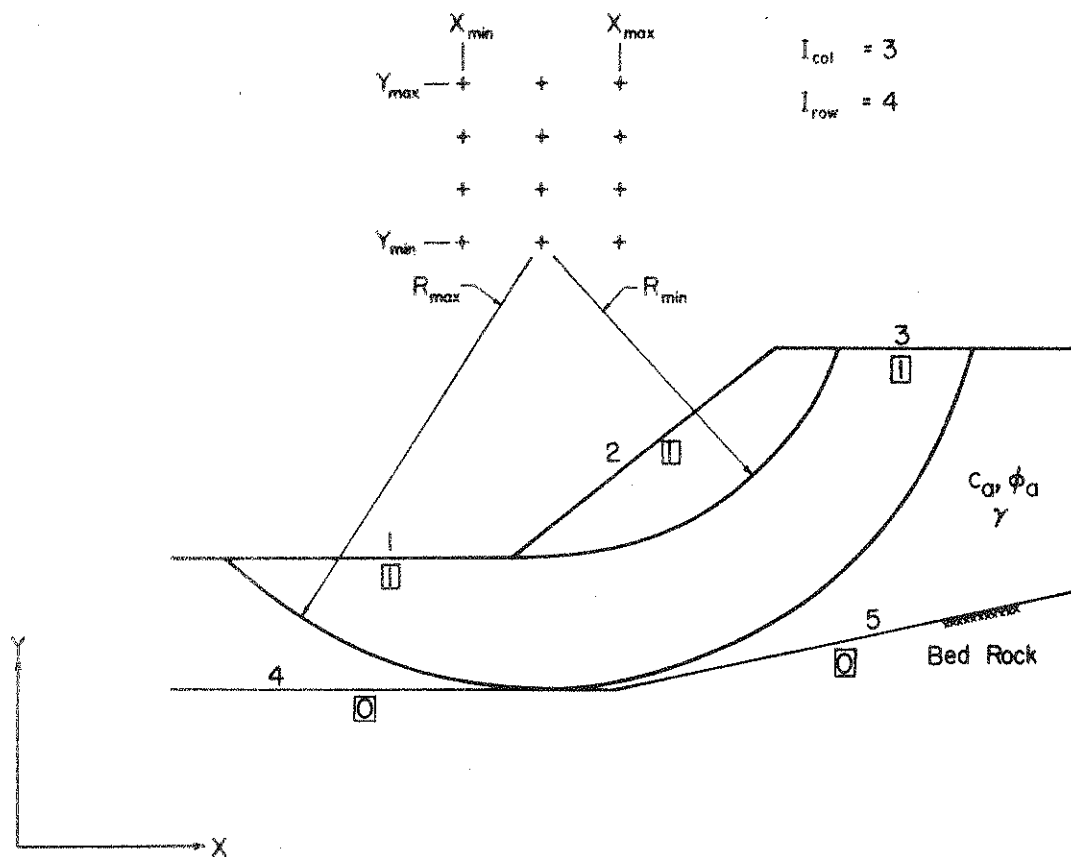


Figure 9 - Grid Search Parameters for Circular Surface Analysis

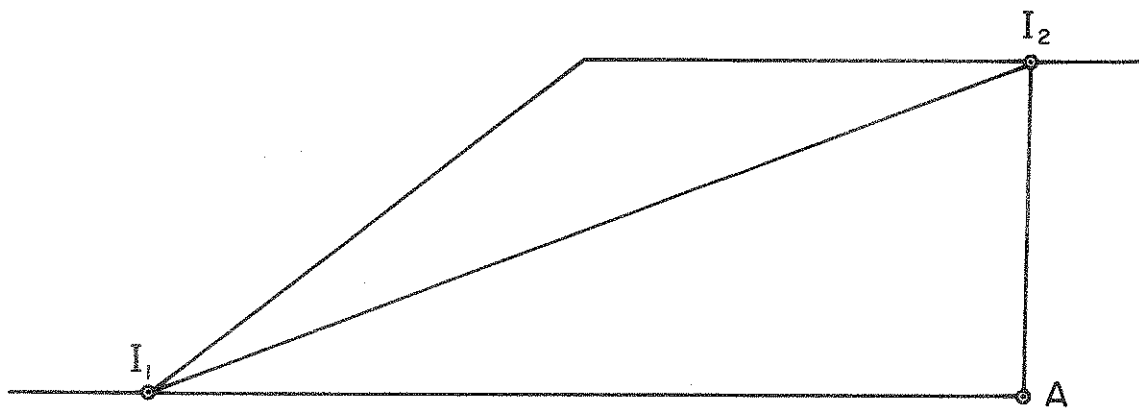


Figure 10 - Probable Range of Irregular Surfaces

Fibonacci sequence evolved (Wilde, 1964). This sequence is a progression in which the first two entries are defined as unity and all succeeding entries are equal to the sum of the two preceding entries. Or, in mathematical terms,

$$T_0 = 1$$

$$T_1 = 1$$

$$T_k = T_{k-1} + T_{k-2} \quad k = 2, 3, \dots \quad 27$$

The Fibonacci sequence is used for generating probable irregular surfaces.

The eight variables needed for the search are: y_{\max} , y_{\min} , x_{\max} , x_{\min} , x -control, N_{\min} , N_{\max} , and N_{sur} . The main program first divides the distance $(y_{\max} - y_{\min})$ into N_{\min} layers.¹ The array of y coordinates of the layers, Y^* , is calculated by a cosine function.

$$y_k = y_0 + H \left(1 - \cos \frac{\pi k}{2n} \right) \quad k = 1, 2, \dots, n \quad 28$$

where

$$H = y_{\max} - y_{\min}$$

$$y_0 = y_{\min}$$

and initially,

$$n = N_{\min}$$

-
1. The program can be modified to read in the turning points. This would be particularly suited to profiles characterized by weak-layer stratification.

Using the Y^* coordinates, a series of straight line segments is generated between x -control and x_{\max} such that the slope of each succeeding segment is in Fibonacci multiples of the slope of the initial segment. The x coordinates of the segments constitute the X^* array.

Therefore,

$$x_k = x_{k-1} + \frac{y_k - y_{k-1}}{\rho T_k} \quad k = 1, 2, \dots, n \quad 29$$

where

$$x_0 = x - \text{control}$$

$$x_n = x_{\max}$$

$$\text{and} \quad \rho = \frac{\sum_{i=0}^n \frac{y_{i+1} - y_i}{T_{i+1}}}{x_n - x_0}$$

Having generated the surface (X^*, Y^*) , the program examines the profile. If the specifications of the search and the definition of the profile are compatible, the factor of safety is calculated. The program then decreases x_n and calculates a new surface, and so on, until x_{\min} is reached. This iteration is repeated N_{sur} times.

Next, n is incremented by one, and the entire loop is repeated. The search is completed when n equals N_{\max} .

When $(x_0 = x\text{-control}, y_0 = y_{\min})$ is defined within the profile, each generated surface is completed by one additional segment directed back to the ground surface. For each (X^*, Y^*) , the program currently

calculates the factor of safety for three such segments, directed at 30° , 45° , and 60° from the -x direction.

Figure 11 illustrates the irregular surface search parameters, and Figure 12 demonstrates the variation in shape resulting from an increase in n with all other variables constant.

Transfer of Control

The third group of information, the transfer of control option, is also acceptable to all four stability programs. The transfer card allows for re-entry into either the first group or second group of information.

Flow Net Analysis

Input data for the fifth main program, FLWNET, should be conformable with the Cartesian coordinate system of the stability programs. In order to perform the trend surface analysis, it is necessary to know and record x , y , and total head observations. The accuracy of the fit is of course commensurate with the number of observations.

Special Computational Methods

Slice Width for Circular Analysis

In the method of slices, the factor of safety for a given circular failure surface converges to a constant as the number of slices is increased. This effect is a result of two factors. First, the length of the failure surface approaches in the limit the true arc length of the circle as the circle is divided into smaller secants.



Figure 11 - Irregular Search Parameter for Irregular Surface Analysis

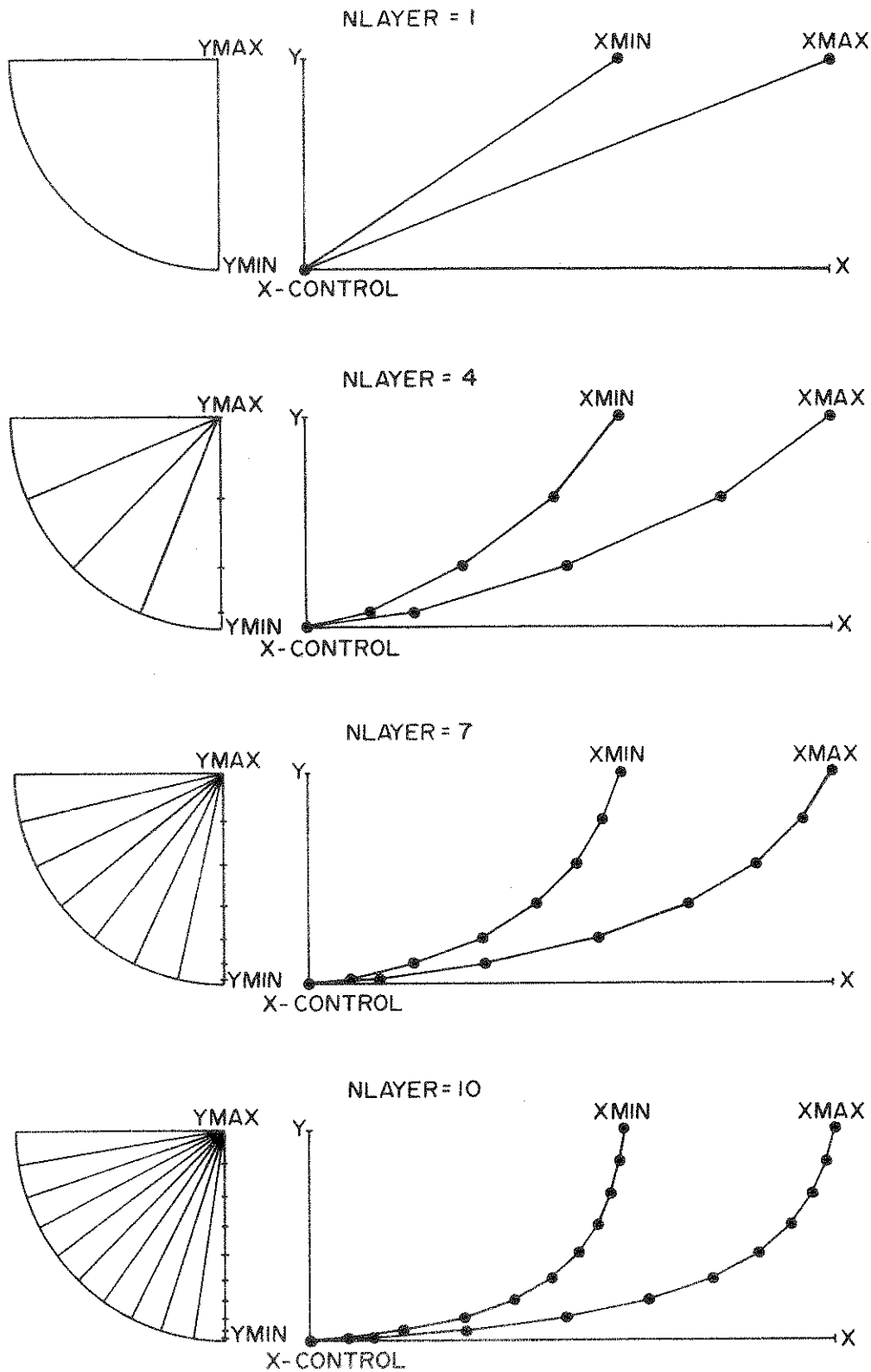


Figure I2 - Variation in Shape of Irregular Surface for Increasing n

The second factor, which is of lesser consequence, is that the weight of the subdivided failure mass approaches also in the limit the true weight of the sliding circular mass. In previous analyses, the sliding body has often been divided into n equal width slices, where n is an arbitrary value in the range of 10-25. However, it is more advantageous to allow the slice width to vary.

Referring to Figure 13, the error of approximating \widehat{L} by \bar{L} is related to θ , the central angle for the slice. By using a constant value of θ , rather than t , it is possible to minimize this error, thereby controlling the aforementioned effects, and giving a constant value for the factor of safety.

Again referring to Figure 13,

$$\bar{L} = 2R \sin \frac{\theta}{2} \quad \text{from elementary geometry} \quad 30$$

Also,

$$\cos \left(\frac{\theta}{2} + \eta \right) = \frac{t}{\bar{L}} \quad 31$$

Substituting \bar{L} ,

$$t = 2R \sin \frac{\theta}{2} \cos \left(\frac{\theta}{2} + \eta \right) \quad 32$$

or

$$x_{i+1} = x_i + 2R \sin \frac{\theta}{2} \cos \left(\frac{\theta}{2} + \eta \right) \quad 33$$

Since it is not possible to determine by analytical means a limiting value of θ , a number of trials were investigated. As a result, a value of $\theta = 0.1$ radian was used in each program.

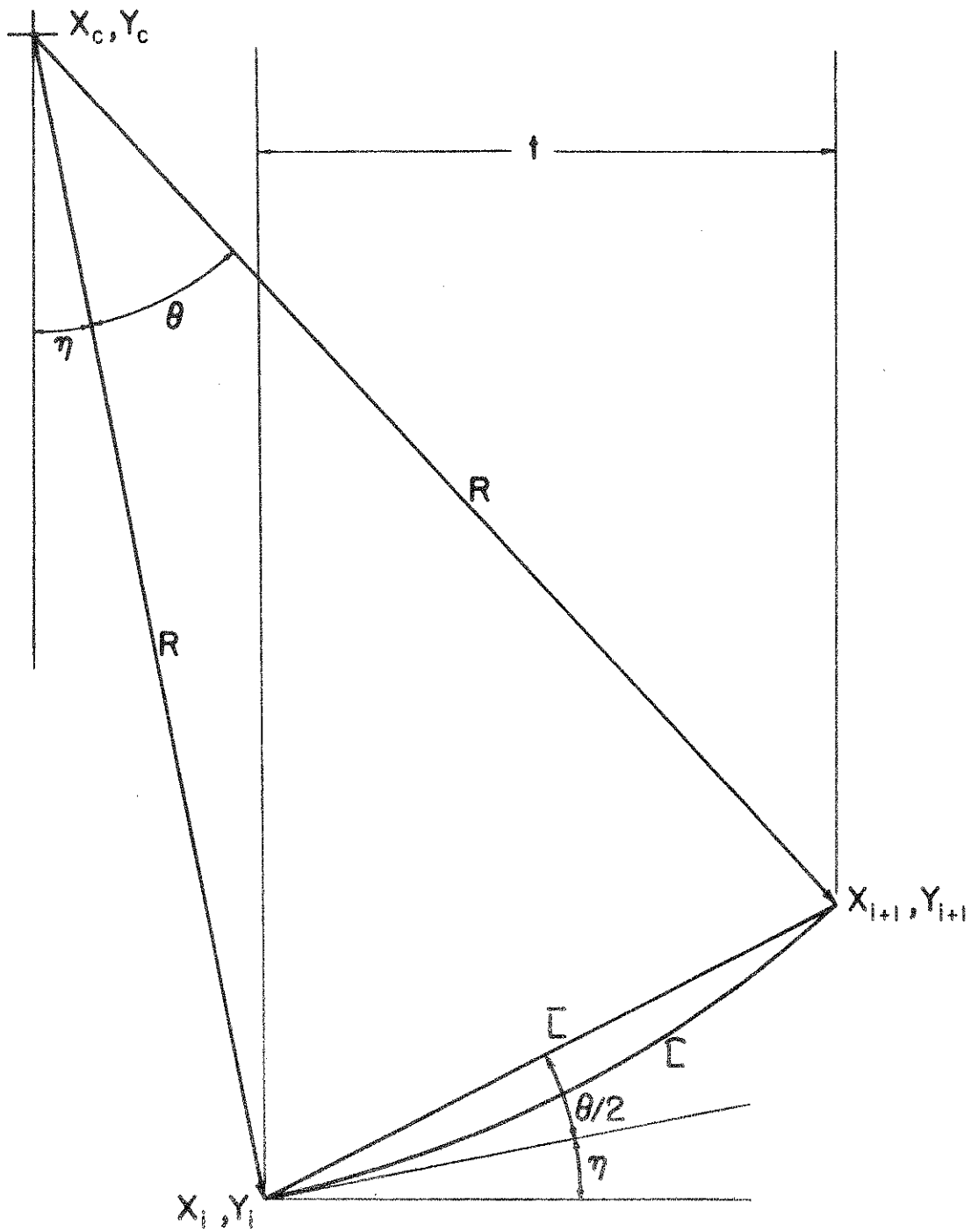


Figure 13 - Central Angle of Slice and Slice Width

Iteration for Factor of Safety

In the modified Bishop equation and in the adjusted form of the modified Bishop equation, the factor of safety cannot be solved for explicitly. Consequently, an iterative technique is necessary.

In the Newton-Raphson method of finding zeros (Hamming, 1962), it is possible to show that a better solution of $g(F)$ is given by,

$$F_1 = F_0 - \frac{g(F_0)}{g'(F_0)} \quad 34$$

where F_0 is an approximate solution.

The modified Bishop equation as developed previously is

$$g(F) = \sum \bar{y} \left(\frac{A_1 - FA_2}{F + A_3} \right) = 0 \quad 35$$

Taking the first derivative yields,

$$g'(F) = \sum \{ \bar{y} \left[- \frac{A_1 - FA_2}{(F + A_3)^2} - \frac{A_2}{F + A_3} \right] \} \quad 36$$

Simplifying,

$$g'(F) = - \sum \bar{y} \left[\frac{A_1 + A_2 A_3}{(F + A_3)^2} \right] \quad 37$$

Backsubstituting,

$$F_1 = F_0 + \frac{\sum \bar{y} \left(\frac{A_1 - F_0 A_2}{F_0 + A_3} \right)}{\sum \bar{y} \left[\frac{A_1 + A_2 A_3}{(F_0 + A_3)^2} \right]} \quad 38$$

Subroutine FACTOR allows for a maximum of ten iterations of Equation 38, although convergence to a successive difference of less than 0.005 generally occurs within the third iteration.

Trend Surface Analysis

Program FLWNET is a modification of program TREND developed by A. K. Turner (1969), for the GCARS system. The matrix algebra procedure used for the computation of the trend surface coefficients is described in Chapter 2 of Draper and Smith (1967).

Capacities and Limitations

The stability programs, as currently developed, are restricted by the size of the problem. Since linkage between the programs and routines is provided by blank common storage, it is imperative that for any change of dimension in one program a corresponding change be made in the other routines. To assist the user in making necessary changes, Table 4 is provided.

The maximum number of profile boundaries is twenty, with no more than fifteen different soil types allowed. The concentrated and uniform ground surface loadings are limited to five each. The ground water surface can be defined by a maximum of nine coordinates.

In defining an irregular surface for the individual surface analysis, no more than twelve points can be used. The irregular search is limited by a maximum of ten layers.

Program FLWNET accommodates one-hundred observations for the polynomial fit.

Since the CDC 6500 has a 60-byte word length, single precision calculations were used in program FLWNET. For systems using word lengths of smaller size, double precision must be used for the matrix calculations. Therefore, the following variables should be declared double precision: A, AM, BB, PAR, SSR, SSZ, and XINV.

Table 5 lists the CDC 6500 word length of each routine.

Table 5
CDC 6500 Program Lengths

Program Name	Program Length, Words (OCTAL)
SLOPE1	2617 Including I-O Buffers
SLOPE2	2624 Including I-O Buffers
SLOPE3	2624 Including I-O Buffers
SLOPE4	3222 Including I-O Buffers
FLWNET	5353 Including I-O Buffers
INOUT	1154 Including I-O Buffers
STORE1	566
STORE2	636
STORE3	613
STORE4	553
CROSS	604
SLPBND	400
WEIGHT	214
RADIUS	236
FACTOR	124
HEAD	112

SUMMARY AND CONCLUSIONS

The primary objective of this research was the development of a computer-assisted system for the prediction of slope stability. The resulting set of programs is proficient in accommodating a complex ground surface and subsurface profile of spatial variations in material properties, a steady state flow domain, both uniform and concentrated ground surface loadings. Efficient search patterns are provided to assist the engineer in locating the critical shearing surface.

It has been contended (Bishop, 1955) that the modified Bishop method gives a more realistic solution, within the congruence of limiting equilibrium, than the Taylor method. The argument that the Bishop assumption ($\Delta X = 0$) better approximates the real situation than the Taylor assumption ($\Delta E_n + \Delta X_n = 0$) seems to have merit. However, neither method satisfies equilibrium and the factor of safety, F , as calculated by the modified Bishop has been shown to vary in a regular fashion with the center selected for the moment equation. If the use of the circle center as a center for moments gives a more realistic value for F , it is believed to be a matter of coincidence. Accordingly it is recommended that this element of chance be eliminated by taking the moment center at a very large value of the Y coordinate, rather than at the center of the assumed

circular failure surface. Use of the center at a large value of Y further produces a minimum value of F . Although the Taylor method is applicable only to circular failure surfaces, the adjusted form of the modified Bishop approach can be applied to the irregular surface as well.

More sophisticated methods of analysis than the Taylor or modified Bishop techniques exist, but, for most practical problems, the simpler methods are satisfactory. It is important not only to use a meaningful method of analysis in determining stability, but also to thoroughly, yet efficiently, scan the soil profile for features that will tend to yield the minimum value of F . This latter requirement emphasizes the need for a rapid method of analysis. Therefore, the more sophisticated methods of analysis should probably serve as a means of assessing the reliability of the simpler methods for special problems, rather than being used in the search proper.

RECOMMENDATIONS FOR FURTHER STUDY

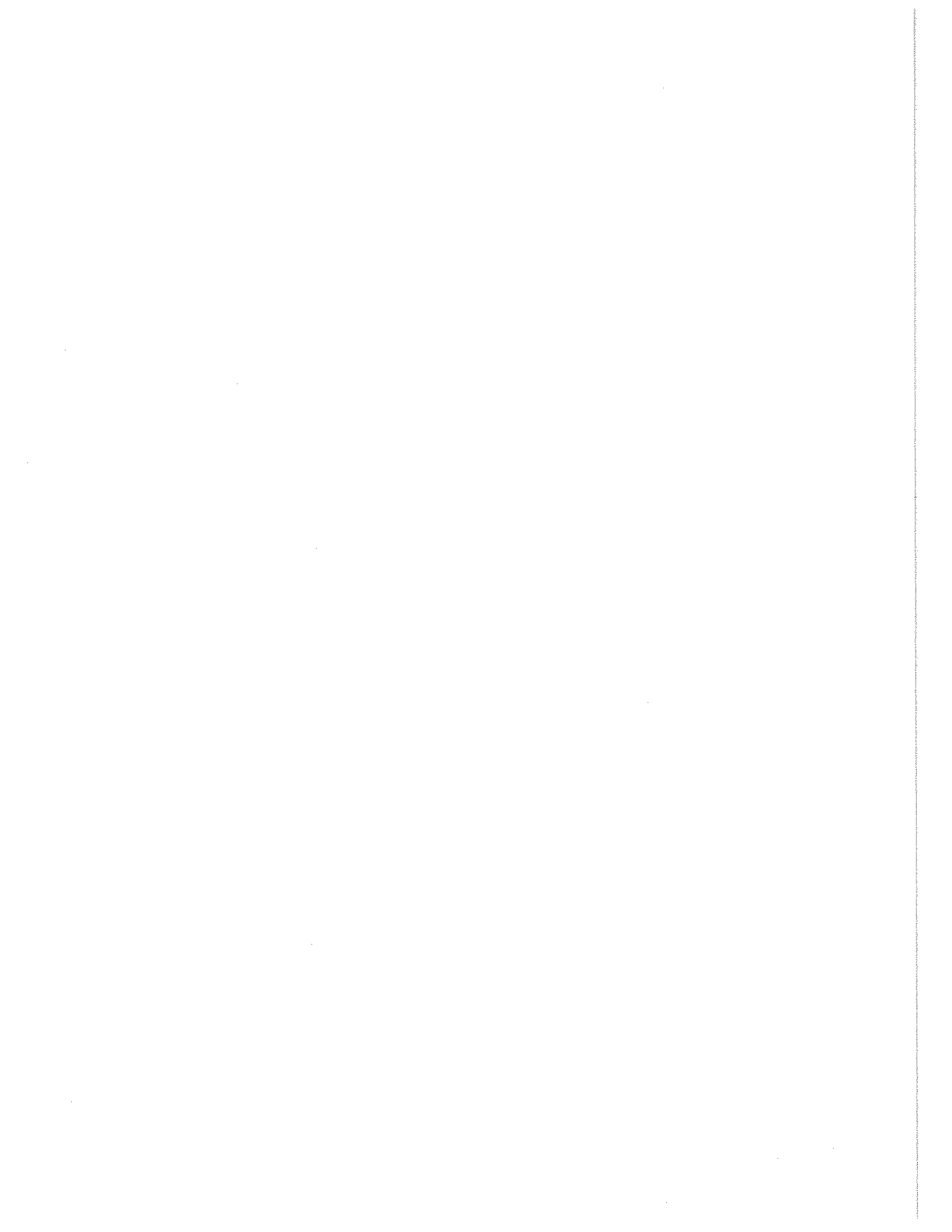
1. It would be desirable to compare the results of the more sophisticated methods of analysis, e.g., the Morgenstern-Price and the Bell method, with the results of the adapted form of the modified Bishop method. It may be feasible to pick a particular point for external moment summation in the simpler method, determined by the characteristic shape of Equation 25, in predicting a value of F approximately equal to that of the more sophisticated methods.
2. The irregular search technique needs further development. At present, the surface from (x -control, x_{\min}) is generated in the negative X direction by one of three straight lines. It would be desirable to expand the internal search to include this segment in the determination of a minimum F .
3. The present program does not accommodate pore pressures in excess of a steady state equilibrium. Such pressures are extant during undrained or partially drained shear. Analysis of the ordinary draw-down case requires such input.

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LIST OF REFERENCES

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APPENDIX A
PROGRAM LISTING AND DOCUMENTATION

APPENDIX A
PROGRAM LISTING AND DOCUMENTATION

Purdue University has implemented a documentation routine titled FORSTAT. Program FORSTAT lists a given routine and produces a cross-reference listing for both statement and variable references. This entire program package has been listed by FORSTAT as an aid to the user in making modifications.

FORSTAT Listing of Program SLOPE1

```

1.      PROGRAM SLOPE1(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT)
C      -----SL1 2
C      PROGRAM SLOPE1
C      -----SL1 4
C      -----SL1 6
C      PURPOSE-
C      -----SL1 8
C      TO ANALYZE A SLOPE PROFILE FOR A CIRCULAR TYPE OF FAILURE
C      -----SL1 10
C      USING THE TAYLOR FACTOR OF SAFETY.
C      -----SL1 12
C      -----SL1 14
C      CONTROL CARDS-
C      -----SL1 16
C      -----SL1 18
C      -----SL1 20
C      ALL FORMATS ARE INTEGER OR FIXED POINT DEPENDING UPON FORTRAN
C      CODING OF VARIABLES, UNLESS OTHERWISE STATED.
C      -----SL1 22
C      INPUT MUST BE IN THE FOLLOWING UNITS,
C      -----SL1 24
C      LENGTH IN FEET.
C      -----SL1 26
C      FORCE IN POUNDS.
C      -----SL1 28
C      ANGLE IN DEGREES.
C      -----SL1 30
C      -----SL1 32
C      (A) DESCRIPTION OF PROFILE-
C      -----SL1 34
C      SEE SUBROUTINE INOUT.
C      -----SL1 36
C      (B) DESCRIPTION OF SLIP SURFACE/SEARCH-
C      -----SL1 38
C      (1) OPTION CARD
C      -----SL1 40
C      IOPT (COL 1) IF IOPT=1, INDIVIDUAL CIRCLE ANALYSIS.
C      -----SL1 42
C      IF IOPT=2, GRID ANALYSIS.
C      -----SL1 44
C      INUM (COL 2-3) NUMBER OF CIRCLES TO BE READ OR NUMBER OF
C      -----SL1 46
C      GRIDS TO BE READ DEPENDING UPON IOPT.
C      -----SL1 48
C      -----SL1 50
C      (2) SLIP SURFACE/SEARCH PARAMETER CARD(S)
C      -----SL1 52
C      -----SL1 54
C      COMPLETE EITHER 2A OR 2B DEPENDING UPON THE IOPT VALUE. THERE MUST
C      -----SL1 56
C      BE INUM TOTAL CARDS IN EITHER CASE.
C      -----SL1 58
C      -----SL1 60
C      (2A) INDIVIDUAL CIRCLE ANALYSIS CARD
C      -----SL1 62
C      XCEN (COL 1-10) X-CENTER OF CIRCLE.
C      -----SL1 64
C      YCEN (COL 11-20) Y-CENTER OF CIRCLE.
C      -----SL1 66
C      R (COL 21-30) RADIUS OF CIRCLE.
C      -----SL1 68
C      -----SL1 70
C      (2B) GRID ANALYSIS CARD
C      -----SL1 72
C      XMAX (COL 1-10) MAXIMUM X-COORD OF GRID.
C      -----SL1 74
C      XMIN (COL 11-20) MINIMUM X-COORD OF GRID.
C      -----SL1 76
C      YMAX (COL 21-30) MAXIMUM Y-COORD OF GRID.
C      -----SL1 78
C      YMIN (COL 31-40) MINIMUM Y-COORD OF GRID.
C      -----SL1 80
C      DRAD (COL 41-50) RADIUS INCREMENT VALUE.
C      -----SL1 82
C      ICOL (COL 51-52) NUMBER OF COLUMNS IN GRID.
C      -----SL1 84
C      IROW (COL 53-54) NUMBER OF ROWS IN GRID.
C      -----SL1 86
C      -----SL1 88
C      (C) TRANSFER OF CONTROL-
C      -----SL1 90
C      (1) CONTROL OPTION CARD
C      -----SL1 92
C      WAY (COL 1-3) IF WAY=NEW, CONTROL IS TRANSFERRED TO (A).
C      -----SL1 94
C      IF WAY=OLD, CONTROL IS TRANSFERRED TO (B).
C      -----SL1 96
C      IF WAY=END, PROGRAM IS TERMINATED.
C      -----SL1 98
C      -----SL1 100
C      -----SL1 102
C      -----SL1 104
C      -----SL1 106
C      REQUIRED ROUTINES-
C      -----SL1 108
C      SUBROUTINE STORE1
C      -----SL1 110
C      SUBROUTINE INOUT
C      -----SL1 112
C      SUBROUTINE CROSS
C      -----SL1 114
C      SUBROUTINE RADIUS
C      -----SL1 116
C      SUBROUTINE WEIGHT (CALLED BY STORE1)
C      -----SL1 118
C      FUNCTION HEAD (CALLED BY STORE1)
C      -----SL1 120
C      -----SL1 122
C      SYSTEM ROUTINES-
C      -----SL1 124
C      FUNCTION FLOAT
C      -----SL1 126
C      -----SL1 128
C      -----SL1 130
C      INTEGER OLD,WAY
C      -----SL1 132
C      DIMENSION RAD(15)
C      -----SL1 134
C      DATA NEW,OLD,3HNEW,3HOLD/
C      -----SL1 136
C      CALL INOUT (1)
C      -----SL1 138
C      READ (5,130) IOPT,INUM
C      -----SL1 140
C      GO TO (15,30), IOPT
C      -----SL1 142
C      -----SL1 144
C      INDIVIDUAL CIRCLE OPTION
C      -----SL1 146
C      -----SL1 148
C      WRITE (6,135) INUM
C      -----SL1 150
C      WRITE (6,140)
C      -----SL1 152

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10.      DO 25 K=1,INUM                      SL1 152
11.      READ (5,145) XCEN,YCEN,H           SL1 154
12.      ISTOP=1                             SL1 156
13.      CALL CROSS (ISTOP,XCEN,YCEN,H)     SL1 158
14.      GO TO (20,25), ISTOP               SL1 160
15.      CALL STORE1 (XCEN,YCEN,H,F1)       SL1 162
16.      WRITE (6,150) XCEN,YCEN,H,F1      SL1 164
17.      25 CONTINUE                        SL1 166
18.      GO TO 115                           SL1 168
19.      C                                   SL1 170
20.      C -----                          SL1 172
21.      C GRID OPTION                       SL1 174
22.      C -----                          SL1 176
23.      30 WRITE (6,145) INUM              SL1 178
24.      DO 110 K=1,INUM                    SL1 180
25.      READ (5,175) AMAX,XMIN,YMAX,YMIN,URAD,ICOL,IROW SL1 182
26.      WRITE (6,170) AMAX,YMAX,XMIN,YMIN,ICOL,IROW,URAD SL1 184
27.      WRITE (6,140)                       SL1 186
28.      DX=FLOAT(ICOL-1)                   SL1 188
29.      IF (DX) 35,35,40                    SL1 190
30.      35 DX=1.0                           SL1 192
31.      GO TO 45                             SL1 194
32.      C                                   SL1 196
33.      40 DX=(XMAX-XMIN)/DX                 SL1 198
34.      45 DY=FLOAT(IROW-1)                 SL1 200
35.      IF (DY) 50,50,55                    SL1 202
36.      50 DY=1.0                           SL1 204
37.      GO TO 60                             SL1 206
38.      C                                   SL1 208
39.      55 DY=(YMAX-YMIN)/DY                 SL1 210
40.      60 DO 105 J=1,IROW                   SL1 212
41.      YCEN=YMAX-FLOAT(JY-1)*DY            SL1 214
42.      DO 100 IX=1,ICOL                     SL1 216
43.      FMIN=999999.                         SL1 218
44.      XCEN=XMIN+FLOAT(IX-1)*DX              SL1 220
45.      WRITE (6,160) XCEN,YCEN             SL1 222
46.      CALL RADIUS (XCEN,YCEN,H,RD,NRAD)    SL1 224
47.      DO 95 I=1,NRAD                       SL1 226
48.      R=RD(I)                             SL1 228
49.      ISTOP=1                             SL1 230
50.      CALL CROSS (ISTOP,XCEN,YCEN,H)     SL1 232
51.      GO TO (70,85), ISTOP                 SL1 234
52.      CALL STORE1 (XCEN,YCEN,H,F1)       SL1 236
53.      IF (F1-FMIN) 75,80,80                SL1 238
54.      FMIN=F1                             SL1 240
55.      WRITE (6,165) H,F1                  SL1 242
56.      IF (I-NRAD) 90,95,95                SL1 244
57.      90 R=H*URAD                          SL1 246
58.      IF (R-RD(I+1)) 65,95,95             SL1 248
59.      95 CONTINUE                          SL1 250
60.      100 WRITE (6,185) FMIN               SL1 252
61.      105 WRITE (6,180)                   SL1 254
62.      110 CONTINUE                        SL1 256
63.      C -----                          SL1 258
64.      C DETERMINE TRANSFER OF CONTROL     SL1 260
65.      C -----                          SL1 262
66.      115 READ (5,190) WAY                SL1 264
67.      IF (WAY-NEW) 120,5,120              SL1 266
68.      IF (WAY-OLD) 125,10,125             SL1 268
69.      125 STOP                             SL1 270
70.      C                                   SL1 272
71.      130 FORMAT (11,12)                  SL1 274
72.      135 FORMAT (1H1///4X,*INDIVIDUAL CIRCLE OPTION SPECIFIED#/13X,I3,* CIRCLES TO BE ANALYZED#//) SL1 276
73.      140 FORMAT (1H /BX,*X-CENTER#,5X,*Y-CENTER#,5X,*RADIUS#,10X,*FS#//) SL1 280
74.      145 FORMAT (13F10.4)                SL1 282
75.      150 FORMAT (1H 6X,F8.1,5X,F8.1,4X,F8.2,F15.3) SL1 284
76.      155 FORMAT (1H1///4X,*GRID OPTION SPECIFIED#/13X,I3,* GRID TO BE ANALYZED#//) SL1 288
77.      160 FORMAT (1H /BX,F8.1,5X,F8.1)    SL1 290
78.      165 FORMAT (1H 32X,F8.2,F13.3)       SL1 292
79.      170 FORMAT (1H ///10X,*GRID SPECIFICATIONS#//12X,*XMAX =#,F10.1,10X,*XMIN =#,F10.1,12X,*YMAX =#,F10.1,12X,*YMIN =#,F10.1,12X,*ICOL =#,I3,12X,*IROW =#,I3,12X,*RADIUS INCREMENT =#,F10.1//) SL1 296
80.      175 FORMAT (5F10.0,2I2)              SL1 300
81.      180 FORMAT (1H //)                  SL1 302
82.      185 FORMAT (1H 14X,*MINIMUM FS FOR THIS CENTER = #,F10.3) SL1 304
83.      190 FORMAT (A3)                     SL1 306
84.      195 ENP                             SL1 308

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STATEMENT NUMBER	DEFINITION	REFERENCES
5	5.	58.
10	6.	59.
15	8.	7.
20	15.	14.
25	17.	10. 14.
30	19.	7.
35	26.	25.
40	28.	25.
45	29.	27.
50	31.	30.
55	33.	30.
60	34.	32.
65	43.	52.
70	46.	45.
75	48.	47.
80	49.	47.
85	50.	45.
90	51.	50.
95	53.	41. 50. 52.
100	54.	36.
105	55.	34.
110	56.	20.
115	57.	18.
120	59.	58.
125	60.	54.
130	61. FORMAT	6.
135	62. FORMAT	8.
140	63. FORMAT	9. 23.
145	64. FORMAT	11.
150	65. FORMAT	16.
155	66. FORMAT	19.
160	67. FORMAT	39.
165	68. FORMAT	49.
170	69. FORMAT	22.
175	70. FORMAT	21.
180	71. FORMAT	55.
185	72. FORMAT	54.
190	73. FORMAT	57.

LABEL	TYPE	DEFINITION	REFERENCES
CROSS	H	13. SUBROUTINE	44.
DRAD	H	21.	22. 51.
DX	H	24.	25. 26. 28. 38.
DY	H	24.	30. 31. 33. 35.
FLOAT	H	24. FUNCTION	29. 35. 38.
FMIN	H	37.	47. 48. 54.
FT	H	15.	16. 46. 47. 48. 49.
I	I	41.	42. 50. 52.
ICOL	I	21.	22. 24. 36.
INOUT	I	5. SUBROUTINE	
INUM	I	6.	8. 18. 19. 20.
IOPF	I	6.	7.
IROW	I	21.	22. 24. 34.
ISTOP	I	12.	13. 14. 43. 44. 45.
IX	I	36.	38.
IY	I	34.	35.
K	I	10.	20.
NEW	I	4. DATA	58.
NRAD	I	40.	41. 50.
OLU	I	2. DATA	4. 54.
R	H	11.	13. 15. 16. 42. 44. 46. 49. 51. 52.
RAD	H	3. D	40. 42. 52.
RADIUS	H	40. SUBROUTINE	
STORE1	K	15. SUBROUTINE	46.
WAY	I	2.	57. 58. 59.
XCEN	H	11.	13. 15. 16. 38. 39. 40. 44. 46.
XMAX	H	21.	22. 28. 38.
AMIN	H	21.	22. 28. 38.
YCEN	H	11.	13. 15. 16. 35. 39. 40. 44. 46.
YMAX	H	21.	22. 33. 35.
YMIN	H	21.	22. 33.

FORSTAT Listing of Program SLOPE2

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1.  PROGRAM SLOPE2(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT)          SL2  2
C  -----SL2  4
C  PROGRAM SLOPE2          SL2  6
C  -----SL2  8
C  PURPOSE=          SL2 10
C  TO ANALYZE A SLOPE PROFILE FOR A CIRCULAR TYPE OF FAILURE      SL2 12
C  USING THE MODIFIED BISHOP FACTOR OF SAFETY.          SL2 14
C  -----SL2 16
C  CONTROL CARDS=          SL2 18
C          SL2 20
C  ALL FORMATS ARE INTEGER OR FIXED POINT DEPENDING UPON FORTRAN  SL2 22
C  CODING OF VARIABLES, UNLESS OTHERWISE STATED.          SL2 24
C  INPUT MUST BE IN THE FOLLOWING UNITS,          SL2 26
C  LENGTH IN FEET.          SL2 28
C  FORCE IN POUNDS.          SL2 30
C  ANGLE IN DEGREES.          SL2 32
C          SL2 34
C  (A) DESCRIPTION OF PROFILE=          SL2 36
C  SEE SUBROUTINE INOUT.          SL2 38
C          SL2 40
C  (B) DESCRIPTION OF SLIP SURFACE/SEARCH=          SL2 42
C  (1) OPTION CARD          SL2 44
C  IOPT (COL 1) IF IOPT=1, INDIVIDUAL CIRCLE ANALYSIS.          SL2 46
C  IF IOPT=2, GRID ANALYSIS.          SL2 48
C  INUM (COL 2-3) NUMBER OF CIRCLES TO BE READ OR NUMBER OF      SL2 50
C  GRIDS TO BE READ DEPENDING UPON IOPT.          SL2 52
C          SL2 54
C  (2) SLIP SURFACE/SEARCH PARAMETER CARD(S)          SL2 56
C          SL2 58
C  COMPLETE EITHER 2A OR 2B DEPENDING UPON THE IOPT VALUE. THERE MUST  SL2 60
C  BE INUM TOTAL CARDS IN EITHER CASE.          SL2 62
C          SL2 64
C  (2A) INDIVIDUAL CIRCLE ANALYSIS CARD          SL2 66
C  XCEN (COL 1-10) X-CENTER OF CIRCLE.          SL2 68
C  YCEN (COL 11-20) Y-CENTER OF CIRCLE.          SL2 70
C  R (COL 21-30) RADIUS OF CIRCLE.          SL2 72
C          SL2 74
C  (2B) GRID ANALYSIS CARD          SL2 76
C  XMAX (COL 1-10) MAXIMUM X-COORD OF GRID.          SL2 78
C  XMIN (COL 11-20) MINIMUM X-COORD OF GRID.          SL2 80
C  YMAX (COL 21-30) MAXIMUM Y-COORD OF GRID.          SL2 82
C  YMIN (COL 31-40) MINIMUM Y-COORD OF GRID.          SL2 84
C  DRAD (COL 41-50) RADIUS INCREMENT VALUE.          SL2 86
C  ICOL (COL 51-52) NUMBER OF COLUMNS IN GRID.          SL2 88
C  IROW (COL 53-54) NUMBER OF ROWS IN GRID.          SL2 90
C          SL2 92
C  (C) TRANSFER OF CONTROL=          SL2 94
C  (1) CONTROL OPTION CARD          SL2 96
C  WAY (COL 1-3) IF WAY=NEW, CONTROL IS TRANSFERRED TO (A).          SL2 98
C  IF WAY=OLD, CONTROL IS TRANSFERRED TO (B).          SL2 100
C  IF WAY=END, PROGRAM IS TERMINATED.          SL2 102
C          SL2 104
C  -----SL2 106
C  REQUIRED ROUTINES=          SL2 108
C  SUBROUTINE STORE2          SL2 110
C  SUBROUTINE INOUT          SL2 112
C  SUBROUTINE CROSS          SL2 114
C  SUBROUTINE RADIUS          SL2 116
C  SUBROUTINE FACTOR          SL2 118
C  SUBROUTINE WEIGHT          SL2 120
C  FUNCTION HEAD          (CALLED BY STORE2)          SL2 122
C  (CALLED BY STORE2)
C  -----SL2 124
C  SYSTEM ROUTINES=          SL2 126
C  FUNCTION FLOAT          SL2 128
C  -----SL2 130
C  INTEGER OLD,WAY          SL2 132
C  DIMENSION RAD(15)          SL2 134
C  DATA NEW,OLD,3HNEW,3HOLD/          SL2 136
C  CALL INOUT (2)          SL2 138
C  READ (5,130) IOPT,INUM          SL2 140
C  GO TO (15,30), IOPT          SL2 142
C  -----SL2 144
C  INDIVIDUAL CIRCLE OPTION          SL2 146
C  -----SL2 148
C  15  WRITE (6,135) INUM          SL2 150
C  15  WRITE (6,140)          SL2 152

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10.      DO 25 K=1,INUM                                SL2 154
11.          READ (5,145) XCEN,YCEN,R                SL2 156
12.          ISTOP=1                                    SL2 154
13.          CALL CROSS (ISTOP,XCEN,YCEN,R)           SL2 160
14.          GO TO (20,25), ISTOP                     SL2 162
15.      20      CALL STORE2 (XCEN,YCEN,R,NSLICE)      SL2 164
16.          CALL FACTOR (NSLICE,FR)                  SL2 166
17.          WRITE (6,150) XCEN,YCEN,R,FR             SL2 168
18.      25      CONTINUE                               SL2 170
19.          GO TO 115                                  SL2 172
20.      C ----- SL2 174
21.      C ----- SL2 176
22.      C GRID OPTION SL2 178
23.      C ----- SL2 180
24.      30      WRITE (6,155) INUM                     SL2 182
25.          DO 110 K=1,INUM                             SL2 184
26.              READ (5,160) XMAX,XMIN,YMAX,YMIN,DRAD,ICOL,IROW SL2 186
27.              WRITE (6,165) XMAX,YMAX,XMIN,YMIN,ICOL,IROW,DRAD SL2 188
28.              WRITE (6,140)                             SL2 190
29.              DX=FLOAT(ICOL-1)                         SL2 192
30.              IF (DX) 35,35,40                          SL2 194
31.              DX=.0                                     SL2 196
32.              GO TO 45                                  SL2 198
33.      C ----- SL2 200
34.              40      DX=(XMAX-XMIN)/DX               SL2 202
35.              45      DY=FLOAT(IROW-1)                 SL2 204
36.              IF (DY) 50,50,55                         SL2 206
37.              DY=1.0                                    SL2 208
38.              GO TO 60                                  SL2 210
39.      C ----- SL2 212
40.              55      DY=(YMAX-YMIN)/DY               SL2 214
41.              60      DO 105 IY=1,IROW                 SL2 216
42.                  YCEN=YMAX-FLOAT(IY-1)*DY           SL2 218
43.                  DO 100 IX=1,ICOL                     SL2 220
44.                      FMIN=999999.                    SL2 222
45.                      XCEN=XMIN+FLOAT(IX-1)*DX         SL2 224
46.                      WRITE (6,170) XCEN,YCEN          SL2 226
47.                      CALL RADIUS (XCEN,YCEN,RAD,NRAD) SL2 228
48.                      DO 95 I=1,NRAD                    SL2 230
49.                          R=RAD(I)                     SL2 232
50.                          ISTOP=1                       SL2 234
51.                          CALL CROSS (ISTOP,XCEN,YCEN,R) SL2 236
52.                          GO TO (70,85), ISTOP         SL2 238
53.                      70      CALL STORE2 (XCEN,YCEN,R,NSLICE) SL2 240
54.                          CALL FACTOR (NSLICE,FR)      SL2 242
55.                          IF (FR-FMIN) 75,80,R0        SL2 244
56.                          FMIN=FR                      SL2 246
57.                          80      WRITE (6,175) R,FR   SL2 248
58.                          85      IF (I-NRAD) 90,95,95 SL2 250
59.                          R=R0                          SL2 252
60.                          IF (R-RAD(I+1)) 65,95,95    SL2 254
61.                      95      CONTINUE                  SL2 256
62.                      100     WRITE (6,185) FMIN       SL2 258
63.                      105     WRITE (6,180)           SL2 260
64.                      110     CONTINUE                  SL2 262
65.      C ----- SL2 264
66.      C DETERMINE TRANSFER OF CONTROL SL2 266
67.      C ----- SL2 268
68.      115     READ (5,190) WAY                          SL2 270
69.          IF (WAY-NEW) 120,5,120                       SL2 272
70.          120     IF (WAY-OLD) 125,10,125              SL2 274
71.          125     STOP                                   SL2 276
72.      C ----- SL2 278
73.          130     FORMAT (I1,I2)                       SL2 280
74.          135     FORMAT (I41///4X,*INDIVIDUAL CIRCLE OPTION SPECIFIED#//13X,I3,* CIRCLES TO BE ANALYZED#//) SL2 282
75.          140     FORMAT (I4 /4X,*X-CENTER#.5X,*Y-CENTER#.5X,*RADIUS#.10X,*FS#//) SL2 284
76.          145     FORMAT (3F10.4)                     SL2 288
77.          150     FORMAT (I4 6X,FR.1,5X,FR.1,4X,FR.2,F15.3) SL2 290
78.          155     FORMAT (I41///4X,*GRID OPTION SPECIFIED#//13X,I3,* GRIDS TO BE ANALYZED#//) SL2 292
79.          160     FORMAT (5F10.0,2I2)                 SL2 294
80.          165     FORMAT (I4 ///10X,*GRID SPECIFICATIONS#//12X,*XMAX #.F10.1,10X,*XMIN #.F10.1,10X,*YMAX #.F10.1,10X,*YMIN #.F10.1,10X,*ICOL #.I2,10X,*IROW #.I2,10X,*RAD #.F10.1,10X,*RADIUS INCREMENT #.F10.1/) SL2 300
81.          170     FORMAT (I4 /8X,FR.1,5X,FR.1)        SL2 304
82.          175     FORMAT (I4 32X,FR.2,F13.3)          SL2 306
83.          180     FORMAT (I4 //)                      SL2 308
84.          185     FORMAT (I4 14X,*MINIMUM FS FOR THIS CENTER = #.F10.3) SL2 310
85.          190     FORMAT (A3)                          SL2 312
86.          END                                           SL2 314

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STATEMENT NUMBER	DEFINITION	REFERENCES
5	5.	40.
10	6.	61.
15	8.	7.
20	15.	14.
25	18.	10.
30	20.	7.
35	27.	26.
40	29.	26.
45	30.	28.
50	32.	31.
55	34.	31.
60	35.	33.
65	44.	54.
70	47.	46.
75	50.	49.
80	51.	49.
85	52.	46.
90	53.	42.
95	55.	42.
100	56.	37.
105	57.	35.
110	58.	21.
115	59.	19.
120	61.	60.
125	62.	61.
130	63.	6.
135	64.	8.
140	65.	9.
145	66.	11.
150	67.	17.
155	68.	20.
160	69.	22.
165	70.	23.
170	71.	40.
175	72.	51.
180	73.	57.
185	74.	56.
190	75.	59.

LABEL	TYPE	DEFINITION	REFERENCES
CROSS	R	13.	SUBROUTINE 45.
DRAD	R	22.	23. 53.
DX	R	25.	26. 27. 29. 39.
DY	R	30.	31. 32. 34. 36.
FACTOR	R	16.	SUBROUTINE 48.
FB	R	16.	17. 48. 49. 50. 51.
FLOAT	R	25.	FUNCTION 30. 36. 39.
FMIN	R	38.	49. 50. 56.
I	I	42.	43. 52. 54.
ICOL	I	22.	23. 25. 37.
INOUT	I	5.	SUBROUTINE
INUM	I	6.	8. 10. 20. 21.
IOPT	I	6.	7.
IROW	I	22.	23. 30. 35.
ISTOP	I	12.	13. 14. 44. 45. 46.
IX	I	37.	39.
IY	I	35.	36.
K	I	10.	21.
NEW	I	4.	DATA 60.
NRAD	I	41.	42. 52.
NSLICE	I	15.	16. 47. 48.
OLD	I	2.	DATA 4. 61.
R	R	11.	13. 15. 17. 43. 45. 47. 51. 53. 54.
RAD	R	3.	41. 43. 54.
RADIUS	R	41.	SUBROUTINE
STOR=2	R	15.	SUBROUTINE
WAY	I	2.	47. 59. 60. 61.
XCEN	R	11.	13. 15. 17. 39. 40. 41. 45. 47.
XMAX	R	22.	23. 29.
XMIN	R	22.	23. 29. 39.
YCEN	R	11.	13. 15. 17. 36. 40. 41. 45. 47.
YMAX	R	22.	23. 34. 36.
YMIN	R	22.	23. 34.

FORSTAT Listing of Program SLOPE3

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1.      PROGRAM SLOPE3(INPUT,OUTPUT,TAP5=INPUT,TAP6=OUTPUT)          SL3   2
C      -----SL3   4
C                      PROGRAM SLOPE3          SL3   6
C      -----SL3   8
C      PURPOSE-          SL3  10
C      TO ANALYZE A SLOPE PROFILE FOR A CIRCULAR TYPE OF FAILURE    SL3  12
C      USING AN ADJUSTED FORM OF THE MODIFIED BISHOP FACTOR OF SAFETY. SL3  14
C      -----SL3  16
C      CONTROL CARDS-      SL3  18
C                      SL3  20
C      ALL FORMATS ARE INTEGER OR FIXED POINT DEPENDING UPON FORTRAN SL3  22
C      CODING OF VARIABLES, UNLESS OTHERWISE STATED.              SL3  24
C      INPUT MUST BE IN THE FOLLOWING UNITS.                        SL3  26
C          LENGTH IN FEET.          SL3  28
C          FORCE IN POUNDS.          SL3  30
C          ANGLE IN DEGREES.        SL3  32
C                      SL3  34
C      (A) DESCRIPTION OF PROFILE-      SL3  36
C          SEE SUBROUTINE INOUT.        SL3  38
C                      SL3  40
C      (B) DESCRIPTION OF SLIP SURFACE/SEARCH-      SL3  42
C          (1) OPTION CARD          SL3  44
C              IOPT (COL 1) IF IOPT=1, INDIVIDUAL CIRCLE ANALYSIS. SL3  46
C                      IF IOPT=2, GRID ANALYSIS.          SL3  48
C              INUM (COL 2-3) NUMBER OF CIRCLES TO BE READ OR NUMBER OF SL3  50
C                      GRIDS TO BE READ DEPENDING UPON IOPT. SL3  52
C                      SL3  54
C          (2) SLIP SURFACE/SEARCH PARAMETER CARD(S)      SL3  56
C                      SL3  58
C      COMPLETE EITHER 2A OR 2B DEPENDING UPON THE IOPT VALUE. THERE MUST SL3  60
C      BE INUM TOTAL CARDS IN EITHER CASE.                SL3  62
C                      SL3  64
C          (2A) INDIVIDUAL CIRCLE ANALYSIS CARD          SL3  66
C              XCEN (COL 1-10) X-CENTER OF CIRCLE.          SL3  68
C              YCEN (COL 11-20) Y-CENTER OF CIRCLE.          SL3  70
C              R (COL 21-30) RADIUS OF CIRCLE.              SL3  72
C                      SL3  74
C          (2B) GRID ANALYSIS CARD          SL3  76
C              XMAX (COL 1-10) MAXIMUM X-COORD OF GRID.      SL3  78
C              XMIN (COL 11-20) MINIMUM X-COORD OF GRID.      SL3  80
C              YMAX (COL 21-30) MAXIMUM Y-COORD OF GRID.      SL3  82
C              YMIN (COL 31-40) MINIMUM Y-COORD OF GRID.      SL3  84
C              DRAD (COL 41-50) RADIUS INCREMENT VALUE.      SL3  86
C              ICOL (COL 51-52) NUMBER OF COLUMNS IN GRID.   SL3  88
C              IROW (COL 53-54) NUMBER OF ROWS IN GRID.       SL3  90
C                      SL3  92
C      (C) TRANSFER OF CONTROL-      SL3  94
C          (1) CONTROL OPTION CARD          SL3  96
C              WAY (COL 1-3) IF WAY=NEW, CONTROL IS TRANSFERRED TO (A). SL3  98
C                      IF WAY=OLD, CONTROL IS TRANSFERRED TO (B). SL3 100
C                      IF WAY=END, PROGRAM IS TERMINATED.      SL3 102
C                      SL3 104
C      -----SL3 106
C      REQUIRED ROUTINES-      SL3 108
C          SUBROUTINE STORE3          SL3 110
C          SUBROUTINE INOUT          SL3 112
C          SUBROUTINE CROSS          SL3 114
C          SUBROUTINE RADIUS          SL3 116
C          SUBROUTINE FACTOR          SL3 118
C          SUBROUTINE WEIGHT          (CALLED BY STORE3)      SL3 120
C          FUNCTION HEAD              (CALLED BY STORE3)      SL3 122
C      -----SL3 124
C      SYSTEM ROUTINES-      SL3 126
C          FUNCTION FLOAT          SL3 128
C      -----SL3 130
C          INTEGER OLD,WAY          SL3 132
C          DIMENSION RAD(15)        SL3 134
C          DATA NEW,OLD,3HNEW,3HOLD/ SL3 136
C          CALL INOUT (3)            SL3 138
C          READ (5,136) IOPT,INUM    SL3 140
C          GO TO (15,30), IOPT       SL3 142
C      -----SL3 144
C      INDIVIDUAL CIRCLE OPTION      SL3 146
C      -----SL3 148
C          WRITE (6,135) INUM        SL3 150
C          WRITE (6,140)              SL3 152

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10.      DO 25 K=1,INUM                                SL3 154
11.          READ (5,145) XCEN,YCEN,H                  SL3 156
12.          ISTOP=1                                     SL3 158
13.          CALL CROSS (ISTOP,XCEN,YCEN,R)             SL3 160
14.          GO TO (20,25), ISTOP                       SL3 162
15.      20      CALL STORE3 (XCEN,YCEN,H,NSLICE)        SL3 164
16.          CALL FACTOR (NSLICE,FMYB)                  SL3 166
17.          WRITE (6,150) XCEN,YCEN,R,FMYB            SL3 168
18.      25      CONTINUE                                SL3 170
19.          GO TO 115                                   SL3 172
20.      C                                              SL3 174
21.      C -----                                SL3 176
22.      C GRID OPTION                                SL3 178
23.      C -----                                SL3 180
24.      30      WRITE (6,155) INUM                      SL3 182
25.          DO 110 K=1,INUM                             SL3 184
26.              READ (5,160) XMAX,XMIN,YMAX,YMIN,DRAD,ICOL,IROW SL3 186
27.              WRITE (6,165) XMAX,YMAX,XMIN,YMIN,ICOL,IROW,DRAD SL3 188
28.              WRITE (6,140)                             SL3 190
29.              DX=FLOAT(ICOL-1)                         SL3 192
30.              IF (DX) 35,35,40                         SL3 194
31.              DX=1.0                                    SL3 196
32.      35      GO TO 45                                  SL3 198
33.      C                                              SL3 200
34.      40      DX=(XMAX-XMIN)/DX                       SL3 202
35.      45      DY=FLOAT(IROW-1)                         SL3 204
36.              IF (DY) 50,50,55                         SL3 206
37.              DY=1.0                                    SL3 208
38.      50      GO TO 60                                  SL3 210
39.      C                                              SL3 212
40.      55      DY=(YMAX-YMIN)/DY                       SL3 214
41.      60      DO 105 IY=1,IROW                         SL3 216
42.          YCEN=YMAX-FLOAT(IY-1)*DY                   SL3 218
43.          DO 100 IX=1,ICOL                             SL3 220
44.              FMIN=999999.                             SL3 222
45.              XCEN=XMIN-FLOAT(IX-1)*DX                 SL3 224
46.              WRITE (6,170) XCEN,YCEN                 SL3 226
47.              CALL RADIUS (XCEN,YCEN,RAD,NRAD)         SL3 228
48.              DO 95 I=1,NRAD                           SL3 230
49.                  R=RAD(I)                             SL3 232
50.      65      ISTOP=1                                   SL3 234
51.              CALL CROSS (ISTOP,XCEN,YCEN,R)           SL3 236
52.              GO TO (70,85), ISTOP                     SL3 238
53.      70      CALL STORE3 (XCEN,YCEN,R,NSLICE)         SL3 240
54.              CALL FACTOR (NSLICE,FMYB)                SL3 242
55.              IF (FMYB=FMIN) 75,80,80                  SL3 244
56.              FMIN=FMYB                                 SL3 246
57.      80      WRITE (6,175) R,FMYB                     SL3 248
58.      85      IF (I=NRAD) 90,95,95                     SL3 250
59.      90      R=R*UNRAD                                  SL3 252
60.              IF (R=NRAD(I+1)) 65,95,95               SL3 254
61.      95      CONTINUE                                  SL3 256
62.      100     WRITE (6,190) FMIN                        SL3 258
63.      105     WRITE (6,180)                             SL3 260
64.      110     CONTINUE                                  SL3 262
65.      C -----                                SL3 264
66.      C DETERMINE TRANSFER OF CONTROL                 SL3 266
67.      C -----                                SL3 268
68.      115     READ (5,185) WAY                          SL3 270
69.      120     IF (WAY=NEW) 120,5,120                   SL3 272
70.      125     IF (WAY=OLD) 125,10,125                  SL3 274
71.      130     STOP                                       SL3 276
72.      C                                              SL3 278
73.      135     FORMAT (I1,I2)                            SL3 280
74.      140     FORMAT (I1,///4X, #INDIVIDUAL CIRCLE OPTION SPECIFIED#//13X,I3, # CIRS SL3 282
75.              ICLES TO BE ANALYZED#//)                SL3 284
76.      145     FORMAT (I1, /8X, #X-CENTER#//5X, #Y-CENTER#//5X, #RADIUS#//10X, #FS#//) SL3 286
77.      150     FORMAT (3F10.4)                          SL3 288
78.      155     FORMAT (I1, 6X, F8.1, 5X, F8.1, 4X, F8.2, F15.3) SL3 290
79.      160     FORMAT (I1,///4X, #GRID OPTION SPECIFIED#//13X,I3, # OHIDS TO BE ANAL SL3 292
80.              IYZ#//)                                  SL3 294
81.      165     FORMAT (5F10.0,2I2)                      SL3 296
82.      170     FORMAT (I1, ///10X, #GRID SPECIFICATIONS#//12X, #XMAX ##F10.1, 10X, #SL3 298
83.              IYMAX ##F10.1/12X, #XMIN ##F10.1, 10X, #YMIN ##F10.1/12X, #ICOL ##I SL3 300
84.              210, 10X, #IROW ##I10//12X, #RADIUS INCREMENT ##F10.1//) SL3 302
85.      175     FORMAT (I1, /8X, F8.1, 5X, F8.1)         SL3 304
86.      180     FORMAT (I1, 32X, F8.2, F13.3)            SL3 306
87.      185     FORMAT (I1, //)                          SL3 308
88.      190     FORMAT (A3)                               SL3 310
89.      195     FORMAT (I1, 14X, #MINIMUM FS FOR THIS CENTER = #F10.3) SL3 312
90.      200     ENP                                       SL3 314

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STATEMENT NUMBER	DEFINITION	REFERENCES
5	5.	60.
10	6.	61.
15	8.	7.
20	15.	14.
25	18.	10. 14.
30	20.	7.
35	27.	26.
40	29.	26.
45	30.	28.
50	32.	31.
55	34.	31.
60	35.	33.
65	44.	54.
70	47.	46.
75	40.	49.
80	51.	49.
85	52.	46.
90	53.	52.
95	55.	42. 52. 54.
100	56.	37.
105	57.	35.
110	58.	21.
115	59.	19.
120	61.	60.
125	62.	61.
130	63. FORMAT	6.
135	64. FORMAT	8.
140	65. FORMAT	9. 24.
145	66. FORMAT	11.
150	67. FORMAT	17.
155	68. FORMAT	20.
160	69. FORMAT	22.
165	70. FORMAT	23.
170	71. FORMAT	40.
175	72. FORMAT	51.
180	73. FORMAT	57.
185	74. FORMAT	59.
190	75. FORMAT	56.

LABEL	TYPE	DEFINITION	REFERENCES
CROSS	R	13. SUBROUTINE	45.
DRAD	R	22.	23. 53.
DX	R	25.	26. 27. 29. 39.
UY	R	30.	31. 32. 34. 36.
FACTOR	R	16. SUBROUTINE	48.
FLOAT	R	25. FUNCTION	30. 36. 39.
FMIN	R	38.	49. 50. 56.
FMYB	R	16.	17. 40. 49. 50. 51.
I	I	42.	43. 52. 54.
ICOL	I	22.	23. 25. 37.
INOUT	I	5. SUBROUTINE	
INUM	I	6.	8. 10. 20. 21.
IOPT	I	6.	7.
IROW	I	22.	23. 30. 35.
ISTOP	I	12.	13. 14. 44. 45. 46.
IX	I	37.	39.
IY	I	18.	36.
K	I	10.	21.
NEW	I	4. DATA	60.
NRAD	I	41.	42. 52.
NSLICE	I	15.	16. 47. 48.
OLD	I	2. DATA	4. 61.
W	R	11. D	13. 15. 17. 43. 45. 47. 51. 53. 54.
RAD	R	3.	41. 43. 54.
RADIUS	R	41. SUBROUTINE	
STORE3	R	15. SUBROUTINE	47.
WAY	I	2.	59. 60. 61.
XCEN	R	11.	13. 15. 17. 39. 40. 41. 45. 47.
XMAX	R	22.	23. 29.
XMIN	R	22.	23. 29. 39.
YCEN	R	11.	13. 15. 17. 36. 40. 41. 45. 47.
YMAX	R	22.	23. 34. 36.
YMIN	R	22.	23. 34.

FORSTAT Listing of Program SLOPE4

1.	PROGRAM SLOPE4 (INPUT, OUTPUT, TAPF3=INPUT, TAPF4=OUTPUT)	SL4	2
C	-----	SL4	4
C	PROGRAM SLOPE4	SL4	6
C	-----	SL4	8
C	PURPOSE-	SL4	10
C	TO ANALYZE A SLOPE PROFILE FOR AN IRREGULAR TYPE OF FAILURE	SL4	12
C	SURFACE USING AN ADJUSTED FORM OF THE MODIFIED BISHOP FACTOR OF	SL4	14
C	SAFETY.	SL4	16
C	-----	SL4	18
C	CONTROL CARDS-	SL4	20
C	-----	SL4	22
C	ALL FORMATS ARE INTEGER OR FIXED POINT DEPENDING UPON FORTRAN	SL4	24
C	CODING OF VARIABLES.	SL4	26
C	INPUT MUST BE IN THE FOLLOWING UNITS.	SL4	28
C	LENGTH IN FEET.	SL4	30
C	FORCE IN POUNDS.	SL4	32
C	ANGLE IN DEGREES.	SL4	34
C	-----	SL4	36
C	(A) DESCRIPTION OF PROFILE-	SL4	38
C	SEE SUBROUTINE INOUT.	SL4	40
C	-----	SL4	42
C	(B) DESCRIPTION OF SLIP SURFACE/SEARCH-	SL4	44
C	(1) OPTION CARD	SL4	46
C	IOPT (COL 1) IF IOPT=1, INDIVIDUAL IRREGULAR SURFACE	SL4	48
C	ANALYSIS.	SL4	50
C	IF IOPT=2, IRREGULAR SURFACE SEARCH ANALYSIS.	SL4	52
C	INUM (COL 2-3) NUMBER OF SURFACES TO BE READ OR NUMBER OF	SL4	54
C	SEARCH PARAMETERS TO BE READ DEPENDING	SL4	56
C	UPON IOPT.	SL4	58
C	-----	SL4	60
C	(2) SLIP SURFACE/SEARCH PARAMETER CARD(S)	SL4	62
C	-----	SL4	64
C	COMPLETE EITHER 2A OR 2B DEPENDING UPON THE IOPT VALUE, BUT IN	SL4	66
C	EITHER CASE ENTER INUM TIMES.	SL4	68
C	-----	SL4	70
C	(2A) INDIVIDUAL SURFACE ANALYSIS CARDS	SL4	72
C	(1) PARAMETER CARD	SL4	74
C	NPTS (COL 1-2) NUMBER OF POINTS DEFINING SLIP	SL4	76
C	SURFACE.	SL4	78
C	(2) COORDINATE CARD(S)	SL4	80
C	ENTER COORDINATES FROM LEFT TO RIGHT.	SL4	82
C	X(I) (COL 1-10) X-COORD OF POINT.	SL4	84
C	Y(I) (COL 11-20) Y-COORD OF POINT.	SL4	86
C	REPEAT, FILLING ALL 80 COLUMNS OF CARD.	SL4	88
C	-----	SL4	90
C	(2B) IRREGULAR SEARCH CARD	SL4	92
C	(1) SEARCH PARAMETER CARD	SL4	94
C	YMAX (COL 1-10) MAXIMUM Y-COORD OF IMAGINARY	SL4	96
C	LAYERING.	SL4	98
C	YMIN (COL 11-20) MINIMUM Y-COORD OF IMAGINARY	SL4	100
C	LAYERING.	SL4	102
C	XMAX (COL 21-30) MAXIMUM ALLOWABLE X-COORD OF	SL4	104
C	EXIT POINT.	SL4	106
C	XMIN (COL 31-40) MINIMUM ALLOWABLE X-COORD OF	SL4	108
C	EXIT POINT.	SL4	110
C	XCONTROL (COL 41-50) CONTROL POINT FOR SEARCH.	SL4	112
C	NMIN (COL 51) MINIMUM NUMBER OF IMAGINARY	SL4	114
C	LAYERS.	SL4	116
C	NMAX (COL 52-53) MAXIMUM NUMBER OF IMAGINARY	SL4	118
C	LAYERS.	SL4	120
C	NSUR (COL 54-55) NUMBER OF SURFACES TO BE	SL4	122
C	ANALYZED IN THE RANGE XMAX TO	SL4	124
C	XMIN. (MUST BE .GE. 2)	SL4	126
C	-----	SL4	128
C	(C) TRANSFER OF CONTROL-	SL4	130
C	(1) CONTROL OPTION CARD	SL4	132
C	WAY (COL 1-3) IF WAY=NEW, CONTROL IS TRANSFERRED TO (A).	SL4	134
C	IF WAY=OLD, CONTROL IS TRANSFERRED TO (B).	SL4	136
C	IF WAY=END, PROGRAM IS TERMINATED.	SL4	138
C	-----	SL4	140
C	SUPPORTING ROUTINES-	SL4	142
C	SUBROUTINE STORF4	SL4	144
C	SUBROUTINE INOUT	SL4	146
C	SUBROUTINE SLPBND	SL4	148
C	-----	SL4	150

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C      SUBROUTINE FACTOR                                SL4 152
C      SUBROUTINE WEIGHT      (CALLED BY STORE4)        SL4 154
C      FUNCTION HEAD      (CALLED BY STORE4)            SL4 156
C      -----SL4 158
C      SYSTEM ROUTINES-                                SL4 160
C      FUNCTION COS                                SL4 162
C      FUNCTION ABS                                SL4 164
C      FUNCTION FLOAT                                SL4 166
C      -----SL4 168
C      NOTE-                                           SL4 170
C      IN ORDER TO ACCOUNT FOR MACHINE ROUNDING, A DIFFERENCE BETWEEN SL4 172
C      TWO VARIABLES OF LESS THAN 10.E-4 IS TAKEN AS EQUAL TO ZERO. THIS SL4 174
C      VALUE IS DEFINED IN THE DATA STATEMENT.        SL4 176
C      -----SL4 178
2.      INTEGER OLD.WAY                                SL4 180
3.      DIMENSION SERIES(10), R(3), BETA(3)            SL4 182
4.      COMMON DUM(23),XTOP,DUM2(2),IDUM1,NTOP,IDUM2(19),RND(20,4) SL4 184
5.      COMMON EQ(20,2),DUM3(312),X(12),Y(12),SEQ(11,2) SL4 186
6.      DATA (R(1),BETA(1),I=1,3)/30.,.5/735,45.,.1,60.,.1,7321/ SL4 188
7.      DATA (SERIES(I),I=1,10)/1.,2.,3.,4.,8.,13.,21.,34.,55.,89./ SL4 190
8.      DATA PI2,P1180,ZERO,NEW,OLD/1.570796,0.017453,10.E-4,3HNEW,3HOLD/ SL4 192
9.      EQUIVALENCE (X(2),XCONT), (Y(2),YMIN)          SL4 194
10.     CALL INOUT(3)                                  SL4 196
11.     10 HEAD (5,205) IOPT,INUM                      SL4 198
12.     GO TO (15,20), IOPT                             SL4 200
C      -----SL4 202
C      INDIVIDUAL SURFACE OPTION                      SL4 204
C      -----SL4 206
13.     15 WRITE (6,210) INUM                          SL4 208
14.     WRITE (6,215)                                  SL4 210
15.     DO 25 K=1,INUM                                  SL4 212
16.     READ (5,220) NLINES                            SL4 214
17.     HEAD (5,225) (X(I),Y(I),I=1,NLINES)           SL4 216
18.     DO 20 I=2,NLINES                                SL4 218
19.     SEQ(I-1,1)=(Y(I)-Y(I-1))/(X(I)-X(I-1))         SL4 220
20.     20 SEQ(I-1,2)=Y(I)-SEQ(I-1,1)*X(I)             SL4 222
21.     CALL SLDRND (2,NLINES)                          SL4 224
22.     CALL STORE4 (NS1ICE,2,NLINES)                  SL4 226
23.     CALL FACTOR (NS1ICE,FMYR)                      SL4 228
24.     25 WRITE (6,230) FMYR,(X(I),Y(I),I=1,NLINES) SL4 230
25.     GO TO 190                                       SL4 232
C      -----SL4 234
C      -----SL4 236
C      IRREGULAR SURFACE SEARCH OPTION               SL4 238
C      -----SL4 240
26.     30 WRITE (6,235) INUM                          SL4 242
27.     DO 185 KNUM=1,INUM                             SL4 244
28.     READ (5,240) YMAX,YMIN,XMAX,XMIN,XCONT,NMIN,NMAX,NSUR SL4 246
29.     WRITE (6,245) XMIN,YMIN,NSUR,XMAX,YMAX,XCONT,NMIN,NMAX SL4 248
30.     DX=(XMAX-XMIN)/FLOAT(NSUR-1)                  SL4 250
31.     MM=1                                             SL4 252
32.     ILOW=2                                           SL4 254
33.     DO 40 I=1,NTOP                                  SL4 256
34.     IF (XCONT-RND(1,1)) 40,35,35                   SL4 258
35.     35 IF (XCONT-RND(1,3)) 45,40,40                 SL4 260
36.     40 CONTINUE                                     SL4 262
37.     STOP                                             SL4 264
38.     45 YI=EQ(I,1)*XCONT+EQ(I,2)                   SL4 266
39.     IF (YI-YMIN-ZERO) 55,50,50                     SL4 268
40.     50 ILOW=1                                       SL4 270
41.     MM=3                                             SL4 272
C      -----SL4 274
C      VARY THE NUMBER OF IMAGINARY LAYERS          SL4 276
C      -----SL4 278
42.     55 DO 100 NM=NMIN,NMAX                         SL4 280
43.     WRITE (6,250) NL                                SL4 282
44.     GO TO (40,65), ILOW                             SL4 284
45.     40 WRITE (6,255)                                SL4 286
46.     GO TO 10                                         SL4 288
C      -----SL4 290
47.     65 WRITE (6,260)                                SL4 292
48.     70 NL=NL+2                                       SL4 294
49.     NM=NMAX-YMIN                                    SL4 296
C      -----SL4 298
C      DETERMINE Y COORDS. OF SLIP SURFACE          SL4 300
C      -----SL4 302
50.     SUMM=0.0                                         SL4 304
51.     DO 75 I=3,NL1                                   SL4 306
52.     Y(I)=H*(1.-COS(FLOAT(I-2)*PI2/FLOAT(NL1)))+YMIN SL4 308
53.     75 SUMM=SUMM+(Y(I)-Y(I-1))/SERIES(I-2)         SL4 310

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C -----
C VARY THE INITIAL ANGLE
C -----
54.      XNEW=XMAX
55.      GO TO 85
56.      C
57.      80      XNEW=XNEW-0X
      85      ANG=SIMM/(XNEW-XCONY)
C -----
C DETERMINE THE X COORDS. OF SLIP SURFACE
C -----
58.      DO 90 J=3,NJ 1
59.      X(J)=X(J-1)+(Y(J)-Y(J-1))/(ANG*SERIES(J-2))
60.      SEQ(J-1,1)=(Y(J)-Y(J-1))/(X(J)-X(J-1))
61.      SEQ(J-1,2)=Y(J)-SEQ(J-1,1)*X(J)
C -----
C FIT SLIP SURFACE TO PROFILE
C -----
62.      DO 120 JJ=1,NL
63.      JJ=NJ+3
64.      DO 115 LL=1,NTOP
65.      L=NTOP-LL+1
66.      IF (XTOP-BNDS(L,1)) 95,95,120
67.      95      TEMP=FQ(L,1)-SEQ(J-1,1)
68.      IF (ABS(TEMP)-ZERO) 115,115,100
69.      100      XI=(SEQ(J-1,2)-FQ(L,2))/TEMP
70.      IF (XI-X(J-1)) 115,105,105
71.      105      IF (XI-BNDS(L,1)) 115,110,110
72.      110      IF (XI-BNDS(L,3)) 125,125,80
73.      115      CONTINUE
74.      120      CONTINUE
75.      GO TO 140
C -----
76.      125      NLT=J
77.      IF (XI-XMIN+ZERO) 140,135,130
78.      IF (XI-XMAX-ZERO) 135,135,80
79.      135      X(NLT)=XI
80.      Y(NLT)=XI*EQ(L,1)+FQ(L,2)
81.      SEQ(NLT-1,1)=(Y(NLT)-Y(NLT-1))/(X(NLT)-X(NLT-1))
82.      SEQ(NLT-1,2)=Y(NLT)-SEQ(NLT-1,1)*X(NLT)
83.      DO 170 J=1,MM
84.      GO TO (140,150), ILOW
85.      140      H=BETA(J)*XCUNT+YMIN
86.      DO 150 L=1,NTOP
87.      XI=(H-FQ(L,2))/(FQ(L,1)+BETA(J))
88.      IF (XI-BNDS(L,1)) 150,145,145
89.      145      IF (XI-BNDS(L,3)) 155,155,150
90.      150      CONTINUE
91.      GO TO 170
C -----
92.      155      X(1)=XI
93.      Y(1)=XI*EQ(L,1)+EQ(L,2)
94.      SEQ(1,1)=(Y(2)-Y(1))/(X(2)-X(1))
95.      SEQ(1,2)=Y(1)-X(1)*SEQ(1,1)
C -----
C CALCULATE FACTOR OF SAFETY FOR CURRENT SURFACE
C -----
96.      160      CALL SLPBND (ILOW+1,NLT)
97.      CALL STORF4 (NSLICE,ILOW+1,NLT)
98.      CALL FACTOR (NSLICE,FMYB)
99.      GO TO (165,175), ILOW
100.      165      WRITE (6,265) XNEW,R(J),FMYB,(X(I),Y(I),I=ILOW,NLT)
101.      170      CONTINUE
102.      WRITE (6,270)
103.      GO TO 80
C -----
104.      175      WRITE (6,275) XNEW,FMYB,(X(I),Y(I),I=ILOW,NLT)
105.      GO TO 80
C -----
106.      180      WRITE (6,270)
107.      WRITE (6,280)
108.      185      CONTINUE

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C -----
C DETERMINE TRANSFER OF CONTROL
C -----
109. 190 READ (5,485) WAY
110. IF (WAY=NEW) 195,5,195
111. 195 IF (WAY=OLD) 200,10,200
112. 200 STOP
C
113. 205 FORMAT (I1,I2)
114. 210 FORMAT (1H1//4X,#INDIVIDUAL IRREGULAR SURFACE OPTION SPECIFIED#/13SL4 474
1X,I3,# SURFACES TO BE ANALYZED#)
115. 215 FORMAT (1H ///5X,#FS#.#X#.#(X(1),Y(1))....#/)
116. 220 FORMAT (I2)
117. 225 FORMAT (8F10,0)
118. 230 FORMAT (1H F8.3,5X,4(F8.2,2X,F8.2,5X)/14X,4(F8.2,2X,F8.2,5X)/14X,3SL4 476
1(F8.2,2X,F8.2,5X))
119. 235 FORMAT (1H1//4X,#SEARCH IRREGULAR SURFACE OPTION SPECIFIED#/13X,I3SL4 478
1,# SEARCHES TO BE ANALYZED#)
120. 240 FORMAT (5F10,0,I1,2I2)
121. 245 FORMAT (1H ///10X,#SEARCH SPECIFICATIONS#//12X,#XMIN =#,F10.1,10XSL4 480
1,#YMIN =#,F10.1/12X,#NSUR =#,I10/12X,#XMAX =#,F10.1,10X,#YMAX =#,FSL4 482
2I0,1//12X,#X-CONTROL =#,F10.1//12X,#NMIN =#,I10/12X,#NMAX =#,I10)
122. 250 FORMAT (1H ///2X,#NLAYER =#,I3/)
123. 255 FORMAT (1H 1X,#X-EXIT#.#X#.#R#.#X#.#FS#.#X#.#(X(1),Y(1))....#/)
124. 260 FORMAT (1H 1X,#X-EXIT#.#X#.#FS#.#X#.#(X(1),Y(1))....#/)
125. 265 FORMAT (1H F8.2,F#.#,F7.3,5X,4(5X,2F10.2)/25X,4(5X,2F10.2)/25X,4SL4 484
1X,2F10.2))
126. 270 FORMAT (1H )
127. 275 FORMAT (1H F8.2,F7.3,5X,4(5X,2F10.2)/21X,4(5X,2F10.2)/21X,4(5X,2F1SL4 486
10.2))
128. 280 FORMAT (1H ///)
129. 285 FORMAT (A3)
130. END

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STATEMENT NUMBER	DEFINITION	REFERENCES
5	10.	110.
10	11.	111.
15	13.	12.
20	20.	18.
25	24.	15.
30	26.	12.
35	35.	34.
40	36.	33. 34. 35.
45	38.	35.
50	40.	39.
55	42.	39.
60	45.	44.
65	47.	44.
70	48.	46.
75	53.	51.
80	56.	72. 78. 103. 105.
85	57.	55.
90	61.	58.
95	67.	66.
100	69.	68.
105	71.	70.
110	72.	71.
115	73.	64. 68. 70. 71.
120	74.	62. 66.
125	76.	72.
130	78.	77.
135	79.	77. 78.
140	85.	84.
145	89.	88.
150	90.	86. 88. 89.
155	92.	89.
160	96.	84.
165	100.	99.
170	101.	83. 91.
175	104.	99.
180	106.	42. 75. 77.
185	108.	27.
190	109.	25.
195	111.	110.
200	112.	111.
205	113. FORMAT	11.
210	114. FORMAT	13.
215	115. FORMAT	14.
220	116. FORMAT	16.
225	117. FORMAT	17.
230	118. FORMAT	24.
235	119. FORMAT	26.
240	120. FORMAT	28.
245	121. FORMAT	29.
250	122. FORMAT	43.
255	123. FORMAT	45.
260	124. FORMAT	47.
265	125. FORMAT	100.
270	126. FORMAT	102. 106.
275	127. FORMAT	104.
280	128. FORMAT	107.
285	129. FORMAT	109.

LABEL	TYPE	DEFINITION	REFERENCES
ABS	R	44. FUNCTION	
ANG	R	47. FUNCTION	54.
B	R	3. D DATA	6. 100.
BETA	R	3. D DATA	6. 85. 97.
BNDP	R	4. CD	34. 35. 66. 71. 72. 89. 89.
COS	R	47. FUNCTION	
DUM1	R	4. CD	
DUM2	R	4. CD	
DUM3	R	5. CD	
DX	R	30.	56.
EQ	R	5. CD	38. 47. 49. 80. 87. 93.
FACTOR	R	23. SUBROUTINE	48. 52.
FLOAT	R	30. FUNCTION	24. 98. 100. 104.
FMVA	R	23.	
FR	R	120.	
H	R	49.	52. 85. 87.
I	I	6. DATA	7. 17. 18. 19. 20. 24. 33.
			34. 35. 38. 51. 52. 53. 100.
			104.
IDUM1	I	4. C	
IDUM2	I	4. CD	
ILOW	I	32.	40. 44. 84. 95. 97. 98. 100.
			104.
INOUT	I	10. SUBROUTINE	
INUM	I	11.	13. 15. 26. 27.
IOPT	I	11.	12.
J	I	58.	59. 60. 61. 63. 67. 69. 70.
			76. 83. 85. 87. 100.
JJ	I	42.	63.
K	I	15.	63.
KNUM	I	27.	63.
L	I	65.	66. 67. 69. 71. 72. 80. 86.
			87. 88. 94. 97.
LL	I	64.	65.
MM	I	71.	41. 83.
NEW	I	8. DATA	110.
NL	I	42.	43. 48. 52. 62. 63.
NLINES	I	16.	17. 18. 21. 22. 24.
NLT	I	76.	19. 80. 81. 82. 96. 97. 100.
			104.
NLI	I	48.	51. 58.
NMAX	I	28.	29. 42.
NMTN	I	28.	29. 42.
NSLICE	I	22.	23. 97. 98.
NSUR	I	28.	29. 30.
NTOP	I	4. C	33. 44. 65. 86.
OLD	I	2. DATA	2. 111.
P1190	R	8. DATA	
P12	R	8. DATA	
SEC	R	5. CD	52. 19. 20. 60. 61. 67. 69. 81.
			82. 94. 95.
SERIES	R	3. D DATA	7. 53. 59.
SLEPNO	R	21. SUBROUTINE	46.
STOFF4	R	22. SUBROUTINE	47.
SUMM	R	50.	53. 57.
TEMP	R	47.	58. 69.
WAY	I	2.	109. 110. 111.
X	R	5. COE	9. 17. 19. 20. 24. 59. 60.
			61. 70. 70. 81. 82. 92. 94.
			95. 100. 104.
XCONT	R	9. E	28. 29. 34. 35. 38. 57. 85.
XI	R	69.	10. 71. 72. 77. 78. 79. 80.
			87. 88. 90. 92. 93.
XMAX	R	28.	29. 30. 54. 78.
XMTN	R	28.	29. 30. 77.
XNEW	R	54.	56. 57. 100. 104.
XTOL	R	4. C	56.
Y	R	5. COE	9. 17. 19. 20. 24. 52. 53.
			59. 60. 61. 80. 81. 82. 93.
			94. 95. 100. 104.
YIT	R	38.	39.
YMAX	R	24.	28. 49.
YMTN	R	9. E	28. 29. 39. 49. 52. 85.
ZFBI	R	8. DATA	39. 68. 77. 78.

FORSTAT Listing of Program FLWNET

```

1.      PROGRAM FLWNET(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT)      FNT 2
C      -----FNT 4
C      PROGRAM FLWNET      FNT 6
C      -----FNT 8
C      PURPOSE-      FNT 10
C      TO APPROXIMATE A FLOWNET WITH A 5TH ORDER POLYNOMIAL.      FNT 12
C      -----FNT 14
C      CONTROL CARDS-      FNT 16
C      (1) PARAMETER CARD      FNT 18
C      NTOT (COL 1-3) TOTAL NUMBER OF POINTS TO BE READ.      FNT 20
C      -----FNT 22
C      (2) DATA CARDS      FNT 24
C      THIS SET INCLUDES ONE CARD/COORDINATE POINT.      FNT 26
C      X(I) (COL 1-10) X-COORD OF POINT      FNT 30
C      Y(I) (COL 11-20) Y-COORD OF POINT      FNT 32
C      Z(I) (COL 21-30) TOTAL HEAD      FNT 34
C      -----FNT 36
C      SUPPORTING ROUTINES-      FNT 38
C      FUNCTION HEAD      FNT 40
C      -----FNT 42
C      SYSTEM ROUTINES-      FNT 44
C      FUNCTION ABS      FNT 46
C      FUNCTION SQRT      FNT 48
C      FUNCTION FLOAT      FNT 50
C      -----FNT 52
C      NOTE-      FNT 54
C      THIS PROGRAM IS A MODIFICATION FROM #GCARS# BY A.K.TURNER.      FNT 56
C      -----FNT 58
2.      DIMENSION XINV(21,21), AM(21,22), PAR(21), BB(21), N(21)      FNT 60
3.      DIMENSION X(100), Y(100), Z(100)      FNT 62
4.      COMMON A(21)      FNT 64
5.      EQUIVALENCE (A,PAR)      FNT 66
6.      SSZ=0.0      FNT 68
7.      ZSUM=0.0      FNT 70
8.      PAR(1)=1.0      FNT 72
9.      DO 10 I=1,21      FNT 74
10.         DO 5 J=1,21      FNT 76
11.            AM(I,J)=0.0      FNT 78
12.            N(I)=0      FNT 80
13.            BB(I)=0.0      FNT 82
C      -----FNT 84
C      READ DATA      FNT 86
C      -----FNT 88
14.      READ (5,190) NTOT      FNT 90
15.      DO 25 L=1,NTOT      FNT 92
16.         READ (5,165) X(L),Y(L),Z(L)      FNT 94
17.         PAR(2)*X(L)      FNT 96
18.         PAR(3)*Y(L)      FNT 98
19.         PAR(4)*X(L)*X(L)      FNT 100
20.         PAR(5)*X(L)*Y(L)      FNT 102
21.         PAR(6)*Y(L)*Y(L)      FNT 104
22.         PAR(7)*PAR(4)*X(L)      FNT 106
23.         PAR(8)*PAR(4)*Y(L)      FNT 108
24.         PAR(9)*PAR(6)*X(L)      FNT 110
25.         PAR(10)*PAR(6)*Y(L)      FNT 112
26.         PAR(11)*PAR(7)*X(L)      FNT 114
27.         PAR(12)*PAR(7)*Y(L)      FNT 116
28.         PAR(13)*PAR(4)*PAR(6)      FNT 118
29.         PAR(14)*PAR(10)*X(L)      FNT 120
30.         PAR(15)*PAR(10)*Y(L)      FNT 122
31.         PAR(16)*PAR(11)*X(L)      FNT 124
32.         PAR(17)*PAR(11)*Y(L)      FNT 126
33.         PAR(18)*PAR(7)*PAR(6)      FNT 128
34.         PAR(19)*PAR(10)*PAR(4)      FNT 130
35.         PAR(20)*PAR(15)*X(L)      FNT 132
36.         PAR(21)*PAR(15)*Y(L)      FNT 134
C      -----FNT 136
C      DEVELOP XY-TRANSPPOSE*XY MATRIX      FNT 138
C      -----FNT 140
37.         DO 15 I=1,21      FNT 142
38.            DO 15 J=I,21      FNT 144
39.               AM(I,J)=AM(I,J)+PAR(I)*PAR(J)      FNT 146

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C -----
C DEVELOP XY-TRANSPOSE*7 MATRIX
C -----
40.      DO 20 I=1,21
41. 20      PR(I)=RR(I)+Z(L)*PAR(I)
42.      SSZ=SSZ+7(L)*Z(L)
43. 25      ZSUM=ZSUM+7(L)
44.      DO 30 I=1,20
45.      IP1=I+1
46.      DO 30 J=IP1,21
47. 30      AM(J,I)=AM(I,J)
48.      DO 105 J=1,21
49.      I=1
50.      JJ=J-1
51. 35      DO 40 L=1,J,J
52.      IF (N(L)-I) 40,45,40
53. 40      CONTINUE
54.      IF (AM(I,1)) 55,45,55
55. 45      I=I+1
56.      IF (21-I) 50,35,35
57. 50      WRITE (6,180)
58.      STOP
59. 55      AMA=ABS(AM(I,1))
60.      II=I
61.      II=II+1
62.      IF (21-II) 80,65,65
63. 65      DO 70 IZ=1,J
64.      IF (N(IZ)-II) 70,60,70
65. 70      CONTINUE
66.      AMB=ABS(AM(II,1))
C -----
C TEST FOR MAXIMAL SIZE PIVOTAL ELEMENT
C -----
67.      IF (AMA-AMB) 75,60,60
68. 75      AMA=AMB
69.      I=II
70.      GO TO 60
C -----
71. 80      N(J)=1
72.      DO 85 IZ=1,21
73. 85      AM(IZ,22)=0.0
74.      AM(I,22)=1.0
75.      DA=AM(I,1)
C -----
C NORMALIZE THE PIVOTAL ROW
C -----
76.      DO 90 IZ=2,22
77. 90      AM(1,IZ-1)=AM(1,IZ)/DA
78.      DO 105 IZ=1,21
79.      IF (IZ-I) 95,105,95
80. 95      DB=AM(IZ,1)
C -----
C ZERO OUT NON-PIVOTAL COLUMN ELEMENTS
C -----
81.      DO 100 JZ=2,22
82. 100      AM(IZ,JZ-1)=AM(IZ,JZ)-AM(I,JZ-1)*DB
83. 105      CONTINUE
84.      DO 120 I=1,21
85.      DO 110 J=1,21
86.      IF (N(J)-I) 110,115,110
87. 110      CONTINUE
88. 115      DO 120 L=1,21
89.      LL=N(L)
90. 120      XINV(L,I)=AM(LL,J)
91.      DO 125 I=1,21
92.      A(I)=0.0
93.      DO 125 J=1,21
94. 125      A(I)=A(I)+XINV(I,J)*RR(J)
C -----
C PRINT RESULTS
C -----
95.      WRITE (6,175)
96.      WRITE (6,180)
97.      DO 130 I=1,21
98. 130      WRITE (6,185) I,A(I)

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ENT 150
ENT 152
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99.      WRITE (6,I40)                                FMT 300
100.     WRITE (6,I45)                                FMT 302
101.     DO J35 I=1,N101                              FMT 304
102.         EST=HEAD(X(I),Y(I))                      FMT 306
103.         DELTA=EST-Z(I)                            FMT 308
104.     135 WRITE (6,I70) I,X(I),Y(I),Z(I),EST,DELTA FMT 311
105.         ZBAR=ZSUM/FLOAT(N101)                    FMT 313
106.         SSZBAR=ZSUM*ZBAR                          FMT 314
107.         SSZ=SSZ-SSZBAR                           FMT 316
108.         SSD=0.0                                    FMT 318
109.         DO I40 I=1,Z1                              FMT 320
110.     140 SSF=SSK+A(I)*RH(I)                        FMT 322
111.         SSF=SSF-SSZBAR                            FMT 324
112.         RR=SSF/SSZ                                 FMT 326
113.         PCENF=RR*I40.                             FMT 328
114.         R=SQRT(RR)                                 FMT 330
115.         WRITE (6,I45) PCENF,RR,R                 FMT 332
116.         STOP                                       FMT 334
117.     C                                           FMT 336
118.     145 FORMAT (1H ///5X,*STATISTICAL VALUES*/10X,*PERCENT 95 =*,F11.4/FMT 340
119.     150 FORMAT (5X,*SQUARED =*,F12.6/10X,*R =*,F12.4) FMT 342
120.     150 FORMAT (5X,*EST. M = A1 + A2(X) + A3(Y) + A4(X**2) + A5(A1(Y) + A6(Y**2) FMT 344
121.     150 FORMAT (1(Y**2) +*/14X,*A7(X**3) + A8(X**2)(Y) + A9(X)(Y**2) + A10(Y**3) + A11 FMT 346
122.     150 FORMAT (2/14X,*A11(Y**4) + A12(X**3)(Y) + A13(X**2)(Y**2) +*/14X,*A14(X)(Y** FMT 348
123.     150 FORMAT (3) + A15(Y**4) + A16(X**5) + A17(X**4)(Y) +*/14X,*A18(X**3)(Y**2) FMT 350
124.     150 FORMAT (4 + A19(X**2)(Y**3) + A20(X)(Y**4) + A21(Y**5).///5X,*T,X,I=*,F17. FMT 352
125.     155 FORMAT (4X,I2,10X,F10.3)                  FMT 354
126.     160 FORMAT (1H15X,*ORIGINAL AND COMPUTED VALUES*/1) FMT 356
127.     165 FORMAT (3F10.0)                            FMT 358
128.     170 FORMAT (1H ,14.5(4X,F7.3))                FMT 360
129.     175 FORMAT (1H1,*FIFTH ORDER POLYNOMIAL APPROXIMATION FOR FLOWNET--*/1) FMT 362
130.     180 FORMAT (1H1,*THE EQUATION HAS THE FOLLOWING FORM*/1) FMT 364
131.     185 FORMAT (1H ,#FLOWNET DATA MATRIX IS SINGULAR*) FMT 366
132.     185 FORMAT (1H ,#PT.NO.,#5X,*X#.10X,*Y#.10X,*H#.7X,*EST. H#.5X,*RESTIDUE# FMT 368
133.     190 FORMAT (13)                                FMT 370
134.     END                                           FMT 372

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STATEMENT NUMBER	DEFINITION	REFERENCES
5	11.	10.
10	13.	9.
15	19.	37. 38.
20	41.	40.
25	43.	15.
30	47.	44. 46.
35	51.	56.
40	53.	51. 52.
45	55.	52. 54.
50	57.	56.
55	59.	54.
60	61.	64. 67. 70.
65	63.	62.
70	65.	63. 64.
75	68.	67.
80	71.	62.
85	73.	72.
90	77.	76.
95	80.	79.
100	82.	81.
105	83.	48. 78. 79.
110	87.	85. 86.
115	88.	86.
120	90.	84. 88.
125	94.	91. 93.
130	98.	97.
135	104.	101.
140	110.	109.
145	117. FORMAT	115.
150	118. FORMAT	96.
155	119. FORMAT	98.
160	120. FORMAT	99.
165	121. FORMAT	16.
170	122. FORMAT	104.
175	123. FORMAT	95.
180	124. FORMAT	57.
185	125. FORMAT	100.
190	126. FORMAT	14.

LABEL	TYPE	DEFINITION	REFERENCES							
A	R	4. CDE	5.	92.	94.	98.	110.			
ABS	R	59.	66.							
AM	R	2. D	11.	39.	47.	54.	59.	66.	73.	
			74.	75.	77.	80.	82.	90.		
AMA	R	59.	67.	68.						
AMR	R	66.	67.	68.						
BB	R	2. D	13.	41.	94.	110.				
DA	R	75.	77.							
DB	R	80.	82.							
DELTA	R	103.	104.							
EST	R	102.	103.	104.						
FLOAT	R	105.								
HEAD	R	102.								
I	I	9.	10.	11.	12.	13.	31.	38.	39.	
			40.	41.	44.	45.	47.	49.	52.	
			54.	55.	56.	59.	60.	69.	71.	
			74.	75.	77.	79.	82.	84.	86.	
			90.	91.	92.	94.	97.	98.	101.	
			102.	103.	04.	109.	110.			
II	I	60.	61.	62.	64.	66.	69.			
IP1	I	45.	46.							
IZ	I	63.	64.	72.	73.	76.	77.	78.	79.	
			80.	82.						
J	I	10.	11.	38.	39.	40.	41.	48.	50.	
			63.	71.	85.	86.	90.	93.	94.	
JJ	I	50.	51.							
JZ	I	81.	82.							
L	I	15.	16.	17.	18.	19.	20.	21.	22.	
			23.	24.	25.	26.	27.	29.	30.	
			31.	32.	35.	36.	41.	42.	43.	
			51.	52.	88.	89.	90.			
LL	I	89.	90.							
N	I	2. D	12.	52.	64.	71.	86.	89.		
NTOT	I	14.	15.	101.	105.					
PAR	R	2. DE	5.	8.	17.	18.	19.	20.	21.	
			22.	23.	24.	25.	26.	27.	28.	
			29.	30.	31.	32.	33.	34.	35.	
			36.	39.	41.					
PCENT	R	113.	115.							
R	R	114.	115.							
RR	R	112.	113.	114.	115.					
SGRT	R	114.								
SSR	R	108.	110.	111.	112.					
SSZ	R	6.	42.	107.	112.					
SSZBAR	R	106.	107.	111.						
X	R	3. D	16.	17.	19.	20.	22.	24.	26.	
			29.	31.	35.	102.	104.			
XINV	R	2. D	90.	94.						
Y	R	3. D	16.	18.	20.	21.	23.	25.	27.	
			30.	32.	36.	102.	104.			
Z	R	3. D	16.	41.	42.	43.	103.	104.		
ZBAR	R	105.	106.							
ZSUM	R	7.	43.	105.	106.					

FORSTAT Listing of Subroutine STORE1

```

1. SUBROUTINE STORE1 (XCEN,YCEN,R,FT)
C -----
C SUBROUTINE STORE1
C -----
C PURPOSE-
C TO CALCULATE THE PROPERTIES OF A SLIP CIRCLE AND TO
C EVALUATE THE TAYLOR FACTOR OF SAFETY.
C -----
C USAGE-
C CALL STORE1(XCEN,YCEN,R,I)
C -----
C WHERE XCEN = X-COORD. OF CIRCLE CENTER
C YCEN = Y-COORD. OF CIRCLE CENTER
C R = RADIUS OF CIRCLE
C FT = TAYLOR FACTOR OF SAFETY
C -----
C ALL OTHER VARIABLES ARE SUPPLIED THROUGH BLANK COMMON
C -----
C SUPPORTING ROUTINES-
C SUBROUTINE WEIGHT
C FUNCTION HEAD
C -----
C SYSTEM ROUTINES-
C FUNCTION SIN
C FUNCTION COS
C FUNCTION ATAN
C -----
2. COMMON DUM1(25),DATUM,IUM(17),NSUR,IWAY,NCONC,NUNIF
3. COMMON DUM2(135),XQL(5),XQR(5),XW(5),QW(5),ANGQU(5),QC(5),ANGQC(5)
4. COMMON C(15),PHI(15),XPIEZ(9),YPIEZ(9),Y1(10),XCHECK(25)
5. COMMON YCHECK(25),EXIT(2,2)
6. EQUIVALENCE (HT,HM), (ALPHA,THETA), (SLP,Y), (YAVED,YAVET)
7. DATA AINT,UNITW/0.1,62.4/
8. L=1
9. IDIR=1
10. RNUM=0.0
11. DENOM=0.0
12. XL=EXIT(1,1)
13. YL=EXIT(1,2)
14. Y1(1)=YL
15. Y1(2)=YL
16. IF (XCHECK(L)-EXIT(1,1)) 10,10,15
17. L=L+1
18. GO TO 5
C -----
C DETERMINE SLICES, MOVING IN +X DIRECTION
C -----
19. IF ALPHA=ATAN((XL-XCEN)/(YCEN-YL))
20. YR=YL+R*(COS(ALPHA)-COS(ALPHA+AIN1))
21. IF (YR-EXIT(2,2)) 20,50,50
22. 20 XR=XL+R*(SIN(ALPHA+AIN1)-SIN(ALPHA))
23. 25 IE (XR-XCHECK(L)) 60,30,40
24. 30 L=L+1
25. GO TO 25
C -----
26. 35 L=L+1
27. 40 IF (XCHECK(L+1)-XCHECK(L)) 45,35,45
28. 45 XR=XCHECK(L)
29. YR=YCHECK(L)
30. L=L+1
31. GO TO 60
C -----
32. 50 IF (EXIT(2,1)-XCHECK(L)) 55,55,40
33. 55 XR=EXIT(2,1)
34. YR=EXIT(2,2)
35. IDIR=2

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	C	-----	STI 136
	C	STORE INFORMATION ON CURRENT SLICE	STI 138
	C	-----	STI 140
36.	60	THICK=XR-XL	STI 142
37.		TNP=(YR-YL)/THICK	STI 144
38.		CALL WEIGHT(XP,YR,TNP,YTL,K,WSLC)	STI 146
39.		WSLC=WSLC*THICK	STI 148
40.		THETA=ATAN(TNP)	STI 150
41.		SN=SIN(THETA)	STI 152
42.		CS=COS(THETA)	STI 154
43.		YAVET=(YTL-YI(1))/2.	STI 156
44.		YBAR=(YCEN-YAVET)/R	STI 158
45.		XAVE=(XR-XL)/2.	STI 160
46.		ALP=(YI(1)-YTL)/THICK	STI 162
47.		RNUM=RNUM+C(K)*THICK/CS	STI 164
48.		PNORM=WSLC*CS	STI 166
49.		DENOM=DENOM+WSLC*SN	STI 168
	C	-----	STI 170
	C	CHECK FOR CONCENTRATED LOADING	STI 172
	C	-----	STI 174
50.		IF (NCONC) 85,85,65	STI 176
51.	65	DO 80 J=1,NCONC	STI 178
52.		IF (XQ(J)-XL) 80,80,70	STI 180
53.	70	IF (XQ(J)-XR) 75,80,80	STI 182
54.	75	DENOM=DENOM+SN*QC(J)*SIN(ANGQC(J))+QC(J)*YBAR*CS(ANGQC(J))	STI 184
55.		PNORM=PNORM+QC(J)*SIN(ANGQC(J)-THETA)	STI 186
56.		GO TO 85	STI 188
	C	-----	STI 190
57.	80	CONTINUE	STI 192
	C	-----	STI 194
	C	CHECK FOR UNIFORM LOADING	STI 196
	C	-----	STI 198
58.	85	IF (NUNIF) 110,110,90	STI 200
59.	90	DO 105 J=1,NUNIF	STI 202
60.		IF (XAVE-XQL(J)) 105,105,95	STI 204
61.	95	IF (XAVE-XQR(J)) 100,105,105	STI 206
62.	100	SLP=QU(J)*THICK/COS(ATAN(ALP))	STI 208
63.		DENOM=DENOM+SLP*(COS(ANGQU(J))*YBAR+SN*SIN(ANGQU(J)))	STI 210
64.		PNORM=PNORM+SLP*SIN(ANGQU(J)-THETA)	STI 212
65.		GO TO 110	STI 214
	C	-----	STI 216
66.	105	CONTINUE	STI 218
	C	-----	STI 220
	C	CHECK FOR G.W.T. CONDITION	STI 222
	C	-----	STI 224
67.	110	IF (IWAT) 170,170,115	STI 226
68.	115	DO 125 J=2,NSUR	STI 228
69.		IF (XAVE-XPIEZ(J-1)) 125,125,120	STI 230
70.	120	IF (XAVE-XPIEZ(J)) 130,125,125	STI 232
71.	125	CONTINUE	STI 234
72.		GO TO 170	STI 236
	C	-----	STI 238
73.	130	SLP=(YPIEZ(J)-YPIEZ(J-1))/(XPIEZ(J)-XPIEZ(J-1))	STI 240
74.		Y=YPIEZ(J-1)+SLP*(XAVE-XPIEZ(J-1))	STI 242
75.		GW=UNITW*THICK	STI 244
76.		HT=Y-YAVET	STI 246
77.		IF (HT) 150,150,135	STI 248
78.	135	GO TO (145,140), IWAT	STI 250
79.	140	HT=HEAD(XAVE,YAVET)-YAVET+DATUM	STI 252
80.	145	DENOM=DENOM+GW*HT*(SN-YBAR*ALP)	STI 254
81.		PNORM=PNORM+GW*HT*(CS+SN*ALP)	STI 256
82.	150	YAVEB=(YR+YL)/2.	STI 258
83.		HB=Y-YAVEB	STI 260
84.		IF (HB) 170,170,155	STI 262
85.	155	GO TO (165,160), IWAT	STI 264
86.	160	HB=HEAD(XAVE,YAVEB)-YAVEB+DATUM	STI 266
87.	165	PNORM=PNORM+GW*HB/CS	STI 268
88.	170	RNUM=RNUM+PNORM*PHI(K)	STI 270
89.		XL=XR	STI 272
90.		YL=YR	STI 274
	C	-----	STI 276
	C	RETURN TO START OF SUBROUTINE TO PROCESS ANOTHER SLICE IF NECESSARY	STI 278
	C	-----	STI 280
91.		GO TO (15,175), IUIR	STI 282
92.	175	FT=RNUM/DENOM	STI 284
93.		RETURN	STI 286
94.		END	STI 288

STATEMENT NUMBER	DEFINITION	REFERENCES
5	16.	18.
10	17.	16.
15	19.	16. 91.
20	22.	21.
25	23.	25.
30	24.	23.
35	26.	27.
40	27.	23. 32.
45	28.	27.
50	32.	21.
55	33.	32.
60	36.	23. 31.
65	51.	50.
70	53.	52.
75	54.	53.
80	57.	51. 52. 53.
85	58.	50. 56.
90	59.	58.
95	61.	60.
100	62.	61.
105	66.	59. 60. 61.
110	67.	58. 65.
115	68.	67.
120	70.	69.
125	71.	68. 69. 70.
130	73.	70.
135	78.	77.
140	79.	78.
145	80.	78.
150	82.	77.
155	85.	84.
160	86.	85.
165	87.	85.
170	88.	67. 72. 84.
175	92.	91.

LABEL	TYPE	DEFINITION	REFERENCES									
AINY	R	7. DATA	20.	22.								
ALP	R	66.	62.	80.	81.							
ALPHA	R	6. E	19.	20.	22.							
ANGOC	R	3. CD	54.	55.								
ANGOU	R	3. CD	63.	64.								
ATAN	R	19.	40.	62.								
C	R	4. CD	47.									
COS	R	20.	42.	54.	62.	63.						
CS	R	42.	47.	48.	81.	87.						
DATUM	R	2. C	79.	86.								
DENOM	R	11.	49.	54.	63.	80.	92.					
DUM1	R	2. CD										
DUM2	R	3. CD										
EXIT	R	5. CD	12.	13.	16.	21.	32.	33.	34.			
FI	R	1.	92.									
GW	R	75.	80.	81.	87.							
HB	R	6. E	83.	84.	86.	87.						
HEAD	R	79.	86.									
HT	R	6. E	76.	77.	79.	80.	81.					
IDIR	I	9.	35.	91.								
IDUM	I	2. CD										
IWAT	I	2. C										
J	I	51.	67.	78.	85.							
			52.	53.	54.	55.	59.	60.	61.			
			62.	63.	64.	68.	69.	70.	73.			
			74.									
K	I	38.	47.	88.								
L	I	8.	16.	17.	23.	24.	26.	27.	28.			
			29.	30.	32.							
NCONC	I	2. C	50.	51.								
NSUR	I	2. C	68.									
NUNIF	I	2. C	58.	59.								
PHI	R	4. CD	88.									
PNORM	R	48.	55.	64.	81.	87.	88.					
QC	R	3. CD	54.	55.								
QU	R	3. CD	62.									
R	R	1.	20.	22.	44.							
RNUM	R	10.	47.	88.	92.							
SIN	R	22.	41.	54.	55.	63.	64.					
SLP	R	6. E	62.	63.	64.	73.	74.					
SN	R	41.	49.	54.	63.	80.	81.					
THETA	R	6. E	40.	41.	42.	53.	64.					
THICK	R	36.	37.	39.	46.	47.	62.	75.				
INP	R	37.	38.	40.								
UNITW	R	7.	75.									
WEIGHT	R	78.										
WSLC	R	38.	39.	48.	49.							
XAVE	R	45.	60.	61.	69.	70.	74.	79.	86.			
XCEN	R	1.	19.									
XCHECK	R	4. CD	16.	23.	27.	28.	32.					
XL	R	12.	19.	22.	36.	45.	52.	89.				
XPIEZ	R	4. CD	69.	70.	73.	74.						
XQ	R	3. CD	52.	53.								
XQL	R	3. CD	60.									
XQR	R	3. CD	61.									
XR	R	22.	23.	28.	33.	36.	38.	45.	53.			
			89.									
Y	R	6. E	74.	76.	83.							
YAVR	R	6. E	82.	83.	86.							
YAVET	R	6. E	43.	44.	76.	79.						
YBAR	R	44.	54.	63.	80.							
YCEN	R	1.	19.	44.								
YCHECK	R	5. CD	29.									
YL	R	13.	14.	15.	19.	20.	37.	82.	90.			
YPIEZ	R	4. CD	73.	74.								
YR	R	20.	21.	29.	34.	37.	38.	82.	90.			
YTL	R	38.	43.	46.								
YI	R	4. CD	14.	15.	43.	46.						

FORSTAT Listing of Subroutine STORE2

1.	C	SUBROUTINE STORE2 (XCEN,YCEN,R,Y)	ST2 2
	C	-----	ST2 4
	C	SUBROUTINE STORE2	ST2 6
	C	-----	ST2 8
	C	PURPOSE-	ST2 10
	C	TO CALCULATE AND STORE IN COMMON THE PROPERTIES OF A SLIP	ST2 12
	C	CIRCLE NEEDED TO EVALUATE THE MODIFIED BISHOP FACTOR OF SAFETY.	ST2 14
	C	(MOMENT CENTER = CIRCLE CENTER)	ST2 16
	C	-----	ST2 18
	C	USAGE-	ST2 20
	C	CALL STORE1(XCEN,YCEN,R,Y)	ST2 22
	C	-----	ST2 24
	C	WHERE XCEN = X-COORD. OF CIRCLE CENTER	ST2 26
	C	YCEN = Y-COORD. OF CIRCLE CENTER	ST2 28
	C	R = RADIUS OF CIRCLE	ST2 30
	C	Y = NUMBER OF SLICES GENERATED	ST2 32
	C	-----	ST2 34
	C	ALL OTHER VARIABLES ARE SUPPLIED THROUGH BLANK COMMON	ST2 36
	C	-----	ST2 38
	C	SUPPORTING ROUTINES-	ST2 40
	C	SUBROUTINE WEIGHT	ST2 42
	C	FUNCTION HEAD	ST2 44
	C	-----	ST2 46
	C	SYSTEM ROUTINES-	ST2 48
	C	FUNCTION SIN	ST2 50
	C	FUNCTION COS	ST2 52
	C	FUNCTION ATAN	ST2 54
	C	-----	ST2 56
2.		COMMON DUM1(25),DATUM,IDUM(17),NSUR,IWAT,NCONC,NUNIF	ST2 58
3.		COMMON DUM2(135),XQL(5),XQR(5),XQ(5),QU(5),ANGQU(5),QC(5),ANGQC(5)	ST2 60
4.		COMMON C(15),PHI(15),XPIEZ(9),YPIEZ(9),Y1(10),XCHECK(25)	ST2 62
5.		COMMON YCHECK(25),EXIT(2,2),TOP1(50),TOP2(50),TOP3(50)	ST2 64
6.		EQUIVALENC (HT,HU), (ALPHA,THETA), (SLP,Y)	ST2 66
7.		DATA AINT,UNITW/0.1,62.4/	ST2 68
8.		I=0	ST2 70
9.		L=1	ST2 72
10.		IDIR=1	ST2 74
11.		XL=EXIT(1,1)	ST2 76
12.		YL=EXIT(1,2)	ST2 78
13.		Y1(1)=YL	ST2 80
14.		Y1(2)=YL	ST2 82
15.	5	IF (XCHECK(L)-EXIT(1,1)) 10,10,15	ST2 84
16.	10	L=L+1	ST2 86
17.		GO TO 5	ST2 88
	C	-----	ST2 90
	C	DETERMINE SLICES, MOVING IN X DIRECTION	ST2 92
	C	-----	ST2 94
18.	15	ALPHA=ATAN((XL-XCEN)/(YCEN-YL))	ST2 96
19.		YR=YL+R*(COS(ALPHA)-COS(ALPHA+AIN))	ST2 98
20.		IF (YR-EXIT(2,2)) 20,50,50	ST2 100
21.	20	XR=XL+R*(SIN(ALPHA+AIN)-SIN(ALPHA))	ST2 102
22.	25	IF (XR-XCHECK(L)) 60,30,60	ST2 104
23.	30	L=L+1	ST2 106
24.		GO TO 25	ST2 108
	C	-----	ST2 110
25.	35	L=L+1	ST2 112
26.	40	IF (XCHECK(L+1)-XCHECK(L)) 45,35,45	ST2 114
27.	45	XR=XCHECK(L)	ST2 116
28.		YR=YCHECK(L)	ST2 118
29.		L=L+1	ST2 120
30.		GO TO 60	ST2 122
	C	-----	ST2 124
31.	50	IF (EXIT(2,1)-XCHECK(L)) 55,55,60	ST2 126
32.	55	XR=EXIT(2,1)	ST2 128
33.		YR=EXIT(2,2)	ST2 130
34.		IDIR=2	ST2 132
35.	60	I=I+1	ST2 134
			ST2 136

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C -----
C STORE INFORMATION ON CURRENT SLICE
C -----
36. THICK=XR-XL
37. TNP=(YR-YL)/THICK
38. CALL WEIGHT (XR,YR,TNP,YTL,K,WSLC)
39. WSLC=SLC*THICK
40. THETA=ATAN(TNP)
41. SN=SIN(THETA)
42. CS=COS(THETA)
43. YAVET=(YTL+Y1(1))/2.
44. YAVER=(YR-YL)/2.
45. YBAR=YCEN-YAVER
46. HYBR=1.-(YAVET-YAVER)/YBAR
47. XAVE=(XR+XL)/2.
48. ALP=(Y1(1)-YTL)/THICK
49. TOP1(I)=C(K)*THICK/(CS*CS)
50. TOP2(I)=WSLC*TNP
51. TOP3(I)=TNP*PHT(K)
52. PNORM=WSLC
C -----
C CHECK FOR CONCENTRATED LOADING
C -----
53. IF (NCONC) 85,85,65
54. 65 DO 80 J=1,NCONC
55. IF (XQ(J)-XL) 80,80,70
56. IF (XQ(J)-XR) 75,80,80
57. 75 PNORM=PNORM+QC(J)*(SIN(ANGQC(J))-HYBR*COS(ANGQC(J))*TNP)
58. TOP2(I)=TOP2(I)+QC(J)*(TNP*SIN(ANGQC(J))+HYBR*COS(ANGQC(J)))
59. GO TO 85
C -----
60. 80 CONTINUE
C -----
C CHECK FOR UNIFORM LOADING
C -----
61. 85 IF (NUNIF) 110,110,90
62. 90 DO 105 J=1,NUNIF
63. IF (XAVE-XQ(J)) 105,105,95
64. IF (XAVE-XQ(J)) 100,105,105
65. 100 SLP=QU(J)*THICK/COS(ATAN(ALP))
66. TOP2(I)=TOP2(I)+SLP*(TNP*SIN(ANGQU(J))+HYBR*COS(ANGQU(J)))
67. PNORM=PNORM+SLP*(SIN(ANGQU(J))-HYBR*COS(ANGQU(J))*TNP)
68. GO TO 110
C -----
69. 105 CONTINUE
C -----
C CHECK FOR G.W.T. CONDITION
C -----
70. 110 IF (IWAT) 170,170,115
71. 115 DO 125 J=2,NSUR
72. IF (XAVE-XPTEZ(J-1)) 125,120,120
73. IF (XAVE-XPTEZ(J)) 130,125,125
74. 125 CONTINUE
75. GO TO 170
C -----
76. 130 SLP=(YPIEZ(J)-YPIEZ(J-1))/(XPTEZ(J)-XPTEZ(J-1))
77. Y=YPTEZ(J-1)+SLP*(XAVE-XPTEZ(J-1))
78. GW=UNIT*THICK
79. HT=Y-YAVET
80. IF (HT) 150,150,135
81. 135 GO TO (145,140), IWAT
82. HT=HEAD(XAVE,YAVET)-YAVET+DATUM
83. 145 PNORM=PNORM+GW*HT*(1.+HYBR*ALP*TNP)
84. TOP2(I)=TOP2(I)+GW*HT*(TNP-HYBR*ALP)
85. 150 HB=Y-YAVER
86. IF (HB) 170,170,155
87. 155 GO TO (165,160), IWAT
88. HB=HEAD(XAVE,YAVER)-YAVER+DATUM
89. 165 PNORM=PNORM+GW*HB/(CS*CS)
90. 170 TOP1(I)=(TOP1(I)+PHI(K)*PNORM)/YBAR
91. TOP2(I)=TOP2(I)+YBAR
92. XL=XR
93. YL=YR
C -----
C RETURN TO START OF SUBROUTINE TO PROCESS ANOTHER SLICE IF NECESSARY
C -----
94. GO TO (15,175), IUIR
95. 175 RETURN
96. END

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ST2 138
ST2 140
ST2 142
ST2 144
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ST2 294

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STATEMENT NUMBER	DEFINITION	REFERENCES
9	15.	17.
10	16.	15.
15	18.	15. 94.
20	21.	20.
25	22.	24.
30	23.	22.
35	25.	26.
40	26.	22. 31.
45	27.	26.
50	31.	20.
55	32.	31.
60	35.	22. 30.
65	54.	53.
70	56.	55.
75	57.	56.
80	60.	54. 58. 86.
85	61.	53. 59.
90	62.	61.
95	64.	63.
100	65.	64.
105	69.	62. 63. 64.
110	70.	61. 66.
115	71.	70.
120	73.	72.
125	74.	71. 72. 73.
130	76.	73.
135	81.	80.
140	82.	81.
145	83.	81.
150	85.	80.
155	87.	86.
160	88.	87.
165	89.	87.
170	90.	70. 75. 86.
175	95.	94.

LABEL	TYPE	DEFINITION	REFERENCES									
AINI	R	7. DATA	19.	21.								
ALP	R	48.	65.	83.	84.							
ALPHA	R	6. E	18.	19.	21.							
ANGGC	R	3. CD	57.	58.								
ANGOU	R	3. CD	66.	67.								
ATAN	R	18.	40.	65.								
C	R	4. CD	49.									
COS	R	19.	42.	57.	58.	65.	66.	67.				
CS	R	42.	49.	89.								
DATUM	R	2. C	82.	88.								
DUM1	R	2. CD										
DUM2	R	3. CD										
EXIT	R	5. CD										
GW	R	78.	11.	12.	15.	20.	31.	32.	33.			
HR	R	6. E	83.	84.	89.							
HEAD	R	82.	85.	86.	88.	89.						
HT	R	6. E	88.									
HYHR	R	46.	79.	80.	82.	83.	84.					
I	I	1.	57.	58.	66.	67.	83.	84.				
			8.	35.	35.	49.	50.	51.	58.			
IDIR	I	10.	66.	84.	90.	91.						
IDUM	I	2. CD	34.	94.								
IWAY	I	2. C										
J	I	54.	70.	81.	87.							
			55.	56.	57.	58.	62.	63.	64.			
			65.	66.	67.	71.	72.	73.	76.			
K	I	38.	77.									
L	I	9.	49.	51.	90.							
			15.	16.	22.	23.	25.	26.	27.			
NCONC	I	2. C	28.	29.	31.							
NSUR	I	2. C	53.	54.								
NUNIF	I	2. C	71.									
PHI	R	4. CD	61.	62.								
PNORM	R	52.	51.	90.								
QC	R	3. CD	57.	67.	83.	89.	90.					
QU	R	3. CD	57.	58.								
R	R	1.	65.									
SIN	R	21.	19.	21.								
SLP	R	6. E	41.	57.	58.	66.	67.					
SN	R	41.	65.	66.	67.	76.	77.					
THETA	R	6. E										
THICK	R	36.	40.	41.	42.							
TNP	R	37.	37.	39.	48.	49.	65.	78.				
			38.	40.	50.	51.	57.	58.	66.			
TOP1	R	5. CD	67.	89.	84.							
TOP2	R	5. CD	49.	90.								
TOP3	R	5. CD	50.	58.	66.	84.	91.					
UNITW	R	7.	51.									
WEIGHT	R	38.	78.									
WSLC	R	38.										
XAVE	R	47.	39.	50.	52.							
XCEN	R	1.	63.	64.	72.	73.	77.	82.	88.			
XCHECK	R	4. CD	18.									
XL	R	11.	15.	22.	26.	27.	31.					
XPIEZ	R	4. CD	18.	21.	36.	47.	55.	92.				
XG	R	3. CD	72.	73.	76.	77.						
XQL	R	3. CD	55.	56.								
XOR	R	3. CD	63.									
XR	R	21.	64.									
			22.	27.	32.	36.	38.	47.	56.			
Y	R	6. E	92.									
YAVEH	R	44.	77.	79.	85.							
YAVET	R	43.	45.	46.	85.	88.						
YBAR	R	45.	46.	79.	82.							
YCEN	R	1.	46.	90.	91.							
YCHECK	R	5. CD	18.	45.								
YL	R	12.	28.									
YPIEZ	R	4. CD	13.	14.	18.	19.	37.	44.	93.			
YR	R	19.	76.	77.								
YTL	R	38.	20.	28.	33.	37.	38.	44.	93.			
YI	R	4. CD	43.	48.								
			13.	14.	43.	48.						

FORSTAT Listing of Subroutine STORE3

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1.      SUBROUTINE STORE3 (XCEN,YCEN,R,I)
C
C-----
C          SUBROUTINE STORE3
C-----
C          PURPOSE-
C          TO CALCULATE AND STORE IN COMMON THE PROPERTIES OF A SLIP
C          CIRCLE NEEDED TO EVALUATE THE ADJUSTED MODIFIED BISHOP FACTOR OF
C          SAFETY. (MOMENT CENTER = +Y INFINITY)
C-----
C          USAGE-
C          CALL STORE3(XCEN,YCEN,R,I)
C
C          WHERE XCEN = X-COORD. OF CIRCLE CENTER
C                YCEN = Y-COORD. OF CIRCLE CENTER
C                R   = RADIUS OF CIRCLE
C                I   = NUMBER OF SLICES GENERATED
C-----
C          ALL OTHER VARIABLES ARE SUPPLIED THROUGH BLANK COMMON
C-----
C          SUPPORTING ROUTINES-
C          SUBROUTINE WEIGHT
C          FUNCTION HEAD
C-----
C          SYSTEM ROUTINES-
C          FUNCTION SIN
C          FUNCTION COS
C          FUNCTION ATAN
C-----
2.      COMMON DUM1(25),DATUM,IDUM(17),NSUP,IWAT,NCONC,MINIF
3.      COMMON DUM2(135),XOL(5),XOR(5),XQ(5),OH(5),ANGQU(5),QC(5),ANGQC(5)
4.      COMMON C(15),PHI(15),XPIEZ(9),YPIEZ(9),Y1(10),XCHECK(25)
5.      COMMON YCHECK(25),EXIT(2,2),TOP1(50),TOP2(50),TOP3(50)
6.      EQUIVALENCE (HT,HD), (ALPHA,THETA), (SLP,Y), (YAVET,YAVEB)
7.      DATA AINT,UNITW/0.,62.4/
8.      I=0
9.      L=1
10.     IDIW=1
11.     XL=EXIT(1,1)
12.     YL=EXIT(1,2)
13.     Y1(1)=YL
14.     Y1(2)=YL
15.     5 IF (XCHECK(L)-EXIT(1,1)) 10,10,15
16.     10 L=L+1
17.     GO TO 5
C-----
C          DETERMINE SLICES, MOVING IN +X DIRECTION
C-----
18.     15 ALPHA=ATAN((XL-XCEN)/(YCN-YL))
19.     YP=YL+R*(COS(ALPHA)-COS(ALPHA+AIINT))
20.     IF (YH-EXIT(2,2)) 20,50,50
21.     20 XR=XL+R*(SIN(ALPHA+AIINT)-SIN(ALPHA))
22.     IF (XR-XCHECK(L)) 40,30,40
23.     30 L=L+1
24.     GO TO 25
C-----
25.     35 L=L+1
26.     40 IF (XCHECK(L+1)-XCHECK(L)) 45,35,45
27.     45 XR=XCHECK(L)
28.     YR=YCHECK(L)
29.     L=L+1
30.     GO TO 60
C-----
31.     50 IF (EXIT(2,1)-XCHECK(L)) 55,55,40
32.     55 XR=EXIT(2,1)
33.     YR=EXIT(2,2)
34.     IDIW=2
35.     60 I=I+1
C-----

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C -----
C STORE INFORMATION ON CURRENT SLICE
C -----
36. THICK=XR-XI
37. TNP=(YR-YL)/THICK
38. CALL WFLIGHT (XR,YR,TNP,YTL,K,WSLC)
39. WSLC=WSLC*THICK
40. THETA=ATAN(TNP)
41. SN=SIN(THETA)
42. CS=COS(THETA)
43. XAVE=(XR+XL)/2.
44. ALP=(YI(1)-YTL)/THICK
45. TOP1(I)=C(K)*THICK/(CS*CS)
46. TOP2(I)=WSLC*TNP
47. TOP3(I)=TNP*PHI(K)
48. PNORM=WSLC
C -----
C CHECK FOR CONCENTRATED LOADING
C -----
49. IF (NCONC) 85,85,65
50. 65 DO 80 J=1,NCONC
51. IF (XQ(J)-XI) 80,80,70
52. 70 IF (XQ(J)-XR) 75,80,80
53. 75 PNORM=PNORM+QC(J)*(SIN(ANGOC(J))-COS(ANGOC(J))*TNP)
54. TOP2(I)=TOP2(I)+QC(J)*TNP*SIN(ANGOC(J))+COS(ANGOC(J))
55. GO TO 85
C -----
C CONTINUE
C -----
C CHECK FOR UNIFORM LOADING
C -----
57. 85 IF (NUNIF) 110,110,90
58. 90 DO 105 J=1,NUNIF
59. IF (XAVE-XQ(J)) 105,105,95
60. 95 IF (XAVE-XQR(J)) 100,105,105
61. 100 SLP=QC(J)*THICK/COS(ATAN(ALP))
62. TOP2(I)=TOP2(I)+SLP*(TNP*SIN(ANGQU(J))+COS(ANGQU(J)))
63. PNORM=PNORM+SLP*(SIN(ANGQU(J))-COS(ANGQU(J))*TNP)
64. GO TO 110
C -----
C CONTINUE
C -----
C CHECK FOR G.W.T. CONDITION
C -----
66. 110 IF (IWAT) 170,170,115
67. 115 DO 125 J=2,NSUR
68. IF (XAVE-XPIEZ(J-1)) 125,120,120
69. 120 IF (XAVE-XPIEZ(J)) 130,125,125
70. 125 CONTINUE
71. GO TO 170
C -----
C
72. 130 SLP=(YPIEZ(J)-YPIEZ(J-1))/(XPIEZ(J)-XPIEZ(J-1))
73. Y=YPIEZ(J-1)+SLP*(XAVE-XPIEZ(J-1))
74. YAVET=(YTL+YI(1))/2.
75. GW=UNITW*THICK
76. HT=Y-YAVET
77. IF (HT) 150,150,135
78. 135 GO TO (145,140), IWAT
79. 140 HT=HEAD(XAVE,YAVET)-YAVET+DATUM
80. 145 PNORM=PNORM+GW*HT*(1.+ALP*TNP)
81. TOP2(I)=TOP2(I)+GW*HT*(TNP-ALP)
82. 150 YAVEH=(YR+YL)/2.
83. HH=Y-YAVEH
84. IF (HH) 170,170,155
85. 155 GO TO (165,160), IWAT
86. 160 HH=HEAD(XAVE,YAVEH)-YAVEH+DATUM
87. 165 PNORM=PNORM+GW*HH/(CS*CS)
88. 170 TOP1(I)=TOP1(I)+PHI(K)*PNORM
89. AL=XP
90. YL=YR
C -----
C RETURN TO START OF SUBROUTINE TO PROCESS ANOTHER SLICE IF NECESSARY
C -----
91. GO TO (13,175), IUTR
92. 175 RETURN
93. END

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ST3 13H
ST3 140
ST3 142
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ST3 286
ST3 288-

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STATEMENT NUMBER	DEFINITION	REFERENCES
5	15.	17.
10	16.	15.
15	18.	15. 91.
20	21.	20.
25	22.	24.
30	23.	22.
35	25.	26.
40	26.	22. 31.
45	27.	26.
50	31.	20.
55	32.	31.
60	35.	22. 30.
65	40.	49.
70	52.	51.
75	43.	52.
80	44.	50. 51. 52.
85	57.	49. 54.
90	58.	57.
95	60.	59.
100	61.	60.
105	65.	58. 59. 60.
110	66.	57. 64.
115	67.	56.
120	69.	68.
125	70.	67. 68. 69.
130	72.	69.
135	78.	77.
140	79.	78.
145	80.	78.
150	82.	77.
155	85.	84.
160	86.	85.
165	87.	85.
170	88.	66. 71. 84.
175	92.	91.

LABEL	TYPE	DEFINITION	REFERENCES									
AINI	R	7. DATA	19.	21.								
ALP	R	44.	61.	80.	81.							
ALPHA	R	6. E	18.	19.	21.							
ANGQC	R	3. CD	53.	54.								
ANGQU	R	3. CD	62.	63.								
ATAN	R	18. FUNCTION	40.	61.								
C	R	4. CD	45.									
COS	R	19. FUNCTION	42.	53.	54.	61.	62.	63.				
CS	R	42.	45.	87.								
DATUM	R	2. C	79.	86.								
DUM1	R	2. CD										
DUM2	R	3. CD										
EXIT	R	5. CD										
GW	R	75.	11.	12.	15.	20.	31.	32.	33.			
HR	R	6. E	80.	81.	87.							
HEAD	P	79. FUNCTION	83.	84.	86.	87.						
HT	R	6. E	86.									
I	I	1.	76.	77.	79.	80.	81.					
			8.	35.	35.	45.	46.	47.	54.			
IDIR	I	10.	62.	81.	88.							
IDUM	I	2. CD	34.	91.								
IWAT	I	2. C										
J	I	50.	66.	78.	85.							
			51.	52.	53.	54.	58.	59.	60.			
			61.	62.	63.	67.	68.	69.	72.			
			73.									
K	I	38.	45.	47.	88.							
L	I	9.	15.	16.	22.	23.	25.	26.	27.			
			28.	29.	31.							
NCONC	I	2. C	49.	50.								
NSUR	I	2. C	67.									
NUNITF	I	2. C	57.	58.								
PHI	R	4. CD	47.	88.								
PNORM	R	48.	53.	63.	80.	87.	88.					
QC	R	3. CD	53.	54.								
QU	R	3. CD	61.									
R	R	1.	19.	21.								
SIN	R	21. FUNCTION	41.	53.	54.	62.	63.					
SLP	R	6. E	61.	62.	63.	72.	73.					
SN	R	41.										
THETA	R	6. E	40.	41.	42.							
THICK	R	36.	37.	39.	44.	45.	61.	75.				
TNP	R	37.	38.	40.	46.	47.	53.	54.	62.			
			63.	80.	81.							
TOP1	R	5. CD	45.	88.								
TOP2	R	5. CD	46.	54.	62.	81.						
TOP3	R	5. CD	47.									
UNITW	R	7. DATA	75.									
WEIGHT	R	38. SUBROUTINE										
WSLC	R	38.	39.	46.	48.							
XAVF	R	43.	59.	60.	68.	69.	73.	79.	86.			
XCEN	R	1.	18.									
XCHECK	R	4. CD	15.	22.	26.	27.	31.					
XL	R	11.	18.	21.	36.	43.	51.	89.				
XPIEZ	R	4. CD	68.	69.	72.	73.						
XQ	R	3. CD	51.	52.								
XQL	R	3. CD	59.									
XQR	R	3. CD	60.									
XR	R	21.	22.	27.	32.	36.	38.	43.	52.			
			89.									
Y	R	6. E	73.	76.	83.							
YAVEH	R	6. E	82.	83.	86.							
YAVET	R	6. E	74.	76.	79.							
YCEN	R	1.	18.									
YCHECK	R	5. CD	28.									
YL	R	12.	13.	14.	18.	19.	37.	82.	90.			
YPIEZ	R	4. CD	72.	73.								
YR	R	19.	20.	28.	33.	37.	38.	82.	90.			
YTL	R	38.	44.	74.								
YI	R	4. CD	13.	14.	44.	74.						

FORSTAT Listing of Subroutine STORE4

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1.      SUBROUTINE STORE4 (NSLICE,ILOW,NUMXY)
C-----
C      SUBROUTINE STORE4
C-----
C      PURPOSE=
C      TO CALCULATE AND STORE IN COMMON THE PROPERTIES OF AN
C      IRREGULAR SLIP SURFACE NEEDED TO EVALUATE THE ADJUSTED MODIFIED
C      HISHOP FACTOR OF SAFETY. (MOMENT CENTER = +Y INFINITY)
C-----
C      USAGE=
C      CALL STORE4(NSLICE,ILOW,NUMXY)
C      WHERE  NSLICE = NUMBER OF SLICES GENERATED
C             ILOW  = SUBSCRIPT OF 2ND COORD POINT OF SLIP SURFACE
C             NUMXY  = SUBSCRIPT OF LAST COORD POINT OF SLIP SURFACE
C      ALL OTHER VARIABLES ARE SUPPLIED THROUGH BLANK COMMON
C-----
C      SUPPORTING ROUTINES=
C      SUBROUTINE WEIGHT
C      FUNCTION HEAD
C-----
C      SYSTEM ROUTINES=
C      FUNCTION SIN
C      FUNCTION COS
C      FUNCTION ATAN
C-----
2.      COMMON DUM1(25),DUM2(17),NSUR,IWAT,NCONC,NHINT,DIME(135)
3.      COMMON XQL(5),XQR(5),XQ(5),QU(2),ANGQU(5),QC(5),ANGQC(5),C(15)
4.      COMMON PHI(15),XPIFZ(9),YPIFZ(9),Y1(10),XCHECK(25),YCHECK(25)
5.      COMMON DUM3(4),TOP1(50),TOP2(50),TOP3(50),XRL(12),YRL(12),SQ(11,2)
6.      EQUIVALENCE (HT,HR), (YAVET,YAVER), (SLP,YIX)
7.      DATA UNITW/62.4/
8.      L=1
9.      NSLICE=0
10.     XL=XBL(ILOW-1)
11.     YL=YBL(ILOW-1)
12.     Y1(1)=YL
13.     Y1(2)=YL
C-----
C      DETERMINE SLICES, MOVING IN +X DIRECTION
C-----
14.     DO 150 I=ILOW,NUMXY
15.         ARCTN=SQ(I-1,1)
16.         THETA=ATAN(ARCTN)
17.         SN=SIN(THETA)
18.         CS=COS(THETA)
19.         GO TO 10
C-----
20.     L=L+1
21.     IF (XBL(I)-XCHECK(L)) 30,5,20
22.     L=L+1
23.     IF (XCHECK(L)-XCHECK(L+1)) 25,15,25
24.     XR=XCHECK(L)
25.     YR=YCHECK(L)
26.     L=L+1
27.     IGO=2
28.     GO TO 35
C-----
29.     30  XR=XBL(I)
30.     YR=YBL(I)
31.     IGO=1
C-----
C      STORE INFORMATION ON CURRENT SLICE
C-----
32.     35  NSLICE=NSLICE+1
33.     THICK=XR-XL
34.     CALL WEIGHT (XR,YR,ARCTN,YTL,K,WSLC)
35.     WSLC=WSLC*THICK
36.     XAVE=(XD+XL)/2.
37.     TP=WSLC
38.     AIP=(Y1(1)-YTL)/THICK
39.     TOP1(NSLICE)=C(K)*THICK/(CS*CD)
40.     TOP2(NSLICE)=WSLC*ARCTN
41.     TOP3(NSLICE)=ARCTN*PHI(K)

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C -----
C CHECK FOR CONCENTRATED LOADING
C -----
42.      IF (NCONC) 60,60,40
43.      40      DO 55 J=1,NCONC
44.          IF (XQ(J)-XL) 55,55,45
45.          45      IF (XQ(J)-XR) 50,55,55
46.          50      TP=TP+QC(J)*(SIN(ANGQC(J))-ARCTN*COS(ANGQC(J)))
47.          TOP2(NSLICE)=TOP2(NSLICE)+QC(J)*(ARCTN*SIN(ANGQC(J))+COS(ANGST4 168
          1      QC(J)))
48.          GO TO 60
          C
49.          55      CONTINUE
          C -----
          C CHECK FOR UNIFORM LOADING
          C -----
50.      60      IF (NUNIF) 85,85,65
51.      65      DO 80 J=1,NUNIF
52.          IF (XAVE-XUL(J)) 80,80,70
53.          70      IF (XAVE-XUR(J)) 75,80,80
54.          75      SLP=QU(J)*THICK/COS(ATAN(ALP))
55.          TOP2(NSLICE)=TOP2(NSLICE)+SLP*(ARCTN*SIN(ANGQU(J))+COS(ANGQUST4 194
          1      (J)))
56.          TP=TP+SLP*(SIN(ANGQU(J))-ARCTN*COS(ANGQU(J)))
57.          GO TO 85
          C
58.      80      CONTINUE
          C -----
          C CHECK FOR G.W.T. CONDITION
          C -----
59.      85      IF (IWAT) 145,145,90
60.      90      DO 100 I=2,NSUR
61.          IF (XAVE-XPIFZ(J-1)) 100,95,95
62.          95      IF (XAVE-XPIEZ(J)) 105,100,100
63.          100      CONTINUE
64.          GO TO 145
          C
65.      105      SLP=(YPIEZ(J)-YPIEZ(J-1))/(XPIEZ(J)-XPIFZ(J-1))
66.          YIX=YPIFZ(J-1)+SLP*(XAVE-XPIFZ(J-1))
67.          YAVEI=(YTL+YI(1))/2.
68.          GW=UNITW*THICK
69.          HT=YIX-YAVEI
70.          IF (HT) 125,125,110
71.          110      GO TO (120,115), IWAT
72.          115      HT=HEAD(XAVE,YAVEI)-YAVEI+DATUM
73.          120      IP=TP+HT*GW*(1.+ARCTN*ALP)
74.          TOP2(NSLICE)=TOP2(NSLICE)+HT*GW*(ARCTN+ALP)
75.          125      YAVEH=(YR+YI)/2.
76.          HR=YIX-YAVEH
77.          IF (HR) 145,145,130
78.          130      GO TO (140,135), IWAT
79.          135      HR=HEAD(XAVE,YAVEH)-YAVEH+DATUM
80.          140      TP=TP+HR*GW/(CS+CS)
81.          145      IOPI(NSLICE)=IOPI(NSLICE)+PHI(KI)*TP
82.          YL=YR
83.          XL=XR
          C -----
          C RETURN TO START OF SUBROUTINE TO PROCESS ANOTHER SLICE IF NECESSARY
          C -----
84.      GO TO (150,10), IGD
85.      150      CONTINUE
86.      RETURN
87.      END

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STATEMENT NUMBER	DEFINITION	REFERENCES
5	20.	21.
10	21.	19. 84.
15	22.	23.
20	23.	21.
25	24.	23.
30	29.	21.
35	32.	28.
40	43.	42.
45	45.	44.
50	46.	45.
55	49.	43. 44. 45.
60	50.	42. 48.
65	51.	50.
70	53.	52.
75	54.	53.
80	58.	51. 52. 53.
85	59.	50. 57.
90	60.	59.
95	62.	61.
100	63.	60. 61. 62.
105	65.	62.
110	71.	70.
115	72.	71.
120	73.	71.
125	75.	70.
130	78.	77.
135	79.	78.
140	80.	78.
145	81.	59. 64. 77.
150	85.	14. 84.

LABEL	TYPE	DEFINITION	REFERENCES
ALP	R	38.	54. 73. 74.
ANGQC	R	3. CD	46. 47.
ANGOU	R	3. CD	55. 56.
ARCTN	R	15.	16. 34. 40. 41. 46. 47. 55.
			56. 73. 74.
ATAN	R	16. FUNCTION	54.
C	R	3. CD	39.
COS	R	18. FUNCTION	46. 47. 54. 55. 56.
CS	R	18.	39. 80.
DATUM	R	2. C	72. 79.
DUM1	R	2. CD	
DUM2	R	2. CD	
DUM3	R	5. CD	
GW	R	68.	73. 74. 80.
HB	R	6. E	76. 77. 79. 80.
HEAD	R	72. FUNCTION	79.
HT	R	6. E	69. 70. 72. 73. 74.
I	I	14.	15. 21. 29. 30.
IDUM	I	2. CD	
IGO	I	27.	31. 84.
ILOW	I	1.	10. 11. 14.
IWAY	I	2. C	59. 71. 78.
J	I	43.	44. 45. 46. 47. 51. 52. 53.
			54. 55. 56. 60. 61. 62. 65.
			66.
K	I	34.	39. 41. 81.
L	I	8.	20. 21. 22. 23. 24. 25. 26.
NCONC	I	2. C	42. 43.
NSLICE	I	1.	9. 32. 32. 39. 40. 41. 47.
			55. 74. 81.
NSUR	I	2. C	60.
NUMXY	I	1.	14.
NUNIF	I	2. C	50. 51.
PHI	R	4. CD	41. 81.
QC	R	3. CD	46. 47.
QU	R	3. CD	54.
SIN	R	17. FUNCTION	46. 47. 55. 56.
SLP	R	6. E	54. 55. 56. 65. 66.
SN	R	17.	
SQ	R	5. CD	15.
THETA	R	16.	17. 18.
THICK	R	33.	35. 38. 39. 54. 68.
TOP1	R	5. CD	39. 81.
TOP2	R	5. CD	40. 47. 55. 74.
TOP3	R	5. CD	41.
TP	R	37.	46. 56. 73. 80. 81.
UNITW	R	7. DATA	68.
WEIGHT	R	34. SUBROUTINE	
WSLC	R	34.	35. 37. 40.
XAVE	R	36.	52. 53. 61. 62. 66. 72. 79.
XBL	R	5. CD	10. 21. 29.
XCHECK	R	4. CD	21. 23. 24.
XL	R	10.	33. 36. 44. 83.
XPIEZ	R	4. CD	61. 62. 65. 66.
XQ	R	3. CD	44. 45.
XQL	R	3. CD	52.
XQR	R	3. CD	53.
XR	R	24.	29. 33. 34. 36. 45. 83.
YAVEB	R	6. E	75. 76. 79.
YAVFT	R	6. E	67. 69. 72.
YHL	R	5. CD	11. 30.
YCHECK	R	4. CD	25.
YIX	R	6. E	66. 69. 76.
YL	R	11.	12. 13. 75. 82.
YPIF7	R	4. CD	65. 66.
YR	R	25.	30. 74. 75. 82.
YTL	R	34.	38. 67.
YI	R	4. CD	12. 13. 38. 67.

FORSTAT Listing of Subroutine INOUT

1.	SUBROUTINE INOUT (IP)	IO	2
C	-----	IO	4
C	SUBROUTINE INOUT	IO	6
C	-----	IO	8
C	PURPOSE-	IO	10
C	TO READ-IN, PRINT-OUT, AND STORE IN BLANK COMMON THE PROBLEM	IO	12
C	PARAMETERS.	IO	14
C	-----	IO	16
C	USAGE-	IO	18
C	CALL INOUT(IP)	IO	20
C	-----	IO	22
C	WHERE IP = INTEGER CODE INDICATING TYPE OF ANALYSIS	IO	24
C	-----	IO	26
C	ALL INPUT VARIABLES ARE PLACED IN BLANK COMMON	IO	28
C	-----	IO	30
C	CONTROL CARDS-	IO	32
C	-----	IO	34
C	(A) DESCRIPTION OF PROFILE	IO	36
C	(1) PROBLEM TITLE CARD	IO	38
C	TITLE (COL 1-60) ALPHANUMERIC DESCRIPTION OF PROBLEM.	IO	40
C	-----	IO	42
C	(2) PROFILE PARAMETER CARD	IO	44
C	NBND (COL 1-2) TOTAL NUMBER OF PROFILE BOUNDARIES.	IO	46
C	NTOP (COL 3-4) NUMBER OF GROUND SURFACE BOUNDARIES.	IO	48
C	NSOIL (COL 5-6) NUMBER OF SOIL TYPES IN PROFILE.	IO	50
C	NCONC (COL 7) NUMBER OF CONCENTRATED LOADINGS ON	IO	52
C	GROUND SURFACE.	IO	54
C	NUNIF (COL 8) NUMBER OF UNIFORM LOADINGS ON GROUND	IO	56
C	SURFACE.	IO	58
C	IWAT (COL 9) IF IWAT=0, NO G.W.L.	IO	60
C	IF IWAT=1, PRESSURES ARE ASSUMED EQUAL	IO	62
C	TO VERTICAL DISTANCE TO G.W.T.	IO	64
C	IF IWAT=2, PRESSURES ARE CALCULATED US-	IO	66
C	ING 5TH ORDER POLYNOMIAL CO-	IO	68
C	EFFICIENTS GENERATED BY	IO	70
C	PROGRAM FLWNET.	IO	72
C	NSUR (COL 10) NUMBER OF COORDINATE POINTS NEEDED TO	IO	74
C	DEFINE G.W.T. (REQUIRED IF IWAT=1OR2)	IO	76
C	DATUM (COL 11-20) ELEVATION DATUM FOR BERNOULLI'S	IO	78
C	EQUATION. (REQUIRED IF IWAT=2)	IO	80
C	XTOE (COL 21-30) X-COORD OF TOE. (IF DEFINED)	IO	82
C	YTOE (COL 31-40) Y-COORD OF TOE. (IF DEFINED)	IO	84
C	XTOP (COL 41-50) X-COORD OF CREST. (IF DEFINED)	IO	86
C	YTOP (COL 51-60) Y-COORD OF CREST. (IF DEFINED)	IO	88
C	-----	IO	90
C	(3) BOUNDARY CARDS	IO	92
C	THIS SET INCLUDES ONE CARD/BOUNDARY. THE ORDER MUST BE	IO	94
C	GROUND SURFACE BOUNDARIES FIRST, FROM LEFT TO RIGHT. THE	IO	96
C	SUBSURFACE BOUNDARIES MUST THEN BE ENTERED IN SUCH A WAY THAT	IO	98
C	ANY VERTICAL LINE WOULD INTERSECT WITH DEPTH BOUNDARIES THAT	IO	100
C	ARE IN ANY SUBSEQUENT ORDER. (THIS IS NECESSARY FOR SLICE	IO	102
C	WEIGHT CALCULATIONS)	IO	103
C	BNDX(I,1) (COL 1-10) X-COORD OF LEFT POINT OF BOUNDARY.	IO	106
C	BNDY(I,2) (COL 11-20) Y-COORD OF LEFT POINT OF BOUNDARY.	IO	108
C	BNDX(I,3) (COL 21-30) X-COORD OF RIGHT POINT OF BOUNDARY.	IO	110
C	BNDY(I,4) (COL 31-40) Y-COORD OF RIGHT POINT OF BOUNDARY.	IO	112
C	ITP(I) (COL 41-42) INTEGER CODE REPRESENTING THE	IO	114
C	ORDER IN WHICH THE SOIL TYPE BELOW	IO	116
C	THE BOUNDARY IS READ LATER.	IO	118
C	-----	IO	120
C	(4) SOIL PROPERTY CARD(S)	IO	122
C	THIS SET INCLUDES ONE CARD/SOIL TYPE. THE ORDER MUST	IO	124
C	CORRESPOND TO THE INTEGER CODING DESCRIBED IN (3).	IO	126
C	GAMMA(I) (COL 1-10) TOTAL UNIT WEIGHT.	IO	128
C	C(I) (COL 11-20) MOHR-COULOMB COHESION.	IO	130
C	PHI(I) (COL 21-30) MOHR-COULOMB ANGLE OF INTERNAL	IO	132
C	FRICTION.	IO	134
C	-----	IO	136
C	DEPENDENT UPON THE INFORMATION ON CARD (2), SOME OR ALL OF THE	IO	138
C	FOLLOWING SETS MAY BE OMITTED.	IO	140
C	-----	IO	142
C	(5) UNIFORM LOADING CARD(S)	IO	144
C	THIS SET INCLUDES ONE CARD/LOADING.	IO	146
C	QU(I) (COL 1-10) MAGNITUDE OF LOAD.	IO	148
C	ANGQU(I) (COL 11-20) ANGLE OF LOAD DIRECTION MEASURED	IO	150
C	COUNTER-CLOCKWISE FROM HORIZONTAL.	IO	152
C	XQ(I) (COL 21-30) X-COORD OF LEFT SIDE OF LOAD.	IO	154
C	XQR(I) (COL 31-40) X-COORD OF RIGHT SIDE OF LOAD.	IO	156
C	-----	IO	160

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C      (6) CONCENTRATED LOADING CARD(S)                      IO 162
C      THIS SET INCLUDES ONE CARD/LOADING.                   IO 164
C      UC(I) (COL 1-10) MAGNITUDE OF LOAD.                   IO 166
C      ANGWC(I) (COL 11-20) ANGLE OF LOAD DIRECTION MEASURED IO 168
C      COUNTER-CLOCKWISE FROM HORIZONTAL.                     IO 170
C      XQ(I) (COL 21-30) X-COORD OF LOAD.                     IO 172
C      IO 174
C      (7) G.W.L. CARDS                                       IO 176
C      THIS SET INCLUDES ONE CARD/COORDINATE POINT. THE ORDER MUST IO 178
C      BE FROM LEFT TO RIGHT.                                  IO 180
C      XPIEZ(I) (COL 1-10) X-COORD OF G.W.L. POINT.          IO 182
C      YPIEZ(I) (COL 11-20) Y-COORD OF G.W.L. POINT.          IO 184
C      IO 186
C      (8) 5TH ORDER FLOWNET COEFFICIENT CARDS                IO 188
C      THIS SET INCLUDES ONE CARD/COEFFICIENT. THE ORDER MUST BE IO 190
C      THE SAME AS THE OUTPUT OF PROGRAM FLWNET. THE FORMAT MUST BE IO 192
C      F10.3.                                                   IO 194
C      COEFF(I) (COL 1-10) POLYNOMIAL COEFFICIENT.           IO 196
C      IO 198
C      IO 200
C      COMPLETE CONTROL CARDS WITH PARTS (B) AND (C) DESCRIBED IN MAIN IO 202
C      PROGRAM.                                                 IO 204
C      ----- IO 206
C      SYSTEM ROUTINES=                                         IO 208
C      FUNCTION TAN                                              IO 210
C      ----- IO 212
2.      DIMENSION TITL(10)                                       IO 214
3.      COMMON COEFF(21),XTOE,YTOE,XTOP,YTOP,DATUM,NBND,NTOP,ITP(15) IO 216
4.      COMMON NSUR,IWAT,NCONC,NUNIF,BNDS(20,4),EQ(20,2),GAMMA(15) IO 218
5.      COMMON XQL(5),XQR(5),XQ(5),QU(5),ANGQU(5),QC(5),ANGQC(5) IO 220
6.      COMMON C(15),PHI(15),XPIEZ(9),YPIEZ(9)                 IO 222
7.      DATA PI180/0.01745329/                                  IO 224
C      ----- IO 226
C      READ DATA                                               IO 228
C      ----- IO 230
8.      READ (5,150) (TITL(I),I=1,10)                          IO 232
9.      READ (5,160) NBND,NTOP,NSOIL,NCONC,NUNIF,IWAT,NSUR,DATUM,XTOE,YTOE IO 234
10.     1,XTOP,YTOP                                              IO 236
10.     READ (5,165) ((BNDS(I,J),J=1,4),ITP(I),I=1,NBND)      IO 238
11.     READ (5,170) (GAMMA(I),C(I),PHI(I),I=1,NSOIL)         IO 240
12.     IF (NUNIF) 10,10,5                                       IO 242
13.     5 READ (5,155) (QU(I),ANGQU(I),XQL(I),XQR(I),I=1,NUNIF) IO 244
14.     10 IF (NCONC) 20,20,15                                    IO 246
15.     15 READ (5,170) (QC(I),ANGQC(I),XQ(I),I=1,NCONC)      IO 248
16.     20 IF (IWAT) 35,35,25                                    IO 250
17.     25 READ (5,175) (XPIEZ(I),YPIEZ(I),I=1,NSUR)          IO 252
18.     GO TO (35,30), IWAT                                       IO 254
19.     30 READ (5,180) (COEFF(I),I=1,21)                      IO 256
C      ----- IO 258
C      PRINT AND REDUCE DATA                                  IO 260
C      ----- IO 262
20.     35 WRITE (6,185)                                         IO 264
21.     GO TO (40,45,50), IP                                     IO 266
22.     40 WRITE (6,190)                                         IO 268
23.     GO TO 55                                                 IO 270
C      IO 272
24.     45 WRITE (6,195)                                         IO 274
25.     GO TO 55                                                 IO 276
C      IO 278
26.     50 WRITE (6,200)                                         IO 280
27.     55 WRITE (6,205) (TITL(I),I=1,10),XTOE,XTOP,YTOE,YTOP IO 282
28.     WRITE (6,210) NTOP,NBND                                  IO 284
29.     DO 75 I=1,NBND                                           IO 286
30.         H=BNDS(I,4)-BNDS(I,2)                                IO 288
31.         IF (H) 65,60,65                                       IO 290
32.         60 EQ(I,1)=0.0                                         IO 292
33.         GO TO 70                                              IO 294
C      IO 296
34.         65 EQ(I,1)=H/(BNDS(I,3)-BNDS(I,1))                  IO 298
35.         70 EQ(I,2)=BNDS(I,2)-EQ(I,1)*BNDS(I,1)              IO 300
36.         75 WRITE (6,215) I,(BNDS(I,J),J=1,4),ITP(I)        IO 302

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37.      WRITE (6,220) NSOIL
38.      DO 80 I=1,NSOIL
39.          WRITE (6,225) I,GAMMA(I),C(I),PHI(I)
40.      80  PHI(I)=TAN(PHI(I)*PI/180)
41.      WRITE (6,230) NUNIF
42.      IF (NUNIF) 95,95,85
43.      85  WRITE (6,235)
44.      DO 90 I=1,NUNIF
45.          WRITE (6,240) QU(I),ANGQU(I),XQL(I),XQR(I)
46.      90  ANGQU(I)=ANGQU(I)*PI/180
47.      95  WRITE (6,245) NCONC
48.      IF (NCONC) 110,110,100
49.      100 WRITE (6,250)
50.      DO 105 I=1,NCONC
51.          WRITE (6,255) QC(I),ANGQC(I),XQC(I)
52.      105 ANGQC(I)=ANGQC(I)*PI/180
53.      110 IF (IWAT) 115,115,120
54.      115 WRITE (6,260)
55.      GO TO 145

C
56.      120 WRITE (6,265) NSUR
57.      DO 125 I=1,NSUR
58.          WRITE (6,270) I,XPIEZ(I),YPIEZ(I)
59.      GO TO (130,135), IWAT
60.      130 WRITE (6,275)
61.      GO TO 145

C
62.      135 WRITE (6,285)
63.      DO 140 I=1,21
64.          WRITE (6,280) I,CUEFF(I)
65.      145 RETURN

C
66.      150 FORMAT (10A6)
67.      155 FORMAT (4F10.3)
68.      160 FORMAT (3I2,4I1,5F10.0)
69.      165 FORMAT (4F10.4,12)
70.      170 FORMAT (3F10.4)
71.      175 FORMAT (2F10.4)
72.      180 FORMAT (E10.3)
73.      185 FORMAT (1H123X,*,--SLOPE STABILITY ANALYSIS--*)
74.      190 FORMAT (1H 25X,*,TAYLOR METHOD OF SLICES*///)
75.      195 FORMAT (1H 21X,*,MODIFIED BISHOP METHOD OF SLICES*/23X,*,MOMENT CENT
IER = CIRCLE CENTER*///)
76.      200 FORMAT (1H 21X,*,MODIFIED BISHOP METHOD OF SLICES*/2/X,*,MOMENT CENT
IER = *Y INF*///)
77.      205 FORMAT (1H 10X,*,PROBLEM DESCRIPTION *,10A6////4X,*,PROFILE PARAME
TERS*/8X,*,TOE COORDINATES*,20X,*,CRESI COORDINATES*/12X,*,XTOE =*,
2F10.1,20X,*,XTOP =*,F10.1/12X,*,YTOE =*,F10.1,20X,*,YTOP =*,F10.1/)
78.      210 FORMAT (1H //8X,*,BOUNDARY COORDINATES*/12X,I2,*, TOP BOUNDARIES#
1/12X,I2,*, TOTAL BOUNDARIES*/12X,*,RNO NO.,4X,*,X-LEFT#,4X,*,Y-LEFT#
2,4X,*,X-HIGHT#,3X,*,Y-HIGHT#,4X,*,SOIL TYPE BELOW#)
79.      215 FORMAT (1H 12X,I3,2X,4F10.1,12X,I2)
80.      220 FORMAT (1H //8X,*,SOIL PROPERTIES*/11X,I2,*, TYPES OF SOIL*/16X,*,
1TYPE NO.,*,3X,*,GAMMA*,6X,*,C*,9X,*,PHI#)
81.      225 FORMAT (1H 16X,I2,3X,3F10.1)
82.      230 FORMAT (1H //8X,*,TOP BOUNDARY LOADING*/11X,I2,*, UNIFORM LOADING#
1)
83.      235 FORMAT (1H13X,*,QU#,8X,*,ANGQU#,5X,*,XQ-LEFT#.3X,*,XQ-RIGHT#)
84.      240 FORMAT (1H 8X,4F10.2)
85.      245 FORMAT (1H10X,I2,*, CONCENTRATED LOADING#)
86.      250 FORMAT (1H14X,*,QC#,8X,*,ANGQC#,5X,*,XC#)
87.      255 FORMAT (1H 8X,3F10.2)
88.      260 FORMAT (1H //8X,*,NO G.W.T. HAS BEEN SPECIFIED#)
89.      265 FORMAT (1H //8X,*,G.W.T. SPECIFIED BY#,I3,*, COORDINATE POINTS*/13
1X,*,NO.,*,6X,*,X-GWT#,7X,*,Y-GWT#)
90.      270 FORMAT (1H 12X,I2,2F12.2)
91.      275 FORMAT (1H //8X,*,VERTICAL DISTANCE TO G.W.T. SET EQUAL TO PRESSURE#
1)
92.      280 FORMAT (1H 11X,I2,5X,E10.3)
93.      285 FORMAT (1H //8X,*,FIFTH ORDER POLYNOMIAL APPROXIMATES FLOW NET*/12
1X,*,I#,8X,*,A(I)*/)
94.      ENI

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STATEMENT NUMBER	DEFINITION	REFERENCES
5	13.	12.
10	14.	12.
15	15.	14.
20	16.	14.
25	17.	16.
30	19.	18.
35	20.	16. 18.
40	22.	21.
45	24.	21.
50	26.	21.
55	27.	23. 25.
60	32.	31.
65	34.	31.
70	35.	33.
75	36.	29.
80	40.	38.
85	43.	42.
90	46.	44.
95	47.	42.
100	49.	48.
105	52.	50.
110	53.	48.
115	54.	53.
120	56.	53.
125	58.	57.
130	60.	59.
135	62.	59.
140	64.	63.
145	65.	55. 61.
150	66. FORMAT	8.
155	67. FORMAT	13.
160	68. FORMAT	9.
165	69. FORMAT	10.
170	70. FORMAT	11. 15.
175	71. FORMAT	17.
180	72. FORMAT	19.
185	73. FORMAT	20.
190	74. FORMAT	22.
195	75. FORMAT	24.
200	76. FORMAT	26.
205	77. FORMAT	27.
210	78. FORMAT	28.
215	79. FORMAT	36.
220	80. FORMAT	37.
225	81. FORMAT	39.
230	82. FORMAT	41.
235	83. FORMAT	43.
240	84. FORMAT	45.
245	85. FORMAT	47.
250	86. FORMAT	49.
255	87. FORMAT	51.
260	88. FORMAT	54.
265	89. FORMAT	56.
270	90. FORMAT	58.
275	91. FORMAT	60.
280	92. FORMAT	64.
285	93. FORMAT	62.

LABEL	TYPE	DEFINITION	REFERENCES							
ANGOC	R	5. CO	15.	51.	52.					
ANGOU	R	5. CO	13.	45.	46.					
HNHS	R	4. CO	10.	30.	34.	35.	36.			
C	R	6. CO	11.	39.						
COEFF	R	3. CO	19.	64.						
DATUM	R	3. C	9.							
EQ	R	4. CO	32.	34.	35.					
GAMMA	R	4. CO	11.	39.						
H	R	30.	31.	34.						
I	I	8.	10.	11.	13.	15.	17.	19.	27.	
			20.	30.	32.	34.	35.	36.	38.	
			39.	40.	44.	45.	46.	50.	51.	
			52.	57.	58.	63.	64.			
IP	I	1.	21.							
ITP	I	3. CO	10.	36.						
IWAT	I	4. C	9.	16.	18.	53.	59.			
J	I	10.	36.							
NHND	I	3. C	9.	10.	28.	29.				
NCONC	I	4. C	9.	14.	15.	47.	48.	50.		
NSOIL	I	9.	11.	37.	38.					
NSUR	I	4. C	9.	17.	56.	57.				
NTOP	I	3. C	9.	28.						
NUNIF	I	4. C	9.	12.	13.	41.	42.	44.		
PHI	R	6. CO	11.	39.	40.					
PI180	R	7.	40.	46.	52.					
QC	R	5. CO	15.	51.						
QU	R	5. CO	13.	45.						
TAN	R	40.								
TITL	R	2. D	8.	27.						
XPIFZ	R	6. CO	17.	58.						
XQ	R	5. CO	15.	51.						
XQL	R	5. CO	13.	45.						
XQH	R	5. CO	13.	45.						
XTOE	R	3. C	9.	27.						
XTOP	R	3. C	9.	27.						
YPIFZ	R	6. CO	17.	58.						
YTOE	R	3. C	9.	27.						
YTOP	R	3. C	9.	27.						

DATA

FUNCTION

FORSTAT Listing of Subroutine CROSS

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1.      SUBROUTINE CROSS (ISTOP,XCEN,YCFN,R)
C      -----
C      SUBROUTINE CROSS
C      -----
C      PURPOSE-
C      TO FIND ENTRANCE-EXIT POINTS, INTERMEDIATE SLICE POINTS, AND
C      OTHER POINTS OF IMPORTANCE FOR A GIVEN SLIP CIRCLE AND THE PROFILE
C      BOUNDARIES.
C      -----
C      USAGE-
C      CALL CROSS(ISTOP,XCEN,YCFN,R)
C      -----
C      WHERE ISTOP = INTEGER CODE INDICATING SUCCESSFUL CALL
C      XCEN = X-COORD. OF CIRCLE CENTER
C      YCFN = Y-COORD. OF CIRCLE CENTER
C      R = RADIUS OF CIRCLE
C      -----
C      ALL OTHER VARIABLES ARE SUPPLIED THROUGH BLANK COMMON
C      -----
C      SYSTEM ROUTINES-
C      FUNCTION ABS
C      FUNCTION SQRT
C      -----
C      NOTE-
C      IN ORDER TO ACCOUNT FOR MACHINE ROUNDING, A DIFFERENCE BETWEEN
C      TWO VARIABLES OF LESS THAN 10.E-4 IS TAKEN AS EQUAL TO ZERO. THIS
C      VALUE IS DEFINED IN THE DATA STATEMENT.
C      -----
2.      COMMON DUM1(26),NBND,NTOP,NDUM(17),NCONC,NUNIT,BNDS(20,4)
3.      COMMON EQ(20,2),DUM2(15),AQL(5),XQH(5),XU(5),DUM3(78),XCHECK(25)
4.      COMMON YCHECK(25),EXIT(2,2)
5.      DATA ZERO/10.E-4/
6.      EQUIVALENCE (C,CHAR), (JJ,I), (N,K), (M,LL)
7.      YDIST(XDIST)=YCFN-SQRT(RSQ-(XDIST-XCEN)**2)
8.      L=0
9.      N=1
10.     RSQ=R*R
11.     CSUM=XCEN*XCEN+YCFN*YCFN-RSQ
C      -----
C      FIND ALL CIRCLE-BOUNDARY INTERSECTIONS
C      -----
12.     DO 115 JJ=1,NBND
13.         GO TO (5,5,15), N
14.         IF (NTOP-JJ) 230,10,10
15.         J=NTOP+1-JJ
16.         GO TO 20
C
17.         J=JJ
18.         20
19.         A=1+EQ(J,1)*EQ(J,1)
20.         B=XCEN+EQ(J,1)*(YCFN-EQ(J,2))
21.         C=CSUM+EQ(J,2)*(EQ(J,2)-2.*YCFN)
22.         CHAR=B*B-A*C
23.         IF (ABS(CHAR)-ZERO) 30,25,25
24.         IF (CHAR) 115,30,35
25.         KK=1
26.         GO TO 40
C
27.         KK=2
28.         CHAR=SQRT(CHAR)
29.         DO 110 M=1,KK
30.             GO TO (45,50), M
31.             X=(B+CHAR)/A
32.             X=(B-CHAR)/A
33.             TEMP=X-BNDS(J,1)
34.             IF (ABS(TEMP)-ZERO) 90,60,60
35.             IF (TEMP) 110,90,65
36.             TEMP=X-BNDS(J,3)
37.             IF (ABS(TEMP)-ZERO) 110,70,70
38.             IF (TEMP) 75,110,110
39.             Y=X*EQ(J,1)+EQ(J,2)
40.             IF (Y-BNDS(J,2)) 80,95,85
41.             IF (Y-BNDS(J,4)) 110,110,95
42.             IF (Y-BNDS(J,4)) 95,110,110
43.             X=BNDS(J,1)
44.             Y=X*EQ(J,1)+EQ(J,2)
45.             GO TO (100,100,105), N

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46.      100      NNN=J-N
47.          EXIT(NNN,1)=X
48.          EXIT(NNN,2)=Y
49.          N=N+1
50.          GO TO 110
C
51.      105      L=L+1
52.          XCHECK(L)=X
53.          YCHECK(L)=Y
54.      110      CONTINUE
55.      115      CONTINUE
56.          IF (EXIT(2,2)=YCEN) 120,120,235
C -----
C FIND ALL BOUNDARY END-POINTS WITHIN CIRCLE LIMITS
C -----
57.      120      DO 140 J=1,NRND
58.          DO 140 K=1,3,2
59.              IF (BNDS(J,K)-EXIT(1,1)) 140,140,125
60.              IF (BNDS(J,K)-EXIT(2,1)) 130,140,140
61.              Y=YDIST(BNDS(J,K))
62.              IF (Y-BNDS(J,K+1)) 135,140,140
63.              L=L+1
64.              XCHECK(L)=BNDS(J,K)
65.              YCHECK(L)=Y
66.      140      CONTINUE
C -----
C CHECK FOR UNIFORM LOADINGS
C -----
67.          IF (NUNIF) 180,180,145
68.      145      DO 175 J=1,NUNIF
69.          DO 175 I=1,2
70.              GO TO (150,155), I
71.      150      X=XQL(J)
72.              GO TO 160
C
73.      155      X=XQR(J)
74.      160      IF (X-EXIT(1,1)) 175,175,165
75.      165      IF (X-EXIT(2,1)) 170,175,175
76.      170      L=L+1
77.              XCHECK(L)=X
78.              YCHECK(L)=YDIST(XCHECK(L))
79.      175      CONTINUE
C -----
C CHECK FOR CONCENTRATED LOADINGS
C -----
80.      180      IF (NCONC) 205,205,185
81.      185      DO 200 J=1,NCONC
82.          IF (XQ(J)-EXIT(1,1)) 200,200,190
83.          IF (XQ(J)-EXIT(2,1)) 195,200,200
84.      195      L=L+2
85.              XCHECK(L-1)=0.999*XQ(J)
86.              XCHECK(L)=1.001*XQ(J)
87.              YCHECK(L-1)=YDIST(XCHECK(L-1))
88.              YCHECK(L)=YDIST(XCHECK(L))
89.      200      CONTINUE
90.      205      LL=L-1
91.              IF (LL) 225,225,210
C -----
C ORDER XCHECK ARRAY
C -----
92.      210      DO 220 J=1,LL
93.          K=J+1
94.          DO 220 JJ=K,L
95.              IF (XCHECK(J)-XCHECK(JJ)) 220,220,215
96.      215      TEMP=XCHECK(J)
97.              XCHECK(J)=XCHECK(JJ)
98.              XCHECK(JJ)=TEMP
99.              TEMP=YCHECK(J)
100.             YCHECK(J)=YCHECK(JJ)
101.             YCHECK(JJ)=TEMP
102.      220      CONTINUE
103.      225      XCHECK(L+1)=999999.
104.      RETURN
105.      230      N=N-1
106.      WRITE (6,245) R,N
107.      GO TO 240
C
108.      235      WRITE (6,250) R
109.      240      ISTOP=2
110.      RETURN
C
111.      245      FORMAT (32X,F8,2,10X,I2,10X, TOP BOUNDARY=CIRCLE INTERSECTION#)
112.      250      FORMAT (32X,F8,2,10X,1Y-EXIT GREATER THAN Y-CENTER#)
113.      END

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CR 158
CR 160
CR 162
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CR 322
CR 324-

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STATEMENT NUMBER	DEFINITION	REFERENCES
5	14.	1.
10	15.	14.
15	17.	13.
0	18.	16.
25	23.	22.
30	24.	22. 27.
35	26.	23.
40	28.	25.
45	30.	29.
50	32.	29.
55	33.	31.
60	35.	34.
65	36.	35.
70	38.	37.
75	39.	38.
80	41.	40.
85	42.	40.
90	43.	34. 35.
95	45.	40. 41. 42.
100	46.	45.
105	51.	45.
10	54.	28. 35. 37. 38. 41. 42. 50.
115	55.	12. 23.
120	57.	56.
125	60.	59.
130	61.	60.
135	63.	62.
140	66.	57. 58. 59. 60. 64.
145	68.	67.
150	71.	70.
155	73.	70.
160	74.	72.
165	75.	74.
170	76.	75.
175	79.	68. 69. 74. 75.
180	80.	67.
185	81.	80.
190	83.	82.
195	84.	83.
200	89.	81. 82. 83.
205	90.	80.
210	92.	91.
215	96.	95.
220	102.	92. 94. 95.
225	103.	91.
230	105.	14.
235	108.	56.
240	109.	107.
245	111. FORMAT	106.
250	112. FORMAT	108.

LABFL	TYPE	DEFINITION	REFERENCES							
A	R	18.	21.	30.	32.					
ABS	R	22.	34.	37.						
B	R	19.	21.	30.	32.					
BNDS	R	2. CD	33.	36.	40.	41.	42.	43.	59.	
			60.	61.	62.	64.				
C	R	6. E	20.	21.						
CHAR	R	6. E	21.	22.	23.	27.	30.	32.		
CSUM	R	11.	20.							
DUM1	R	2. CD								
DUM2	R	3. CD								
DUM3	R	3. CD								
EQ	R	3. CD	18.	19.	20.	39.	44.			
EXIT	R	4. CD	47.	48.	56.	59.	60.	74.	75.	
			82.	83.						
I	I	6. E	69.	70.						
IDUM	I	2. CD								
ISTOP	I	1.	109.							
J	I	15.	17.	18.	19.	20.	33.	36.	39.	
			40.	41.	42.	43.	44.	57.	59.	
			60.	61.	62.	64.	68.	71.	73.	
			81.	82.	83.	85.	86.	92.	93.	
			95.	96.	97.	99.	100.			
JJ	I	6. E	12.	14.	15.	17.	94.	95.	97.	
			98.	100.	101.					
K	I	6. E	58.	59.	60.	61.	62.	64.	93.	
			94.							
KK	I	24.	26.	28.						
L	I	8.	51.	52.	53.	63.	64.	65.	76.	
			77.	78.	84.	85.	86.	87.	88.	
			90.	94.	103.					
LL	I	6. E	90.	91.	92.					
M	I	6. E	28.	29.						
N	I	6. E	9.	13.	45.	46.	49.	105.	106.	
NBND	I	2. C	12.	57.						
NCONC	I	2. C	80.	81.						
NNN	I	46.	47.	48.						
NTOP	I	2. C	14.	15.						
NUNIF	I	2. C	67.	68.						
R	R	1.	10.	106.	108.					
RSQ	R	7.	10.	11.						
SQRT	R	7.	27.							
TEMP	R	33.	34.	35.	36.	37.	38.	96.	98.	
			99.	101.						
X	R	30.	32.	33.	36.	39.	43.	44.	47.	
			52.	71.	73.	74.	75.	77.		
XCEN	R	1.	7.	11.	19.					
XCHECK	R	3. CD	52.	64.	77.	78.	85.	86.	87.	
			88.	95.	96.	97.	98.	103.		
XDIST	R	7.								
XQ	R	3. CD	82.	83.	85.	86.				
XQL	R	3. CD	71.							
XQR	R	3. CD	73.							
Y	R	39.	40.	41.	42.	44.	48.	53.	61.	
			62.	65.						
YCEN	R	1.	7.	11.	11.	19.	20.	56.		
YCHECK	R	4. CD	53.	65.	78.	87.	88.	99.	100.	
			101.							
YDIST	R ASF	7.	61.	78.	87.	88.				
ZERO	R	5. DATA	22.	34.	37.					

FORSTAT Listing of Subroutine SLPBND

```

1.      SUBROUTINE SLPBND (ILOW,NUMXY)                                SLB  2
C      -----SLB  4
C      SUBROUTINE SLPBND                                SLB  6
C      -----SLB  8
C      PURPOSE=                                SLB 10
C      TO FIND INTERMEDIATE SLICE POINTS FOR A GIVEN IRREGULAR SLIP SLB 12
C      SURFACE AND THE PROFILE BOUNDARIES.                                SLB 14
C      -----SLB 16
C      USAGE=                                SLB 18
C      CALL SLPBND(ILOW,NUMXY)                                SLB 20
C      -----SLB 22
C      WHERE ILOW = SUBSCRIPT OF 2ND COORD POINT OF SLIP SURFACE SLB 24
C      NUMXY = SUBSCRIPT OF LAST COORD POINT OF SLIP SURFACE SLB 26
C      -----SLB 28
C      ALL OTHER VARIABLES ARE SUPPLIED THROUGH BLANK COMMON SLB 30
C      -----SLB 32
C      SYSTEM ROUTINES=                                SLB 34
C      FUNCTION ABS                                SLB 36
C      -----SLB 38
C      NOTE=                                SLB 40
C      IN ORDER TO ACCOUNT FOR MACHINE ROUNDING, A DIFFERENCE BETWEEN SLB 42
C      TWO VARIABLES OF LESS THAN 10.E-4 IS TAKEN AS EQUAL TO ZERO. THIS SLB 44
C      VALUE IS DEFINED IN THE DATA STATEMENT.                                SLB 46
C      -----SLB 48
2.      COMMON DUM1(26),NRND,NTOP,INDUM(17),NCONC,NUNIF,BNDS(20,4) SLB 50
3.      COMMON FQ(20,2),DUM2(15),XQL(5),XQR(5),XQ(5),DUM3(74),XCHECK(25) SLB 52
4.      COMMON YCHECK(25),DUM4(154),XI(12),DUM5(12),SEQ(11,2) SLB 54
5.      DATA ZERO/10.E-4/ SLB 56
6.      ICHECK=0 SLB 58
C      -----SLB 60
C      FIND SURFACE-BOUNDARY INTERSECTIONS AND INTERIOR BOUNDARY POINTS SLB 62
C      -----SLB 64
7.      DO 55 L=ILOW,NUMXY SLB 66
8.      DO 55 K=1,NRND SLB 68
9.      IF (K-NTOP) 35,35,5 SLB 70
10.     5 TEMP=EQ(K,1)-SEQ(L-1,1) SLB 72
11.     IF (ABS(TEMP)-ZERO) 35,10,10 SLB 74
12.     10 XI=(SEQ(L-1,2)-EQ(K,2))/TEMP SLB 76
13.     IF (XI-X(L-1)-ZERO) 35,35,15 SLB 78
14.     15 IF (XI-X(L)+ZERO) 20,35,35 SLB 80
15.     20 IF (XI-BNDS(K,1)-ZERO) 35,35,25 SLB 82
16.     25 IF (XI-BNDS(K,3)+ZERO) 30,35,35 SLB 84
17.     30 ICHECK=ICHECK+1 SLB 86
18.     XCHECK(ICHECK)=XI SLB 88
19.     YCHECK(ICHECK)=XI*SEQ(L-1,1)+SEQ(L-1,2) SLB 90
20.     35 DO 55 I=1,3,2 SLB 92
21.     IF (BNDS(K,I)-X(L-1)-ZERO) 55,55,40 SLB 94
22.     IF (BNDS(K,I)-X(L)+ZERO) 45,55,55 SLB 96
23.     45 YI=BNDS(K,I)*SEQ(L-1,1)+SEQ(L-1,2) SLB 98
24.     IF (BNDS(K,I+1)-YI+ZERO) 55,55,60 SLB 100
25.     50 ICHECK=ICHECK+1 SLB 102
26.     XCHECK(ICHECK)=BNDS(K,I) SLB 104
27.     YCHECK(ICHECK)=YI SLB 106
28.     55 CONTINUE SLB 108
C      -----SLB 110
C      CHECK FOR UNIFORM LOADING SLB 112
C      -----SLB 114
29.     IF (NUNIF) 110,110,60 SLB 116
30.     60 DO 105 K=1,NUNIF SLB 118
31.     DO 105 I=1,2 SLB 120
32.     GO TO (65,70), I SLB 122
33.     65 XI=XQL(K) SLB 124
34.     GO TO 75 SLB 126
C      -----SLB 128
35.     70 XI=XQR(K) SLB 130
36.     75 IF (XI-X(ILOW-1)) 105,105,80 SLB 132
37.     80 IF (XI-X(NUMXY)) 85,105,105 SLB 134
38.     85 ICHECK=ICHECK+1 SLB 136
39.     XCHECK(ICHECK)=XI SLB 138
40.     DO 100 L=ILOW,NUMXY SLB 140
41.     IF (XI-X(L)) 90,100,100 SLB 142
42.     90 IF (XI-X(L-1)) 100,100,95 SLB 144
43.     95 YCHECK(ICHECK)=SEQ(L-1,1)*XI+SEQ(L-1,2) SLB 146
44.     GO TO 105 SLB 148
C      -----SLB 150
45.     100 CONTINUE SLB 152
46.     105 CONTINUE SLB 154

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C -----
C CHECK FOR CONCENTRATED LOADING
C -----
47. 110 IF (NCONC) 150,155,115 SLB 162
48. 115 DO 145 K=1,NCONC SLB 164
49. IF (XQ(K)-X(TLOW-1)) 145,145,120 SLB 166
50. 120 IF (XQ(K)-X(NUMXY)) 125,145,145 SLB 168
51. 125 ICHECK=ICHECK+2 SLB 170
52. XCHECK(ICHECK-1)=0.999*XQ(K) SLB 172
53. XCHECK(ICHECK)=1.001*XQ(K) SLB 174
54. DO 140 L=TLOW,NUMXY SLB 176
55. IF (XQ(K)-X(L)) 130,140,140 SLB 178
56. 130 IF (XQ(K)-X(L-1)) 140,140,135 SLB 180
57. 135 YCHECK(ICHECK)=SEQ(L-1,1)*XCHECK(ICHECK)+SEQ(L-1,2) SLB 182
58. YCHECK(ICHECK-1)=SEQ(L-1,1)*XCHECK(ICHECK-1)+SEQ(L-1,2) SLB 184
59. GO TO 145 SLB 186
C SLB 188
60. 140 CONTINUE SLB 190
61. 145 CONTINUE SLB 192
62. 150 K=ICHECK-1 SLB 194
63. IF (K) 170,170,155 SLB 196
C SLB 198
C ORDER XCHECK ARRAY SLB 200
C SLB 202
64. 155 DO 165 I=1,K SLB 204
65. L=I+1 SLB 206
66. DO 165 II=L,ICHECK SLB 208
67. IF (XCHECK(I)-XCHECK(II)) 165,165,160 SLB 210
68. 160 TEMP=XCHECK(I) SLB 212
69. XCHECK(I)=XCHECK(II) SLB 214
70. XCHECK(II)=TEMP SLB 216
71. TEMP=YCHECK(I) SLB 218
72. YCHECK(I)=YCHECK(II) SLB 220
73. YCHECK(II)=TEMP SLB 222
74. 165 CONTINUE SLB 224
75. 170 XCHECK(ICHECK+1)=999999. SLB 226
76. RETURN SLB 228
77. END SLB 230-

```

STATEMENT NUMBER	DEFINITION	REFERENCES
5	10.	9.
10	12.	11.
15	14.	13.
20	15.	14.
25	16.	15.
30	17.	16.
35	20.	9. 11. 13. 14. 15. 16.
40	22.	21.
45	23.	22.
50	25.	24.
55	28.	7. 8. 20. 21. 22. 24.
60	30.	29.
65	33.	32.
70	35.	32.
75	36.	34.
80	37.	36.
85	38.	37.
90	42.	41.
95	43.	42.
100	45.	40. 41. 42.
105	46.	30. 31. 36. 37. 44.
110	47.	29.
115	48.	47.
120	50.	49.
125	51.	50.
130	56.	55.
135	57.	56.
140	60.	54. 55. 56.
145	61.	48. 49. 50. 54.
150	62.	47.
155	64.	63.
160	68.	67.
165	74.	64. 66. 67.
170	75.	63.

LABEL	TYPE	DEFINITION	REFERENCES							
ABS	R	11.	FUNCTION							
BND5	R	2. CD		15.	16.	21.	22.	23.	24.	26.
DUM1	R	2. CD								
DUM2	R	3. CD								
DUM3	R	3. CD								
DUM4	R	4. CD								
DUM5	R	4. CD								
EQ	R	3. CD		10.	12.					
I	I	20.		21.	22.	23.	24.	26.	31.	32.
ICHECK	I	6.		64.	65.	67.	68.	69.	71.	72.
				17.	18.	19.	25.	26.	27.	38.
				39.	43.	51.	52.	53.	57.	58.
				62.	66.	75.				
IDUM	I	2. CD								
II	I	66.		67.	69.	70.	72.	73.		
ILOW	I	1.		7.	36.	40.	49.	54.		
K	I	8.		9.	10.	12.	15.	16.	21.	22.
				23.	24.	26.	30.	33.	35.	48.
				49.	50.	52.	53.	55.	56.	62.
				63.	64.					
L	I	7.		10.	12.	13.	14.	19.	21.	22.
				23.	40.	41.	42.	43.	54.	55.
				56.	57.	58.	65.	66.		
NBND	I	2. C		8.						
NCONC	I	2. C		47.	48.					
NTOP	I	2. C		9.						
NUMXY	I	1.		7.	37.	40.	50.	54.		
NUNIF	I	2. C		29.	30.					
SEQ	R	4. CD		10.	12.	19.	23.	43.	57.	58.
TEMP	R	10.		11.	12.	68.	70.	71.	73.	
X	R	4. CD		13.	14.	21.	22.	36.	37.	41.
				42.	49.	50.	55.	56.		
XCHECK	R	3. CD		18.	26.	39.	52.	53.	57.	58.
				67.	68.	69.	70.	75.		
XI	R	12.		13.	14.	15.	16.	18.	19.	33.
				35.	36.	37.	39.	41.	42.	43.
XQ	R	3. CD		49.	50.	52.	53.	55.	56.	
XQL	R	3. CD		33.						
XQR	R	3. CD		35.						
YCHECK	R	4. CD		19.	27.	43.	57.	58.	71.	72.
				73.						
YI	R	23.		24.	27.					
ZERO	R	5.	DATA	11.	13.	14.	15.	16.	21.	22.
				24.						

FORSTAT Listing of Subroutine WEIGHT

```

1.      SUBROUTINE WEIGHT (XR,YR,TNP,YTL,K,WSLC)
C      -----
C      SUBROUTINE WEIGHT
C      -----
C      PURPOSE=
C      TO CALCULATE THE WEIGHT OF A GIVEN SLICE AND TO DETERMINE
C      THE SOIL TYPE AT THE BASE OF THE SLICE.
C      -----
C      USAGE=
C      CALL WEIGHT(XR,YR,TNP,YTL,K,WSLC)
C
C      WHERE XR = AI CALL, BOTTOM RIGHT X-COORD. OF SLICE
C            YR = AI CALL, BOTTOM RIGHT Y-COORD. OF SLICE
C            TNP = AI CALL, SLOPE OF LOWER BOUNDARY OF SLICE
C            YTL = AI RETURN, TOP LEFT Y-COORD. OF SLICE
C            K   = AI RETURN, SOIL TYPE AT BASE OF SLICE
C            WSLC = AI RETURN, WEIGHT OF SLICE/UNIT WIDTH
C
C      ALL OTHER VARIABLES ARE SUPPLIED THROUGH BLANK COMMON
C      -----
2.      DIMENSION JSTORE(9), YY1(10), YY2(10)
3.      COMMON DUM(26),NBND,1DUM1,1TP(15),1DUM2(4),BNDS(20,4),EW(20,2)
4.      COMMON GAMMA(15),DUM2(13),Y1(10)
5.      N1=1
6.      N2=1
C      -----
C      FIND ALL R.H.S. INTERSECTIONS
C      -----
7.      DO 55 J=1,NBND
8.          Y=XR*EW(J,1)+EW(J,2)
9.          IF (XR-BNDS(J,1)) 55,15,5
10.         IF (XR-BNDS(J,3)) 10,20,55
11.         IF (Y-YR) 55,25,40
12.         IF (Y-YR) 55,30,45
13.         IF (Y-YR) 55,35,50
14.         IF (EW(J,1)-TNP) 50,55,45
15.         IF (EW(J,1)-TNP) 55,55,45
16.         IF (EW(J,1)-TNP) 50,55,55
17.         YY1(N1)=Y
18.         JSTORE(N1)=1TP(J)
19.         N1=N1+1
20.         YY2(N2)=Y
21.         N2=N2+1
22.         GO TO 55
C
23.         YY1(N1)=Y
24.         JSTORE(N1)=1TP(J)
25.         N1=N1+1
26.         55 CONTINUE
27.         YY1(N1)=YR
28.         YY2(N2)=YR
C      -----
C      CALCULATE WEIGHT OF SLICE
C      -----
29.         WSLC=0.0
30.         DO 60 J=2,N1
31.             K=JSTORE(J-1)
32.             WSLC=WSLC+.5*GAMMA(K)*(YY1(J-1)+Y1(J-1)-YY1(J)-Y1(J))
33.             YTL=Y1(J)
C      -----
C      RESTORE R.H.S. INTERSECTIONS FOR NEXT SLICE
C      -----
34.         DO 65 J=1,N2
35.             Y1(J)=YY2(J)
36.             RETURN
37.         END

```

STATE IDENT NUMBER	DEFINITION	REFERENCES							
5	10.	9.							
10	11.	10.							
15	12.	9.							
20	13.	10.							
25	14.	11.							
30	15.	12.							
35	16.	13.							
40	17.	11.							
45	20.	12.	14.	15.					
50	23.	13.	14.	16.					
55	26.	7.	9.	10.	11.	12.	13.	14.	
		15.	16.	22.					
60	32.	30.							
65	35.	34.							

LABEL	TYPE	DEFINITION	REFERENCES							
HNDS	R	3. C	9.	10.						
DUM1	R	3. C								
DUM2	R	4. C								
EU	R	3. C	8.	14.	15.	16.				
GAMMA	R	4. C	32.							
IDUM1	I	3. C								
IDUM2	I	3. C								
ITP	I	3. C	18.	24.						
J	I	7.	8.	9.	10.	14.	15.	16.	18.	
JSTORE	I	2. D	24.	30.	31.	32.	34.	35.		
K	I	1.	18.	24.	31.					
NBND	I	3. C	31.	32.						
N1	I	5.	7.							
			17.	18.	19.	23.	24.	25.	27.	
			30.							
N2	I	6.	20.	21.	28.	34.				
INP	R	1.	14.	15.	16.					
WSLC	R	1.	29.	32.						
XR	R	1.	8.	9.	10.					
Y	R	8.	11.	12.	13.	17.	20.	23.		
YR	R	1.	11.	12.	13.	27.	28.			
Y1L	R	1.	33.							
YY1	R	2. D	17.	23.	27.	32.				
YY2	R	2. D	20.	28.	35.					
Y1	R	4. C	32.	33.	35.					

FORSTAT Listing of Subroutine RADIUS

1.		SUBROUTINE RADIUS (XCEN,YCEN,RAD,I)	RD	2
	C	-----	RD	4
	C	SUBROUTINE RADIUS	RD	6
	C	-----	RD	8
	C	PURPOSE=	RD	10
	C	TO BUILD ARRAY OF RADII THAT ARE TANGENT TO LOWER BOUNDARIES.	RD	12
	C	THE MAXIMUM RADIUS IS THE MINIMUM OF THOSE THAT ARE TANGENT TO	RD	14
	C	BOUNDARIES WITH ITP=0.	RD	16
	C	-----	RD	18
	C	USAGE=	RD	20
	C	CALL RADIUS(XCEN,YCEN,RAD,I)	RD	22
	C		RD	24
	C	WHERE XCEN = X-COORD. OF CIRCLE CENTER	RD	26
	C	YCEN = Y-COORD. OF CIRCLE CENTER	RD	28
	C	RAD = ARRAY OF RADII	RD	30
	C	I = NUMBER OF RADII	RD	32
	C		RD	34
	C	ALL OTHER VARIABLES ARE SUPPLIED THROUGH BLANK COMMON	RD	36
	C	-----	RD	38
	C	SYSTEM ROUTINES=	RD	40
	C	FUNCTION SQRT	RD	42
	C	-----	RD	44
2.		DIMENSION RAD(15)	RD	46
3.		COMMON DUM1(21),XIOE,YIOE,XTOP,YTOP,DUM2,NBND,NTOP,ITP(15)	RD	48
4.		COMMON IDUM(4),BNDS(20,4),EQ(20,2)	RD	50
5.		EQUIVALENCE (XI,TEMP), (MTOP,II)	RD	52
6.		R(A,B)=SQRT((XCEN-A)**2+(YCEN-B)**2)	RD	54
7.		RMAX=999999.	RD	56
8.		RAD(I)=R(XIOE,YIOE)	RD	58
9.		TEMP=R(XTOP,YTOP)	RD	60
10.		IF (RAD(I)-TEMP) 5,10,10	RD	62
11.	5	RAD(I)=TEMP	RD	64
12.	10	MTOP=NTOP+1	RD	66
13.		II=I	RD	68
	C	-----	RD	70
	C	FIND ALL TANGENTS TO LOWER BOUNDARIES	RD	72
	C	-----	RD	74
14.		DO 50 J=MTOP,NBND	RD	76
15.		XI=(XCEN+EQ(J,1)*(YCEN-EQ(J,2)))/(EQ(J,1)*EQ(J,1)+1.)	RD	78
16.		IF (XI-BNDS(J,1)) 50,15,15	RD	80
17.	15	IF (XI-BNDS(J,3)) 20,50,50	RD	82
18.	20	YI=EQ(J,1)*XI+EQ(J,2)	RD	84
19.		IF (YI-BNDS(J,2)) 30,35,25	RD	86
20.	25	IF (YI-BNDS(J,4)) 35,50,50	RD	88
21.	30	IF (YI-BNDS(J,4)) 50,50,35	RD	90
22.	35	I=I+1	RD	92
23.		RAD(I)=R(XI,YI)	RD	94
24.		IF (ITP(J)) 40,40,50	RD	96
25.	40	IF (RAD(I)-RMAX) 45,50,50	RD	98
26.	45	RMAX=RAD(I)	RD	100
27.	50	CONTINUE	RD	102
28.		II=I-1	RD	104
	C	-----	RD	106
	C	ORDER RAD ARRAY	RD	108
	C	-----	RD	110
29.		DO 60 J=1,II	RD	112
30.		K=J+1	RD	114
31.		DO 60 JJ=K,I	RD	116
32.		IF (RAD(J)-RAD(JJ)) 60,60,55	RD	118
33.	55	TEMP=RAD(J)	RD	120
34.		RAD(J)=RAD(JJ)	RD	122
35.		RAD(JJ)=TEMP	RD	124
36.	60	CONTINUE	RD	126
	C	-----	RD	128
	C	INSURE DESIRED (ITP=0) MAXIMUM	RD	130
	C	-----	RD	132
37.		DO 65 JJ=1,I	RD	134
38.		J=I-JJ+1	RD	136
39.		IF (RAD(J)-RMAX) 70,70,65	RD	138
40.	65	CONTINUE	RD	140
41.	70	I=J	RD	142
42.		RETURN	RD	144
43.		END	RD	146

STATEMENT NUMBER	DEFINITION	REFERENCES							
5	11.	10.							
10	12.	10.							
15	17.	16.							
20	18.	17.							
25	20.	19.							
30	21.	19.							
35	22.	19.	20.	21.					
40	25.	24.							
45	26.	25.							
50	27.	14.	16.	17.	20.	21.	24.	25.	
55	33.	32.							
60	36.	29.	31.	32.					
65	40.	37.	39.						
70	41.	39.							

LABEL	TYPE	DEFINITION	REFERENCES							
A	R	6.								
B	R	6.								
BNDS	R	4. CD	16.	17.	19.	20.	21.			
DUM1	R	3. CD								
DUM2	R	3. C								
EQ	R	4. CD								
I	I	1.	15.	18.	22.	23.	25.	26.	28.	31.
			13.	22.	38.	41.				
IDUM	I	4. CD								
II	I	5. E	28.	29.						
IYP	I	3. CD	24.							
J	I	14.	15.	16.	17.	18.	19.	20.	21.	
			24.	29.	30.	32.	33.	34.	36.	
			39.	41.						
JJ	I	31.	32.	34.	35.	37.	38.			
K	I	30.	31.							
MTOP	I	5. E	12.	14.						
NBND	I	3. C								
NTOP	I	3. C	12.							
R	R ASF	6.	8.	9.	23.					
RAD	R	1. D	2.	8.	10.	11.	23.	25.	26.	
			32.	33.	34.	35.	39.			
			25.	26.	39.					
RMAX	R	7.								
SQRT	R	6.								
TEMP	R	5. E	9.	10.	11.	33.	35.			
XCEN	R	1.	6.	15.						
XI	R	5. E	15.	16.	17.	18.	23.			
XTOE	R	3. C	8.							
XTOP	R	3. C	9.							
YCEN	R	.	6.	15.						
YI	R	18.	19.	20.	21.	23.				
YTOE	R	3. C	8.							
YTOP	R	3. C	9.							

FUNCTION

FORSTAT Listing of Function HEAD

```

1.      FUNCTION HEAD (XD,YD)
C      -----
C      FUNCTION HEAD
C      -----
C      PURPOSE-
C      TO CALCULATE TOTAL HEAD AT POINT (XD,YD) USING FIFTH ORDER
C      POLYNOMIAL COEFFICIENTS GENERATED BY PROGRAM FLWNEI.
C      -----
C      USAGE-
C      TOTAL HEAD = HEAD(XD,YD)
C      -----
C      WHERE  XD = X-COORD. OF FLOW DOMAIN
C              YD = Y-COORD. OF FLOW DOMAIN
C      -----
C      ALL OTHER VARIABLES ARE SUPPLIED THROUGH BLANK COMMON
C      -----
2.      COMMON A(21)
3.      XD2=XD*XD
4.      XD3=XD2*XD
5.      XD4=XD3*XD
6.      YD2=YD*YD
7.      YD3=YD2*YD
8.      YD4=YD3*YD
9.      PT=A(1)+XD*A(2)+YD*A(3)+XD2*A(4)+XD*YD*A(5)+YD2*A(6)+XD3*A(7)
10.     PT=PT+XD2*YD*A(8)+XD*YD2*A(9)+YD3*A(10)+XD4*A(11)+XD3*YD*A(12)
11.     PT=PT+XD2*YD2*A(13)+XD*YD3*A(14)+YD4*A(15)+XD4*YD*A(16)
12.     PT=PT+XD4*YD*A(17)+XD3*YD2*A(18)+XD2*YD3*A(19)+XD*YD4*A(20)
13.     HEAD=PT+YD*YD4*A(21)
14.     RETURN
15.     END

```

LABEL	TYPE	DEFINITION	REFERENCES							
A	R	2. CD	9.	10.	11.	12.	13.			
HEAD	R	13.								
PT	R	9.	10.	11.	12.	13.				
XD	R	1.	3.	4.	5.	9.	10.	11.	12.	
XD2	R	3.	4.	9.	10.	11.	12.			
XD3	R	4.	5.	9.	10.	12.				
XD4	R	5.	10.	11.	12.					
YD	R	1.	6.	7.	8.	9.	10.	12.	13.	
YD2	R	6.	7.	9.	10.	11.	12.			
YD3	R	7.	8.	10.	11.	12.				
YD4	R	8.	11.	12.	13.					

APPENDIX B
EXAMPLE PROBLEM

APPENDIX B

EXAMPLE PROBLEM

Each main program deck has been provided with test data. The purpose of the test data is twofold: (1) to illustrate several of the available options; (2) to serve as a check for duplicated decks.

Two slope profiles are shown in Figure 14. Slope A is used by examples 1, 2, and 3. In example 1, the Taylor equation (SLOPE1) is used. The soil profile is considered in a dry condition, and a grid search was specified. For each grid center, the factor of safety of all circles generated by the radius increment value is printed in addition to the statement of the minimum. By examining at each center the variation of F as the radius is increased, the designer may conclude whether a "good" value of the radius increment value was chosen. Once the validity of the minimum factors of safety at each center is decided, a contour map of F can be made to determine the "local" minimum factor of safety. In example 1, this minimum factor of safety is at (140,60) and equals 2.169.

Program SLOPE2 was used in the second example. The same grid was analyzed but for the condition of a water table, where the pressure heads are assumed equal to the vertical distance to the water table. However, this analysis was incomplete. Upon examining a contour map of the grid, one can readily see that the contours do

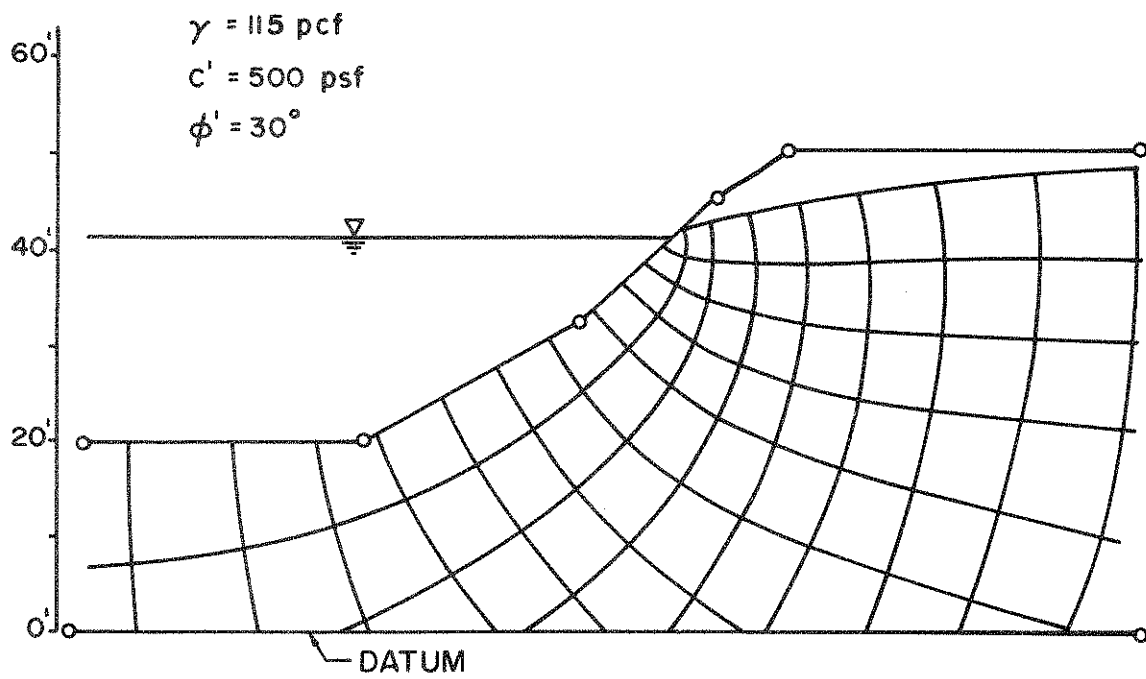


Figure 14a - Example Profile A

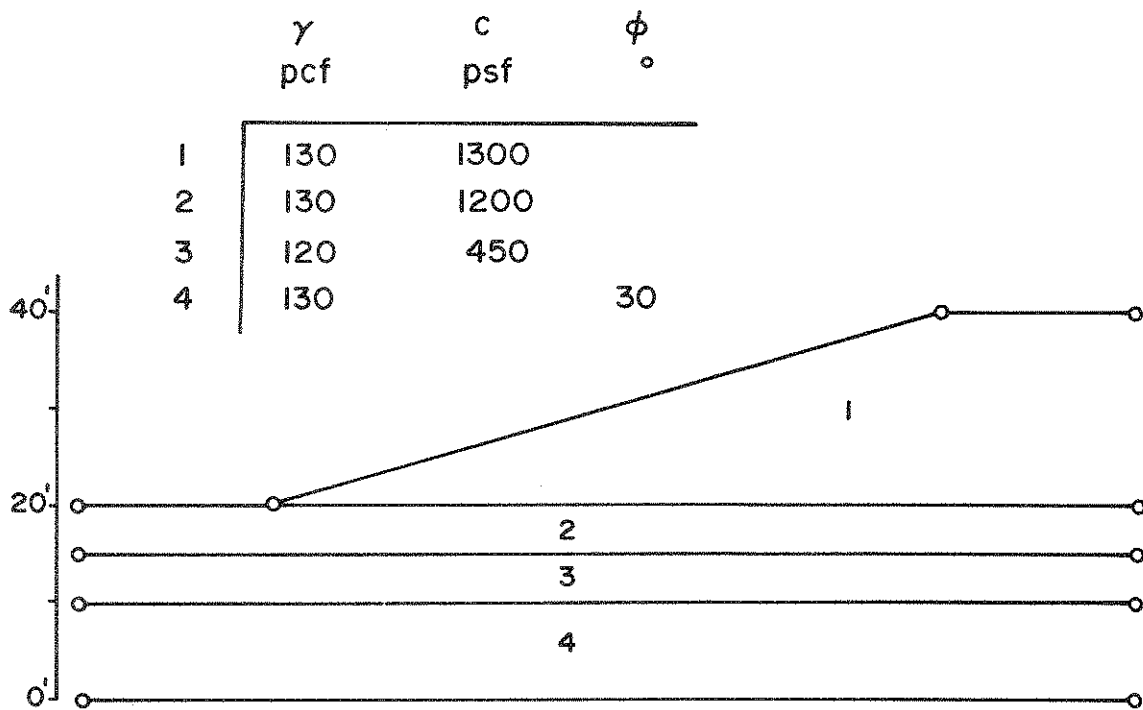


Figure 14b - Example Profile B

not close. Therefore, the magnitude of the minimum is still unknown, and another grid would have to be analyzed.

The third example illustrates an analysis of profile A using the flow net. Program SLOPE3 is used for this example. The fifth order polynomial used to approximate the flow net was first calculated by program FLWNET. Also, in this example, the individual circle option was used.

The fifth example uses program SLOPE4, the irregular search, to analyze slope B. To locate the minimum factor of safety for the irregular search, the following procedure is recommended. For each NLayer and X-EXIT determine the minimum factor of safety. Prepare a contour map of F over the two parameters NLayer and X-EXIT to locate the minimum F of the search. Run two more searches using different values of X-CONTROL to determine the minimum F of the profile.

Example Problem 1 - Input

```

EXAMPLE 1  SLOPE 4--ARY CONDITION
6 5 1 0      129.0      20.0      174.0      50.0
0.0      20.0      129.0      20.0      1
129.0      20.0      151.0      32.0      1
151.0      32.0      167.0      47.0      1
167.0      47.0      174.0      50.0      1
174.0      50.0      300.0      50.0      1
0.0      0.0      300.0      0.0      0
115.0      500.0      30.0
2 1
150.0      130.0      70.0      50.0      10.0      3 3
END

```

Example Problem 1 - Output

---SLOPE STABILITY ANALYSIS---
TAYLOR METHOD OF SLICES

PROBLEM DESCRIPTION EXAMPLE 1 SLOPE 4--ARY CONDITION

PROFILE PARAMETERS---

TOE COORDINATES

XTOE = 129.0
YTOE = 20.0

CREST COORDINATES

XTOP = 174.0
YTOP = 50.0

---BOUNDARY COORDINATES

5 TOP BOUNDARIES

6 TOTAL BOUNDARIES

BND NO.	X-LEFT	Y-LEFT	X-RIGHT	Y-RIGHT	SOIL TYPE BELOW
1	0.0	20.0	129.0	20.0	1
2	129.0	20.0	151.0	32.0	1
3	151.0	32.0	167.0	47.0	1
4	167.0	47.0	174.0	50.0	1
5	174.0	50.0	300.0	50.0	1
6	0.0	0.0	300.0	0.0	0

---SOIL PROPERTIES---

1 TYPES OF SOIL

TYPE NO.	GAMMA	C	PHI
1	115.0	500.0	30.0

---TOP BOUNDARY LOADING---

-0 UNIFORM LOADING
-0 CONCENTRATED LOADING

NO G.W.L. HAS BEEN SPECIFIED

GRID OPTION SPECIFIED
1 GRIDS TO BE ANALYZED

GRID SPECIFICATIONS

XMAX = 150.0 YMAX = 70.0
XMIN = 130.0 YMIN = 50.0
ICOL = 3 ICOW = 3

RADIUS INCREMENT = 10.0

X-CENTER	Y-CENTER	RADIUS	FS	
130.0	70.0	50.01	2.444	
		60.01	2.441	
		70.00	2.940	
		MINIMUM FS FOR THIS CENTER =		2.444
		140.0	70.0	
140.0	70.0	51.20	2.104	
		61.20	2.911	
		70.00	2.977	
		MINIMUM FS FOR THIS CENTER =		2.104
		150.0	70.0	
150.0	70.0	54.23	2.448	
		64.23	2.754	
		70.00	2.941	
		MINIMUM FS FOR THIS CENTER =		2.448
		130.0	60.0	
130.0	60.0	45.12	2.797	
		55.12	2.792	
		60.00	2.958	
		MINIMUM FS FOR THIS CENTER =		2.797
		140.0	60.0	
140.0	60.0	41.48	2.169	
		51.48	2.453	
		60.00	2.907	
		MINIMUM FS FOR THIS CENTER =		2.169
		150.0	60.0	
150.0	60.0	45.18	2.777	
		55.18	2.701	
		60.00	2.897	
		MINIMUM FS FOR THIS CENTER =		2.777
		130.0	50.0	
130.0	50.0	44.00	3.033	
		50.00	3.183	
		MINIMUM FS FOR THIS CENTER =		3.033
		140.0	50.0	
		140.0	50.0	34.00
44.00	2.563			
50.00	2.907			
MINIMUM FS FOR THIS CENTER =				2.356
150.0	50.0			
150.0	50.0	36.62	2.305	
		46.62	2.726	
		50.00	2.869	
		MINIMUM FS FOR THIS CENTER =		2.305

Example Problem 2 - Input

```

EXAMPLE 2  SLOPE A--WATER TABLE
A 5 1 14
0.0 20.0 129.0 20.0 174.0 50.0
129.0 20.0 151.0 32.0 1
151.0 32.0 167.0 47.0 1
167.0 47.0 174.0 50.0 1
174.0 50.0 300.0 50.0 1
0.0 0.0 300.0 0.0 0
115.0 500.0 30.0
0.0 41.0
160.0 41.0
167.0 42.0
165.0 43.0
160.5 44.0
174.0 45.0
180.0 46.0
210.0 40.0
300.0 50.0
2 1
150.0 130.0 70.0 50.0 10.0 3.1
END

```

Example Problem 2 - Output

```

--SLOPE STABILITY ANALYSIS--
MODIFIED BISHOP METHOD OF SLICES
MOMENT CENTER = CIRCLE CENTER

```

PROBLEM DESCRIPTION EXAMPLE 2 SLOPE A--WATER TABLE

PROFILE PARAMETERS

TOE COORDINATES

XTOE = 129.0
YTOE = 20.0

CREST COORDINATES

XTOP = 174.0
YTOP = 50.0

BOUNDARY COORDINATES

5 TOP BOUNDARIES
6 TOTAL BOUNDARIES

BOUND NO.	X-LEFT	Y-LEFT	X-RIGHT	Y-RIGHT	SOIL TYPE	REFLOW
1	0.0	20.0	129.0	20.0	1	
2	129.0	20.0	151.0	32.0	1	
3	151.0	32.0	167.0	47.0	1	
4	167.0	47.0	174.0	50.0	1	
5	174.0	50.0	300.0	50.0	1	
6	0.0	0.0	300.0	0.0	0	

SOIL PROPERTIES

1 TYPES OF SOIL

TYPE NO.	GAMMA	C	PHI
1	115.0	500.0	30.0

TOP BOUNDARY LOADING

=0 UNIFORM LOADING

=0 CONCENTRATED LOADING

G.W.L. SPECIFIED BY 9 COORDINATE POINTS

NO.	X-GWL	Y-GWL
1	0.00	41.00
2	160.00	41.00
3	163.88	42.00
4	165.00	42.00
5	165.50	44.00
6	170.00	45.00
7	180.00	46.00
8	210.00	40.00
9	300.00	50.00

VERTICAL DISTANCE TO G.W.L. SET EQUAL TO PRESSURE

GRID OPTION SPECIFIED
1 GRIDS TO BE ANALYZED

GRID SPECIFICATIONS

XMAX = 150.0 YMAX = 70.0
XMIN = 130.0 YMIN = 50.0
ICOL = 3 IDOW = 3

RADIUS INCREMENT = 10.0

X-CENTER	Y-CENTER	RADIUS	FS
130.0	70.0	50.00	3.278
		60.00	3.222
		70.00	3.477
		MINIMUM FS FOR THIS CENTER = 3.222	
		140.0	70.0
140.0	70.0	50.00	2.498
		60.00	2.854
		70.00	3.212
		MINIMUM FS FOR THIS CENTER = 2.498	
		150.0	70.0
150.0	70.0	50.00	2.567
		60.00	2.912
		70.00	3.178
		MINIMUM FS FOR THIS CENTER = 2.567	
		130.0	60.0
130.0	60.0	40.00	3.024
		50.00	3.560
		60.00	3.663
		MINIMUM FS FOR THIS CENTER = 3.560	
		140.0	60.0
140.0	60.0	40.00	2.654
		50.00	2.923
		60.00	3.267
		MINIMUM FS FOR THIS CENTER = 2.654	
		150.0	60.0
150.0	60.0	40.00	2.999
		50.00	2.977
		60.00	3.100
		MINIMUM FS FOR THIS CENTER = 2.999	
		130.0	50.0
130.0	50.0	40.00	4.306
		50.00	4.137
		MINIMUM FS FOR THIS CENTER = 4.137	
		140.0	50.0
		140.0	50.0
40.00	3.214		
50.00	3.436		
MINIMUM FS FOR THIS CENTER = 3.165			
150.0	50.0		
150.0	50.0	30.00	2.730
		40.00	3.123
		50.00	3.290
		MINIMUM FS FOR THIS CENTER = 2.730	
		130.0	40.0

Example Problem 3 - Input

```

EXAMPLE 3  SLOPE A--FLORNET
5 5 1 20 0.0
0.0 20.0 120.0 20.0 1
120.0 20.0 151.0 32.0 1
151.0 32.0 167.0 47.0 1
167.0 47.0 174.0 50.0 1
174.0 50.0 300.0 50.0 1
115.0 500.0 70.0
8.0 41.0
160.0 41.0
167.0 42.0
165.0 43.0
160.5 44.0
174.0 45.0
180.0 46.0
210.0 49.0
300.0 50.0
-1.435E+02
6.126E+00
7.346E+00
-7.498E-02
-1.254E-01
-2.155E-01
4.542E-04
5.374E-04
5.063E-03
-0.609E-03
-1.167E-04
4.899E-07
-3.604E-05
5.078E-05
-6.651E-07
1.664E-04
-4.786E-09
7.055E-08
-1.273E-07
-4.890E-08
8.549E-09
1 A
130.0 60.0 45.17
140.0 60.0 41.40
150.0 60.0 45.19
130.0 70.0 50.02
140.0 70.0 51.21
150.0 70.0 56.24
END

```

Example Problem 3 - Output

```

--SLOPE STABILITY ANALYSIS--
MODIFIED RISHOP METHOD OF SLICES
MOMENT CENTER = +Y INF

```

PROBLEM DESCRIPTION-- EXAMPLE 3 SLOPE A--FLORNET

PROFILE PARAMETERS

TOE COORDINATES

XTOE = -0.0
YTOE = 0.0

HEEL COORDINATES

XHEEL = -0.0
YHEEL = 0.0

BOUNDARY COORDINATES

% TOP BOUNDARIES
% TOTAL BOUNDARIES

AND NO	X-LEFT	Y-LEFT	X-RIGHT	Y-RIGHT	KATI	TYPE	REFLOW
1	0.0	20.0	120.0	20.0	1		
2	120.0	20.0	151.0	32.0	1		
3	151.0	32.0	167.0	47.0	1		
4	167.0	47.0	174.0	50.0	1		
5	174.0	50.0	300.0	50.0	1		

SOIL PROPERTIES

1 TYPES OF SOIL

TYPE NO.	GAMMA	C	PHI
1	115.0	500.0	30.0

TOP BOUNDARY LOADING

-0 UNIFORM LOADING

-0 CONCENTRATED LOADING

G.W.L. SPECIFIED BY 9 COORDINATE POINTS

NO.	X-GWL	Y-GWL
1	0.00	41.00
2	160.00	41.00
3	163.00	42.00
4	165.00	43.00
5	164.50	44.00
6	174.00	45.00
7	180.00	44.00
8	210.00	40.00
9	300.00	50.00

FIFTH ORDER POLYNOMIAL APPROXIMATES FLOW NET

I	A(I)
1	-1.635E+02
2	6.194E+00
3	7.346E+00
4	-7.298E+02
5	-1.254E+01
6	-2.155E+01
7	4.542E+04
8	5.374E+04
9	5.063E+03
10	-2.200E+03
11	-1.367E+06
12	4.899E+07
13	-3.604E+05
14	5.078E+05
15	-6.651E+07
16	1.645E+09
17	-4.786E+09
18	7.955E+08
19	-1.273E+07
20	-4.840E+08
21	4.549E+08

INDIVIDUAL CIRCLE OPTION SPECIFIED
6 CIRCLES TO BE ANALYZED

X-CENTER	Y-CENTER	RADIUS	FS
130.0	60.0	45.13	3.209
140.0	60.0	41.69	2.282
150.0	60.0	45.19	2.197
130.0	70.0	50.02	2.889
140.0	70.0	51.21	2.198
150.0	70.0	54.24	2.230

Example Problem 4 - Input

```

EXAMPLE 4  SLOPE R--IRREGULAR SEARCH
A 3 4      200.0    10.0    270.0    30.0
0.0        10.0    200.0    10.0
200.0      10.0    270.0    30.0
270.0      30.0    1000.0    30.0
200.0      10.0    1000.0    10.0
0.0        5.0     1000.0    5.0
0.0        0.0     1000.0    0.0
130.0      1000.0    0.0
130.0      1200.0    0.0
120.0      450.0    0.0
130.0      0.0     30.0
2 1
30.0      0.0     300.0    200.0    210.0    A 7 3
END

```

Example Problem 4 - Output

--SLOPE STABILITY ANALYSIS--
 MODIFIED BISHOP METHOD OF SLICES
 MOMENT CENTER = 4Y INF

PROBLEM DESCRIPTION EXAMPLE 4 SLOPE R--IRREGULAR SEARCH

PROFILE PARAMETERS

TOE COORDINATES

XTOE = 200.0
 YTOE = 10.0

CREST COORDINATES

XTOP = 270.0
 YTOP = 30.0

BOUNDARY COORDINATES

3 TOP BOUNDARIES
 6 TOTAL BOUNDARIES

AND NO.	X=LEFT	Y=LEFT	X=RIGHT	Y=RIGHT	SOIL TYPE BELOW
1	0.0	10.0	200.0	10.0	2
2	200.0	10.0	270.0	30.0	1
3	270.0	30.0	1000.0	30.0	1
4	200.0	10.0	1000.0	10.0	2
5	0.0	5.0	1000.0	5.0	3
6	0.0	0.0	1000.0	0.0	4

SOIL PROPERTIES

4 TYPES OF SOIL

TYPE NO.	GAMMA	C	PHI
1	100.0	1000.0	0.0
2	130.0	1200.0	0.0
3	120.0	450.0	0.0
4	130.0	0.0	30.6

TOP BOUNDARY LOADING

=0 UNIFORM LOADING

=0 CONCENTRATED LOADING

NO G.W.L. HAS BEEN SPECIFIED

SEARCH IRREGULAR SURFACE OPTION SPECIFIED
1 SEARCHES TO BE ANALYZED

SEARCH SPECIFICATIONS

XMIN = 280.0 YMIN = 0.0
NSUR = 3
XMAX = 320.0 YMAX = 30.0
X-CONTROL = 210.0
NMIN = 6
NMAX = 7

NI LAYER = 6

A-EXIT	R	FS	(X(1),Y(1))...							
120.00	30	2.857	192.68	10.00	210.00	0.00	226.41	1.02		
			250.45	4.02	275.96	8.79	285.90	15.00		
			310.41	22.24	320.00	30.00				
120.00	45	2.751	200.00	10.00	210.00	0.00	226.41	1.02		
			250.45	4.02	275.96	8.79	285.90	15.00		
			310.41	22.24	320.00	30.00				
120.00	60	2.924	203.63	11.04	210.00	0.00	226.41	1.02		
			250.45	4.02	275.96	8.79	285.90	15.00		
			310.41	22.24	320.00	30.00				
100.00	30	2.603	192.68	10.00	210.00	0.00	223.42	1.02		
			243.10	4.02	263.97	8.79	280.28	15.00		
			292.16	22.24	300.00	30.00				
100.00	45	2.590	200.00	10.00	210.00	0.00	223.42	1.02		
			243.10	4.02	263.97	8.79	280.28	15.00		
			292.16	22.24	300.00	30.00				
100.00	60	2.770	203.63	11.04	210.00	0.00	223.42	1.02		
			243.10	4.02	263.97	8.79	280.28	15.00		
			292.16	22.24	300.00	30.00				
280.00	30	2.651	192.68	10.00	210.00	0.00	220.44	1.02		
			235.74	4.02	251.97	8.79	264.66	15.00		
			273.90	22.24	280.00	30.00				
280.00	45	2.638	200.00	10.00	210.00	0.00	220.44	1.02		
			235.74	4.02	251.97	8.79	264.66	15.00		
			273.90	22.24	280.00	30.00				
280.00	60	2.846	203.63	11.04	210.00	0.00	220.44	1.02		
			235.74	4.02	251.97	8.79	264.66	15.00		
			273.90	22.24	280.00	30.00				

NI LAYER = 7

A-EXIT	R	FS	(X(1),Y(1))...							
120.00	30	2.686	192.68	10.00	210.00	0.00	224.99	.75		
			247.10	2.97	270.84	6.55	289.77	11.30		
			303.94	16.98	313.66	23.32	320.00	30.00		
120.00	45	2.676	200.00	10.00	210.00	0.00	224.99	.75		
			247.10	2.97	270.84	6.55	289.77	11.30		
			303.94	16.98	313.66	23.32	320.00	30.00		
120.00	60	2.843	203.63	11.04	210.00	0.00	224.99	.75		
			247.10	2.97	270.84	6.55	289.77	11.30		
			303.94	16.98	313.66	23.32	320.00	30.00		
100.00	30	2.535	192.68	10.00	210.00	0.00	222.26	.75		
			240.35	2.97	259.78	6.55	275.27	11.30		
			286.86	16.98	294.82	23.32	300.00	30.00		
100.00	45	2.522	200.00	10.00	210.00	0.00	222.26	.75		
			240.35	2.97	259.78	6.55	275.27	11.30		
			286.86	16.98	294.82	23.32	300.00	30.00		
100.00	60	2.694	203.63	11.04	210.00	0.00	222.26	.75		
			240.35	2.97	259.78	6.55	275.27	11.30		
			286.86	16.98	294.82	23.32	300.00	30.00		
280.00	30	2.574	192.68	10.00	210.00	0.00	219.54	.75		
			233.61	2.97	248.72	6.55	260.77	11.30		
			269.78	16.98	275.97	23.32	280.00	30.00		
280.00	45	2.559	200.00	10.00	210.00	0.00	219.54	.75		
			233.61	2.97	248.72	6.55	260.77	11.30		
			269.78	16.98	275.97	23.32	280.00	30.00		
280.00	60	2.755	203.63	11.04	210.00	0.00	219.54	.75		
			233.61	2.97	248.72	6.55	260.77	11.30		
			269.78	16.98	275.97	23.32	280.00	30.00		

Example Output of FLWNET

FIFTH ORDER POLYNOMIAL APPROXIMATION FOR FLOWNET--

THE EQUATION HAS THE FOLLOWING FORM

$$\begin{aligned} \text{EST. H} = & A1 + A2(X) + A3(Y) + A4(X**2) + A5(X)(Y) + A6(Y**2) + \\ & A7(X**3) + A8(X**2)(Y) + A9(X)(Y**2) + A10(Y**3) + \\ & A11(X**4) + A12(X**3)(Y) + A13(X**2)(Y**2) + \\ & A14(X)(Y**3) + A15(Y**4) + A16(X**5) + A17(X**4)(Y) + \\ & A18(X**3)(Y**2) + A19(X**2)(Y**3) + A20(X)(Y**4) + A21(Y**5) \end{aligned}$$

I	A1
1	-1.635E+02
2	6.196E+00
3	7.346E+00
4	-7.498E-02
5	-1.254E-01
6	-2.155E-01
7	4.542E-04
8	5.374E-04
9	5.063E-03
10	-4.609E-03
11	-3.367E-06
12	4.899E-07
13	-3.604E-05
14	5.078E-05
15	-6.651E-07
16	1.645E-09
17	-4.786E-09
18	7.955E-08
19	-1.273E-07
20	-4.880E-08
21	8.549E-08

ORIGINAL AND COMPUTED VALUES

PT.NO.	X	Y	H	EST. H	RESIDUAL
1	100.000	20.000	41.000	40.968	-.032
2	104.000	20.000	41.000	41.029	.029
3	115.000	20.000	41.000	41.029	.029
4	124.000	20.000	41.000	41.063	.063
5	130.000	20.500	41.000	41.092	.092
6	137.000	24.000	41.000	40.772	-.228
7	142.500	27.500	41.000	40.565	-.435
8	148.000	30.500	41.000	40.703	-.297
9	152.500	33.500	41.000	40.914	-.086
10	155.000	37.000	41.000	40.822	-.178
11	157.500	39.000	41.000	41.112	.112
12	160.000	41.000	41.000	41.512	.512
13	105.000	7.000	42.000	41.908	-.092
14	116.000	9.000	42.000	42.124	.124
15	125.500	11.000	42.000	42.074	.074
16	133.500	14.000	42.000	41.984	-.016
17	141.000	17.500	42.000	41.943	-.057
18	146.500	21.000	42.000	41.981	-.019
19	152.000	25.000	42.000	42.087	.087
20	157.000	29.000	42.000	42.301	.301
21	159.500	33.000	42.000	42.278	.278
22	161.500	36.500	42.000	42.293	.293
23	162.000	39.000	42.000	42.177	.177
24	163.000	42.000	42.000	42.211	.211
25	129.000	1.000	43.000	42.997	-.003
26	137.500	6.000	43.000	42.836	-.164
27	145.000	10.000	43.000	42.884	-.116
28	151.000	15.000	43.000	42.912	-.088
29	156.000	20.000	43.000	42.999	-.001
30	161.000	25.000	43.000	43.216	.216
31	163.000	30.000	43.000	43.119	.119
32	164.500	35.000	43.000	42.993	-.007
33	165.000	38.500	43.000	42.862	-.138
34	165.000	43.000	43.000	42.682	-.318
35	144.000	0.000	44.000	44.054	.054

36	150.000	3.500	44.000	44.030	.030
37	156.500	9.000	44.000	43.940	-.060
38	162.000	15.000	44.000	44.034	.034
39	168.000	22.000	44.000	44.070	.070
40	168.000	27.500	44.000	44.031	.031
41	168.500	44.000	44.000	43.540	-.460
42	169.500	33.000	44.000	43.975	-.025
43	170.000	38.500	44.000	43.856	-.144
44	163.000	3.500	45.000	45.071	.071
45	168.000	12.000	45.000	44.946	-.054
46	171.500	19.500	45.000	44.931	-.069
47	173.000	25.500	45.000	44.847	-.153
48	174.500	32.000	45.000	44.813	-.187
49	175.000	38.000	45.000	44.763	-.237
50	174.000	45.000	45.000	44.798	-.202
51	170.000	0.000	46.000	45.893	-.107
52	175.500	9.000	46.000	46.019	.019
53	179.000	17.000	46.000	46.030	.030
54	180.000	46.000	46.000	45.994	-.006
55	181.000	24.000	46.000	46.017	.017
56	181.500	31.000	46.000	45.888	-.112
57	181.500	38.500	46.000	45.816	-.184
58	183.000	6.000	47.000	46.990	-.010
59	186.000	14.500	47.000	46.996	-.004
60	187.000	23.000	47.000	46.833	-.167
61	188.000	47.000	47.000	47.223	.223
62	189.000	31.000	47.000	46.922	-.078
63	189.000	39.000	47.000	46.883	-.117
64	192.000	3.000	48.000	47.957	-.043
65	195.000	13.000	48.000	48.017	.017
66	197.000	22.000	48.000	47.995	-.005
67	197.500	48.000	48.000	48.177	.177
68	198.500	30.500	48.000	48.066	.066
69	199.000	39.000	48.000	48.058	.058
70	202.000	0.000	49.000	48.982	-.018
71	205.000	10.000	49.000	48.974	-.026
72	207.500	21.000	49.000	48.864	-.136
73	209.000	30.000	49.000	49.033	.033
74	209.000	39.000	49.000	49.004	.004
75	210.000	49.000	49.000	48.807	-.193

STATISTICAL VALUES

PERCENT SS	=	45.722857
R-SQUARED	=	.867227
R	=	.931250

APPENDIX C
LIST OF SYMBOLS

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LIST OF SYMBOLS

a	Point of application of N' measured from left side of slice
\bar{a}	Equals $(\bar{y} - h)$
b	Point of application of E measured from base of slice
$c'_a(c_a)$	Effective (total) stress Mohr-Coulomb strength intercept
$C'_a(C_a)$	Effective (total) force when the unit value is $c'_a(c_a)$
$E'(E)$	Effective (total normal force on side of slice
F	Factor of safety (strength reduction factor)
F_T	Factor of Safety in the Taylor Method of Slices
F_{MB}	Factor of Safety in the Modified Bishop Method of Slices
h	Average height of slice
i	Subscript denoting a particular slice
\bar{k}	Equals $(1 - \frac{h}{\bar{y}})$
$N'(N)$	Effective (total) normal force on base of slice
R	Radius of assumed failure surface; Resultant force on slice side
S_a	Available shear force on base of slice
S_r	Required (for equilibrium) shear force on base of slice
T_k	Terms in Fibonacci sequence
t	Width of slice
U_α	Water force on base of slice
U_β	Water force on top of slice

U	Water force on interslice side
$W'(W)$	Submerged (total) weight of slice
W_w	Equivalent water weight of slice
X	Shear force on side of slice
\bar{x}	Distance in the x-direction from the center of the slice base to a moment center
\bar{y}	Distance in the y-direction from the center of the slice base to a moment center
α	Angle of inclination of base of slice
β	Angle of inclination of top of slice
γ	Total unit weight
$\phi'(\phi)$	Effective (total) stress Mohr-Coulomb strength angle
θ	Central angle of circular failure surface
$\tau_r(\tau_a)$	Shear stress required (available)
$\sigma'(\sigma)$	Effective (total) normal stress

